### Problem 1. Units

- (a) Show that electric field and magnetic field have units  $\sqrt{(\text{force})/\text{area}}$  or  $\sqrt{\text{energy}/\text{volume}}$ .
- (b) A rule of thumb that you may need in the lab is that coaxial cable has a capcitance of 12 pF/foot. That is why cable length must be kept to a minimum in high speed electronics.

The order of magnitude of this result is set by  $\epsilon_o = 8.85 \,\mathrm{pF/m}$ . In the Heavyside-Lorentz system capacitance is still  $Q_{HL} = C_{HL}V_{HL}$ . Show that  $C_{HL}$  has units of meters, and that

$$C_{MKS} = 8.85 \, pF\left(\frac{C_{HL}}{\text{meters}}\right) \tag{1}$$

(c) The "impedance of the vacuum" is  $Z_o = \sqrt{\mu_o/\epsilon_o} = 376$  Ohms. This is why high frequency antennas will typically have a "radiation resistance" of this order of magnitude. As this problem will discuss, the unit of resistance is s/m for the Heavyside Lorentz system, and "the impedance of the vacuum" is 1/c

In Heavyside-Lorentz units Ohm's law still reads,  $\mathbf{j}_{HL} = \sigma_{HL} \mathbf{E}_{HL}$ , where  $\sigma_{HL}$  is the conductivity, and  $\mathbf{j}$  is the current per area. Show that the conductivity in Heavyside-Lorentz has units  $[\sigma_{HL}] = 1$ /seconds and that  $\sigma_{MKS} = \sigma_{HL}\epsilon_o$ . Then show that a wire of length L and radius  $R_o$  has resistance

$$R_{MKS} = 376 \text{ Ohms } (R_{HL}c) \tag{2}$$

$$=376 \text{ Ohms}\left(\frac{Lc}{\pi R_o^2 \sigma_{HL}}\right) \tag{3}$$

What is  $\sigma_{HL}$  for copper?

### Problem 2. Vector Identities

(a) Use the epsilon tensor to prove the analog of "b(ac)-(ab)c" rule for curls

$$\nabla \times (\nabla \times \boldsymbol{V}) = \nabla (\nabla \cdot \boldsymbol{V}) - \nabla^2 \boldsymbol{V}$$
(4)

Use this result, together with the Maxwell equations in the absence of charges and currents, to establish that E and B obey the wave equation

$$\frac{1}{c^2}\partial_t^2 \boldsymbol{B} - \nabla^2 \boldsymbol{B} = 0 \tag{5}$$

$$\frac{1}{c^2}\partial_t^2 \boldsymbol{E} - \nabla^2 \boldsymbol{E} = 0 \tag{6}$$

(b) When differentiating 1/r we write

$$\frac{1}{r} = \frac{1}{\sqrt{x^i x_i}} \tag{7}$$

with  $\boldsymbol{x} = x^i \boldsymbol{e}_i$ , and use results like

$$\partial_i x^j = \delta^j_i \qquad \partial_i x^i = \delta^i_i = d = 3 \tag{8}$$

where d = 3 is the number of spatial dimensions. (It is usually helps to write this as d rather than 3 to get the algebra right). In this way, one finds that field due to a electric charge (monopole) is the familiar  $\hat{r}/r^2$ 

*j*-th component of 
$$-\nabla(1/r) = \left(-\nabla\frac{1}{r}\right)_j = -\partial_j \frac{1}{\sqrt{x^i x_i}} = \frac{\frac{1}{2}(x^i \delta_{ji} + x_i \delta_j^i)}{\sqrt[3]{x^k x_k}} = \frac{x_j}{r^3} = \frac{(\hat{\boldsymbol{r}})_j}{r^2}$$
(9)

where  $\hat{\boldsymbol{r}} \equiv \boldsymbol{n} = \boldsymbol{x}/r$ .

