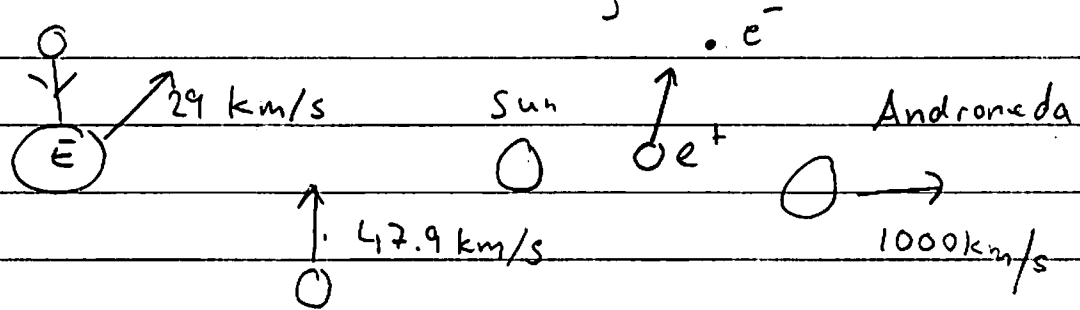


Today Relativity

Classical Motivations for Relativity



These observers should have the same laws of physics, but the force seems to be different

$$F = q \vec{E} + \vec{v} \times \vec{B} \quad \text{this is different for all observers}$$

Einstein; speed of Light is constant

Earth

$$\frac{d\vec{p}}{dt} = q \vec{E} + q \frac{\vec{v}}{c} \times \vec{B}$$

$$\nabla \cdot \vec{E} = \rho$$

$$-\frac{1}{c} \partial_t \vec{E} + \nabla \times \vec{B} = \vec{j} / c$$

$$\nabla \cdot \vec{B} = 0$$

$$+\frac{1}{c} \partial_t \vec{B} + \nabla \times \vec{E} = 0$$

The only thing relativity changes is the relation between \vec{v} and \vec{p}

$$\frac{\vec{v}}{c} = \frac{c \vec{p}}{E} \quad \text{energy}$$

Andromeda measures the same equations: (But renames t, x, E, B)

$$\frac{d\vec{p}}{dt} = q \vec{E} + q \frac{\vec{v}}{c} \times \vec{B}, \quad \nabla \cdot \vec{E} = \rho, \quad -\frac{1}{c} \partial_t \vec{E} + \nabla \times \vec{B} = \vec{j} / c$$

Relativity relates $(t, x, \vec{E}, \vec{B}, \rho, \vec{j})$ to $(\underline{t}, \underline{x}, \underline{\vec{E}}, \underline{\vec{B}}, \underline{\rho}, \underline{\vec{j}})$

