

## Electrostatics in Media:

$$\nabla \cdot \mathbf{E} = \rho$$

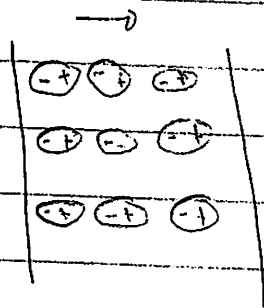
$$\nabla \times \mathbf{B} = \frac{\mathbf{j}}{c} + \frac{1}{c} \partial_t \mathbf{E} \quad \partial_t \rho + \nabla \cdot \mathbf{j} = 0$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{1}{c} \partial_t \mathbf{B}$$

Need to specify the currents in the medium in order to solve. Symmetry is key

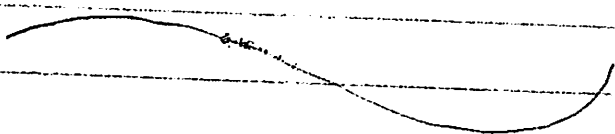
## Basic Picture of Insulating Material



Electric field polarizes the insulating material

Key points:

- ① The wavelength of the external field is vastly longer than the microscopic scales



$$\lambda_{\text{light}} \sim 500 \text{ nm}$$

Where as size of atom  $a_0 \sim \frac{1 \text{ \AA}}{2}$

$$\frac{\lambda_{\text{light}}}{a_0} \sim 10^4$$

(2) Fields are often weak compared to micro-fields

$$E_{\text{ext}} \sim \frac{1 \text{ kV}}{\text{cm}} \sim 10^5 \frac{\text{V}}{\text{m}} \quad (\text{Largest man-made field})$$

$$E_{\text{atom}} \sim \frac{13.6 \text{ eV}}{a_0} \sim 13 \times 10^{10} \frac{\text{V}}{\text{m}}$$

Now we will need these points and symmetry

## Rotations:

$$x \rightarrow \underbrace{x^i}_{\text{rotated coords}} = R^i_j \underbrace{x^j}_{\text{rotation matrix}}$$

$$\begin{pmatrix} x^1 \\ x^2 \\ x^3 \end{pmatrix} = (R) \begin{pmatrix} x^1 \\ x^2 \\ x^3 \end{pmatrix}$$

- Repeated indices sum  $a_i b^i = a_1 b^1 + a_2 b^2 + a_3 b^3$
- Think of upper indices (covariant indices) as row indices, lower indices (contravariant indices) as column indices. (But  $x^i$  is a column vector,  $x_i$  is a row vector)

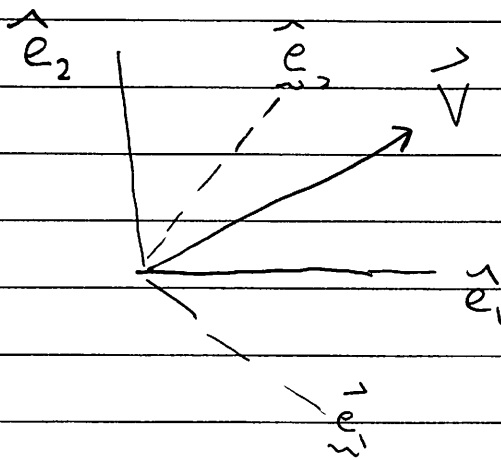
## Scalars

$$S \rightarrow \underbrace{S} = S \quad (\text{invariant under rotations})$$

$$Q \rightarrow \underbrace{Q} = Q \quad \text{charge}$$

$$m \rightarrow \underbrace{m} = m \quad \text{mass}$$

## Vectors



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Take passive point of view

$$\vec{V} \rightarrow \vec{V} = \vec{V}$$

Vectors are physical objects unchanged by coordinate rotations

$$\vec{V} = v^i \vec{e}_i = \tilde{v}^i \tilde{e}_i$$

But the components and the basis vectors are changed by rotations (see figure on previous page)

$$\tilde{v}^i = R^i_j v^j$$

$$\tilde{e}_j = \vec{e}_i (R^{-1})^i_j$$

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i.e

$$(\hat{e}_{\tilde{1}} \hat{e}_{\tilde{2}} \hat{e}_{\tilde{3}}) = (\hat{e}_1 \hat{e}_2 \hat{e}_3) (R^{-1})$$