Using tensor notation (i.e. indexed notation) show that

$$\nabla \times \frac{\hat{\boldsymbol{r}}}{r^2} = 0 \tag{10}$$

(c) Using the tensor notation (*i.e.* indexed notation) show that for constant vector  $\boldsymbol{p}$  (and away from  $\boldsymbol{r} = 0$ ) that

$$-\nabla\left(\frac{\boldsymbol{p}\cdot\boldsymbol{n}}{4\pi r^2}\right) = \frac{3(\boldsymbol{n}\cdot\boldsymbol{p})\boldsymbol{n}-\boldsymbol{p}}{4\pi r^3}$$
(11)

**Remark:**  $\phi_{\text{dip}} = \mathbf{p} \cdot \mathbf{n}/(4\pi r^2)$  is the electrostatic potential due to an electric dipole  $\mathbf{p}$ , and Eq. (11) records the corresponding electric field. Notice the  $1/r^3$  as opposed to  $1/r^2$  for the monopole, and, taking  $\mathbf{p}$  along the z-axis, notice how the electric field points at  $\theta = 0$  (or  $\mathbf{n} = \hat{\mathbf{z}}$ ) and  $\theta = \pi/2$  (or  $\mathbf{n} = \hat{\mathbf{x}}$ ). How could you derive this using the identities on the front cover of Jackson?

# Problem 3. Easy important application of Helmholtz theorems

(a) Using the source free Maxwell equations (*i.e.* those without  $\rho$  and **j**) and the Helmholtz theorems, explain why **E** and **B** can be written in terms of a scalar field  $\Phi$  (the scalar potential) and a vector field **A** (the vector potential)

$$\boldsymbol{B} = \nabla \times \boldsymbol{A} \tag{12}$$

$$\boldsymbol{E} = -\frac{1}{c}\partial_t \boldsymbol{A} - \nabla\Phi \tag{13}$$

Thus two of the four Maxwell equations are trivially solved by introducing  $\Phi$  and A.

(b) Show that  $\boldsymbol{A}$  and  $\boldsymbol{\Phi}$  are not unique, *i.e.* 

$$A_i = (A_{\text{old}})_i + \partial_i \Lambda(t, \boldsymbol{x}) \tag{14}$$

$$\Phi = (\Phi_{\text{old}}) - \frac{1}{c}\partial_t \Lambda(t, \boldsymbol{x})$$
(15)

gives the same  $\boldsymbol{E}$  and  $\boldsymbol{B}$  fields. Here  $\Lambda(t, \boldsymbol{x})$  is any function. This change of fields is known as a gauge transformation of the gauge fields  $(\Phi, \boldsymbol{A})$ .

#### Problem 4. Tensor decomposition

(a) Consider a tensor  $T^{ij}$ , and define the symmetric and anti-symmetric components

$$T_S^{ij} = \frac{1}{2} \left( T^{ij} + T^{ji} \right) \tag{16}$$

$$T_A^{ij} = \frac{1}{2} \left( T^{ij} - T^{ji} \right)$$
 (17)

so that  $T^{ij} = T_S^{ij} + T_A^{ij}$ . Show that the symmetric and anti-symmetric components don't mix under rotation

$$\underline{T_S}^{ij} = R^i_{\ \ell} R^j_{\ m} T^{\ell m}_S \tag{18}$$

$$\underline{T_A}^{ij} = R^i_{\ \ell} R^j_{\ m} T^{\ell m}_A \tag{19}$$

This means that I don't need to know  $T_A$  if I want to find  $\underline{T_S}$  in a rotated coordinate system.

**Remarks:** We say that the general rank two tensor is reducable to  $T^{ij} = T_S^{ij} + T_A^{ij}$  into two tensors that dont mix under rotation

(b) You should recognize that an antisymmetric tensor is isomorphic to a vector

$$V_i \equiv \frac{1}{2} \epsilon_{ijk} T_A^{jk} \tag{20}$$

Explain qualitatively the identity  $\epsilon^{ijk}\epsilon_{\ell mk} = \delta^i_{\ell}\delta^j_m - \delta^j_{\ell}\delta^i_m$  using  $\epsilon^{ij3}\epsilon_{\ell m3}$  as an example, and use this to show

$$T_A^{ij} = \epsilon^{ijk} V_k \tag{21}$$

**Remark:** In matrix form this reads

$$T_{A} = \begin{pmatrix} 0 & V_{z} & -V_{y} \\ -V_{z} & 0 & V_{x} \\ V_{y} & -V_{x} & 0 \end{pmatrix}$$
(22)

(c) Using the Einstein summation convention, show that the trace of a symmetric tensor is rotationally invariant

$$\underline{T}^i_i \equiv T^i_i \tag{23}$$

and that

$$\mathring{T}_{S}^{ij} \equiv T^{ij} - \frac{1}{3}\delta^{ij}T^{\ell}_{\ \ell} \tag{24}$$

is traceless.

**Remark:** A symmetric tensor is therefore reducable to a symmetric traceless tensor and a scalar times  $\delta^{ij}$ .

$$T_S^{ij} = \mathring{T}_S^{ij} + \frac{1}{3}\delta^{ij}T_\ell^\ell \qquad \text{where} \qquad \mathring{T}_S^{ij} \equiv T_S^{ij} - \frac{1}{3}T_\ell^\ell\delta^{ij} \tag{25}$$

I don't need to know  $T_{\ell}^{\ell}$  in order to compute  $\underline{\mathring{T}_{S}^{ij}} = R_{\ell}^{i} R_{m}^{j} \mathring{T}_{S}^{\ell m}$ 

**Remarks:** The results of this problem show that a general second rank tensor is decomposable into irreducable components

$$T^{ij} = \mathring{T}^{ij}_S + \epsilon^{ijk} V_k + \frac{1}{3} T^\ell_\ell \delta^{ij}$$
<sup>(26)</sup>

$$= \frac{1}{2} \left( T^{ij} + T^{ji} - \frac{2}{3} T^{\ell}_{\ell} \delta^{ij} \right) + \frac{1}{2} \epsilon^{ijk} \epsilon_{k\ell m} T^{\ell m} + \frac{1}{3} T^{\ell}_{\ell} \delta^{ij}$$
(27)

No further reduction is possible. A general result is that a fully symmetric traceless tensor is irreducable.

When this result is applied to the product of two vectors it says

$$E^{i}B^{j} = \frac{1}{2} \left( E^{i}B^{j} + B^{i}E^{j} - \frac{2}{3}\boldsymbol{E} \cdot \boldsymbol{B}\delta^{ij} \right) + \frac{1}{2}\epsilon^{ijk}(\boldsymbol{E} \times \boldsymbol{B})_{k} + \frac{1}{3}\boldsymbol{E} \cdot \boldsymbol{B}\delta^{ij}$$
(28)

which expresses the tensor product of two vectors as the sum of an irreducable (traceless and symmetric) tensor, a vector, and a scalar,  $1 \otimes 1 = 2 \oplus 1 \oplus 0$ .

More physically it says that not all of  $E_iB_j$  is really described by a tensor. Rather, part of  $E_iB_j$  is described by the vector  $\mathbf{E} \times \mathbf{B}$ , and part is described by the scalar  $\mathbf{E} \cdot \mathbf{B}$ . It is for this reason that the tensors we work with in physics (*i.e.* the moment of inertia tensor, the quadrupole tensor, the maxwell stress tensor) are symmetric and traceless.