Now

$$\begin{aligned} \vec{V} &= (\hat{e}_{\tilde{1}} \hat{e}_{\tilde{2}} \hat{e}_{\tilde{3}}) \begin{pmatrix} v_{\tilde{1}} \\ v_{\tilde{2}} \\ v_{\tilde{3}} \end{pmatrix} = (e_1 e_2 e_3) \overbrace{(R^{-1})(R)}^{\mathbb{1}} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \\ &= (e_1 e_2 e_3) \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \vec{V} \end{aligned}$$

For Rotation group  $R^{-1} = R^T$  so:

$$(e_{\tilde{1}} e_{\tilde{2}} e_{\tilde{3}}) = (e_1 e_2 e_3) (R^T)$$

Take  
Transpose

$$\begin{pmatrix} e_{\tilde{1}} \\ e_{\tilde{2}} \\ e_{\tilde{3}} \end{pmatrix} = (R) \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix}$$

This is the same transformation rule as for upstairs indices (covariant components). Thus for rotations there is no difference between up and down indices (covariant and contravariant indices).

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### Scalar Product:

$$S = \vec{a} \cdot \vec{b} = a_i b^i$$

Takes two vectors  
and gives a scalar.

i.e.

$$S \rightarrow \underbrace{S} = \underbrace{\vec{a}} \cdot \underbrace{\vec{b}} = \vec{a} \cdot \vec{b} = S$$

Ex:

$$\nabla \cdot \vec{E} = \frac{\partial}{\partial x^i} E^i$$

$$\vec{\nabla} = \hat{e}^i \frac{\partial}{\partial x^i}$$

$$= \partial_i E^i \quad (\partial_i \equiv \frac{\partial}{\partial x^i})$$

### Vector Product:

Takes two vectors and  
gives another vector

$$(\vec{a} \times \vec{b})^i = \epsilon^{ijk} a_j b_k$$

$$\text{Ex } (\nabla \times \vec{F})^i = \epsilon^{ijk} \frac{\partial}{\partial x^j} F_k$$

$$\text{where } \frac{\partial}{\partial x^j} = \partial_j$$

## Tensors

$$\underline{\underline{T}} = T^{ij} \vec{e}_i \vec{e}_j$$

They are invariant under rotations but the components change as:

$$\underline{\underline{T}}^{ij} = R^i_{i'} R^j_{j'} T^{i'j'}$$

## Parity

$$t \rightarrow \underset{\sim}{t} = t \quad (\text{P-even})$$

$$x \rightarrow \underset{\sim}{x} = -x \quad (\text{P-odd})$$

$$\vec{p} \rightarrow \underset{\sim}{\vec{p}} = -\vec{p} \quad (\text{P-odd})$$

Prf:

$$\underset{\sim}{\vec{p}} = m \frac{d\underset{\sim}{x}}{dt} = -m \frac{dx}{dt} = -p$$

$$F \rightarrow -\vec{F} \quad (\text{P-odd})$$

$$\vec{L} \rightarrow \underset{\sim}{\vec{L}} = \vec{L} \quad (\text{P-even} \equiv \text{pseudo vector})$$

(Use  $L = \vec{r} \times \vec{p}$ )

$$j \rightarrow \underset{\sim}{j} = -j \quad (\text{P-odd})$$

$$E \rightarrow -\vec{E} \quad (\text{P-odd})$$

$$B \rightarrow B \quad (\text{P-even} \equiv \text{pseudo vector})$$

Use  $F_E = q E$  and  $F_B = q \vec{v} \times \vec{B}$

↑ odd    ↑ even    ↑ odd                    ↑ odd    ↑ even    ↑ odd    ↑ even



## Time Reversal

$$t \rightarrow \underline{t} = -t \quad (\text{T-odd})$$

$$x \rightarrow \underline{x} = x \quad (\text{T-even})$$

$$\underline{\vec{p}} \rightarrow \underline{p} = -p \quad (\text{T-odd})$$

P.r.f:

$$\underline{p} = m \frac{d\underline{x}}{dt} = -m \frac{dx}{dt} = -p$$

$$F \rightarrow \underline{F} = F \quad (\text{T-even})$$

(Use  $\underline{F} = dp/dt$ )

$$E \rightarrow \underline{E} = E \quad (\text{T-even})$$

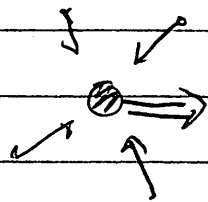
(Use  $F = qE$ )

$$\underline{B} \rightarrow \underline{B} = -B \quad (\text{T-odd})$$

(Use  $F = q \vec{v} \times \vec{B}$ )

↑ even      ↑ odd      ↖ odd

# Dissipation



Put a heavy particle interacting with light particles in a computer simulation

$$m \frac{d^2 x}{dt^2} = \sum F_i$$

$$F_i = \frac{q_i q_j}{4\pi |\vec{r} - r_j|^2}$$

The heavy particle experiences an effective force

$$M \frac{d^2 x}{dt^2} = F_D$$

$$F_D = -\gamma v$$

Now imagine running all particles in reverse.  $t \rightarrow \underline{t} = -t$ . The equations of motion are the same, and the heavy particle would still slow down. The effective force

$$\underline{F}_D = -\underline{\gamma} \underline{v}$$

even under time reversal

time reversal

odd under  $t$ -reverse

odd under  $t$ -reverse

$$\underline{\gamma} = -\gamma$$

Summary

$$\eta \rightarrow \eta = -\eta \quad \text{under time reversal}$$

Dissipative coefficients are T-odd

## Fourier Transforms:

$$\phi(t, \vec{r}) = \int \frac{d\omega}{2\pi} \int \frac{d^3k}{(2\pi)^3} e^{-i\omega t + i\vec{k} \cdot \vec{r}} \phi(\omega, \vec{k}) \equiv (\phi(\omega, \vec{k}))_{FT}$$

$$\phi(\omega, \vec{k}) = \int dt d^3\vec{r} e^{i\omega t - i\vec{k} \cdot \vec{r}} \phi(t, \vec{r}) \equiv (\phi(t, \vec{r}))_{FT}$$

slow & long wavelength means  $k, \omega$  small

$$\phi(t, \vec{r}) \longleftrightarrow \phi(\omega, \vec{k})$$

$$\partial_t \phi(t, \vec{r}) \longleftrightarrow -i\omega \phi(\omega, \vec{k}) = (\partial_t \phi)_{FT}$$

Prf

$$\partial_i \phi(t, \vec{r}) \longleftrightarrow i k_i \phi(\omega, \vec{k})$$

$$\partial_t \phi(t, \vec{r}) = \int \frac{d\omega}{2\pi} \int \frac{d^3k}{(2\pi)^3} \partial_t (e^{-i\omega t + i\vec{k} \cdot \vec{r}}) \phi(\omega, \vec{k})$$

$$= \int \frac{d\omega}{2\pi} \int \frac{d^3k}{(2\pi)^3} e^{-i\omega t + i\vec{k} \cdot \vec{r}} -i\omega \phi(\omega, \vec{k})$$

Thus:

$$\vec{\nabla} \cdot \vec{E} = \rho(\vec{x})$$

$$(\vec{\nabla} \cdot \vec{E})_{FT} = (\rho(\vec{x}))_{FT}$$

$$(\partial_i E^i)_{FT} = (\rho(\vec{x}))_{FT}$$

$$i k_i E^i(\omega, \vec{k}) = \rho(\omega, \vec{k})$$