# Problem 5. 3d delta-functions

A delta-function in 3 dimensions  $\delta^3(\mathbf{r} - \mathbf{r}_o)$  is an infinitely narrow spike at  $\mathbf{r}_o$  which satisfies

$$\int d^3 \boldsymbol{r} \, \delta^3(\boldsymbol{r} - \boldsymbol{r}_o) = 1 \tag{29}$$

In spherical coordinates, where the measure is

$$d^{3}\boldsymbol{r} = r^{2}dr\,d(\cos\theta)\,d\phi = r^{2}\sin\theta\,dr\,d\theta\,d\phi\,,\tag{30}$$

we must have

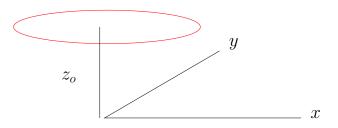
$$\delta^{3}(\boldsymbol{r}-\boldsymbol{r}_{o}) = \frac{1}{r^{2}}\delta(r-r_{o})\delta(\cos\theta-\cos\theta_{o})\delta(\phi-\phi_{o}) = \frac{1}{r^{2}\sin\theta}\delta(r-r_{o})\,\,\delta(\theta-\theta_{o})\delta(\phi-\phi_{o}) \quad (31)$$

so that  $\int d^3 \boldsymbol{r} \, \delta^3(\boldsymbol{r}) = 1$ . For a general curvlinear coordinate system

$$\delta^{3}(\boldsymbol{r} - \boldsymbol{r}_{o}) = \frac{1}{\sqrt{g}} \prod_{a} \delta(u^{a} - u_{o}^{a})$$
(32)

where  $u_o^a$  are the coordinates of  $r_o$ .

- (a) What is formula  $\delta^3(\boldsymbol{r} \boldsymbol{r}_o)$  for cylindrical coordinates?
- (b) A uniform ring of charge Q and radius a sits at height  $z_o$  above the xy plane, and the plane of the ring is parallel to the xy plane. Express the charge density  $\rho(\mathbf{r})$  (charge per volume) in spherical coordinates using delta-functions. Check that the volume integral of  $\rho(\mathbf{r})$  gives the total Q.



# Problem 6. Fourier Transforms of the Coulomb Potential

The fourier transfrom takes a function in coordinate space and represents in momentum  $\rm space^1$ 

$$F(k) = \int_{-\infty}^{\infty} dx \left[ e^{-ikx} \right] f(x)$$
(33)

The inverse transformation repesents a function as a sum of plane waves

$$F(x) = \int_{-\infty}^{\infty} \frac{dk}{2\pi} \left[ e^{ikx} \right] F(k) \tag{34}$$

The Fourier transform generalizes the concept of a fourier series to non-periodic, but square integrable functions  $-i.e. \int dx |f(x)|^2$  should converge.

The Fourier transform of a 3D function  $\mathbf{r} = (x, y, z)$  is:

$$F(\boldsymbol{k}) = \int d^3 \boldsymbol{r} \left[ e^{-i\boldsymbol{k}\cdot\boldsymbol{r}} \right] F(\boldsymbol{r})$$
(35)

$$F(\boldsymbol{r}) = \int \frac{d^3 \boldsymbol{k}}{(2\pi)^3} \left[ e^{i\boldsymbol{k}\cdot\boldsymbol{r}} \right] F(\boldsymbol{k})$$
(36)

To do this problem you will need to know (as discussed in class) that the integral of a pure phase  $e^{ikx}$  is proportional to a delta-fcn. In 3D we have

$$\delta^{3}(\boldsymbol{r}) = \int \frac{d^{3}\boldsymbol{k}}{(2\pi)^{3}} e^{i\boldsymbol{k}\cdot\boldsymbol{r}}$$
(37)

$$(2\pi)^3 \delta^3(\boldsymbol{k}) = \int d^3 \boldsymbol{r} \, e^{-i\boldsymbol{k}\cdot\boldsymbol{r}}$$
(38)

(a) Use tensors notation to show that the Fourier transform of  $\nabla F(\mathbf{r})$  is

$$i\mathbf{k}F(\mathbf{k}),$$
 (39)

and that the Fourier transform of the curl of a vector vector field  $\boldsymbol{F}(\boldsymbol{r})$  is  $\nabla \times \boldsymbol{F}(\boldsymbol{r})$  is

$$i\mathbf{k} \times \mathbf{F}(\mathbf{k})$$
 (40)

- (b) The genral rule is to replace  $\nabla \to i\mathbf{k}$ . What is the Fourier transform of  $\nabla^2 F(\mathbf{r})$
- (c) Prove the Convolution Theorem, *i.e.* the Fourier Transform of a product is a convolution

$$\int d^3 \boldsymbol{r} \, e^{-i\Delta \boldsymbol{k} \cdot \boldsymbol{r}} \, |F(\boldsymbol{r})|^2 = \int \frac{d^3 \boldsymbol{k}}{(2\pi)^3} F(\boldsymbol{k}) F^*(\boldsymbol{k} - \Delta \boldsymbol{k}) \tag{41}$$

making liberal use of the completeness integrals

$$\int d^3 \boldsymbol{r} \, e^{-i\boldsymbol{k}\cdot\boldsymbol{r}} = (2\pi)^3 \delta^3(\boldsymbol{k}) \tag{42}$$

<sup>&</sup>lt;sup>1</sup>The notation of putting  $e^{ikx}$  in square brackets is not standard, but I have used it in the notes to highlight the similarity between this expansion and other eigenfunction expansions.

**Remark:** Setting  $\Delta \mathbf{k} = 0$  we recover Parseval's Theorem

$$\int d^3 r |F(\mathbf{r})|^2 = \int \frac{d^3 \mathbf{k}}{(2\pi)^3} |F(\mathbf{k})|^2$$
(43)

**Remark:** This is often used in reverse, the fourier transform of a convolution is a product of the fourier transforms

F.T. of 
$$\int d^3 \boldsymbol{r}_o F(\boldsymbol{r}_o) G(\boldsymbol{r} - \boldsymbol{r}_o) = F(\boldsymbol{k}) G(\boldsymbol{k})$$
 (44)

(d) The Fourier transform of the Coulomb potential is difficult (try it and find out why!). This is because  $1/(4\pi r)$  is not in the space of square integrable functions (Why?). Thus, we will consider the Fourier transform of  $1/(4\pi r)$  to be the limit as  $m \to 0$  of the Fourier transform of a screened Coulomb potential known as the Yukawa potential

$$\Phi(\boldsymbol{x}) = \frac{e^{-m|\boldsymbol{r}|}}{4\pi|\boldsymbol{r}|} \tag{45}$$

The Yukawa potential is square integrable. Show that the Fourier transform of the Yukawa potential is

$$\Phi(\mathbf{k}) = \frac{1}{k^2 + m^2} \tag{46}$$

with  $k = \sqrt{k^2}$ . Thus, we conclude with  $m \to 0$  that

$$\int d^3 \boldsymbol{x} \ e^{-i\boldsymbol{k}\cdot\boldsymbol{r}} \ \frac{1}{4\pi r} = \frac{1}{k^2}$$
(47)

Note that the inverse transform can be computed by direct integration

$$\frac{1}{4\pi |\boldsymbol{r} - \boldsymbol{r}_o|} = \int \frac{d^3k}{(2\pi)^3} \frac{e^{i\boldsymbol{k}\cdot(\boldsymbol{r} - \boldsymbol{r}_o)}}{k^2}$$
(48)

(e) In electrostatics the electric field is the negative gradient of the potential,  $\boldsymbol{E} = -\nabla \Phi$ . From  $\nabla \cdot \boldsymbol{E} = \rho$ , we derive the Poisson equation  $-\nabla^2 \Phi = \rho$ . For a unit charge at the origin, the coulomb potential,  $1/(4\pi r)$ , satisfies

$$-\nabla^2 \Phi = \delta^3(\boldsymbol{r}) \tag{49}$$

Deduce Eq. (47) by fourier transforming this equation.