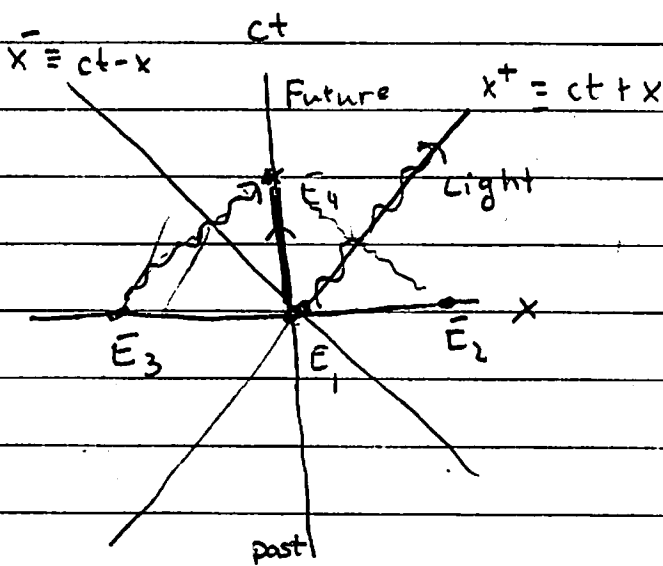
Transformation of Coords

- We describe physics as a sequence of events labelled by space-time coordinates

$$x^{\mu} = (x^0, x^1, x^2, x^3) = (ct, \vec{x})$$

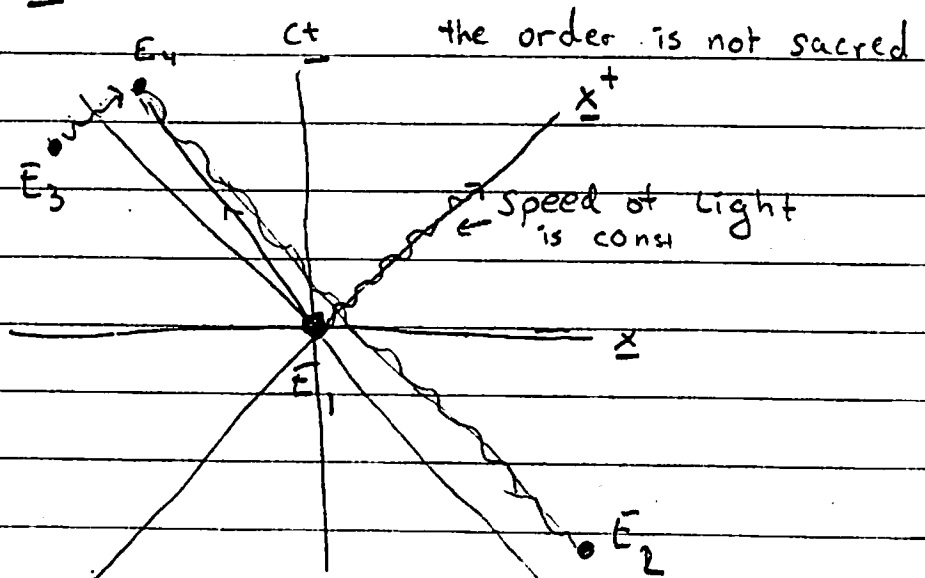
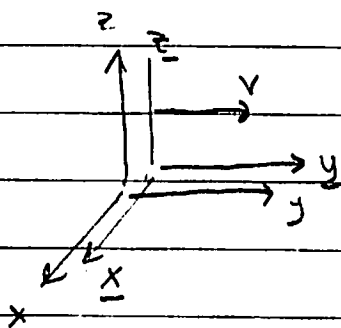
k

Then an observer k sets up his own coordinates, recording events



An observer k moving with speed v to the right relative to the first makes measurements of same events:

- (a) his own coordinates \underline{x}^{μ} . For causally disconnected events



We seek a change of coordinates which leave the trajectory of light fixed, $c = x/t$

$$-(ct)^2 + x^2 = -\underline{ct^2} + \underline{x^2}$$

i.e. it is the same for both observers

So $x^\mu \rightarrow \underline{x^\mu} = L^\mu_\nu(v) x^\nu$, or as matrices

$$\begin{pmatrix} \underline{x^0} \\ \underline{x^1} \\ \underline{x^2} \\ \underline{x^3} \end{pmatrix} = \begin{pmatrix} L(v) \end{pmatrix} \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix}$$

Properties

$$L(-\vec{v})L(\vec{v}) = 1 \quad \star$$

$$L(v_2)L(v_1) = L(v_3) \quad \star\star$$

This is known as a group of transformations. The Lorentz Group. With these properties find, for v in x^1 direction

$$\begin{pmatrix} \underline{x^0} \\ \underline{x^1} \\ \underline{x^2} \\ \underline{x^3} \end{pmatrix} = \begin{pmatrix} \gamma & -\gamma\beta & & \\ -\gamma\beta & \gamma & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix} \quad \begin{matrix} \gamma = \frac{1}{\sqrt{1-\beta^2}} \\ \beta = \frac{v}{c} \end{matrix}$$

defines L^μ_ν

in general use vectors to express boosts in a general direction

Often use a parameter y (the rapidity) to parametrize the boost matrix instead of v to parametrize the boost

$$\frac{v}{c} = \tanh y \rightarrow y = \tanh^{-1} \frac{v}{c} = \frac{1}{2} \ln \left(\frac{1+\beta}{1-\beta} \right)$$

Then $\beta \approx \beta$ for small β

$$\gamma = \cosh y \quad \text{and} \\ \gamma\beta = \sinh y$$

The Lorentz boost is a hyperbolic rotation

$$\begin{pmatrix} x^0 \\ x^1 \end{pmatrix} = \begin{pmatrix} \cosh y & -\sinh y \\ -\sinh y & \cosh y \end{pmatrix} \begin{pmatrix} x^0 \\ x^1 \end{pmatrix}$$

Exercises

① Show that the Lorentz boost compresses x^+ and expands x^- , by the factors of e^{-y} and e^{+y} .

$$\underline{x^+} = \sqrt{\frac{1-\beta}{1+\beta}} x^+ \quad \underline{x^-} = \sqrt{\frac{1+\beta}{1-\beta}} x^-$$

$$\underline{x^+} = e^{-y} x^+ \quad \underline{x^-} = e^{+y} x^-$$

Four Vectors and Tensors (Mechanics of Indices)

① The coordinates obey a transformation rule

$$\underline{X^{\mu}} = L^{\mu}_{\nu} X^{\nu}$$

we call any set of four quantities which transform in this way a four vector. Upper indices are referred to as contravariant components

$$\underline{A^{\mu}} = L^{\mu}_{\nu} A^{\nu}$$

$$\underline{B^{\mu}} = L^{\mu}_{\nu} A^{\nu}$$

Any two four vectors which transform in this way have an invariant product, $\underline{A^{\mu}} \equiv (a^0, \vec{a})$ and $\underline{B^{\mu}} \equiv (b^0, \vec{b})$

$$\underline{A} \cdot \underline{B} = -a^0 b^0 + \vec{a} \cdot \vec{b} = \underline{A} \cdot \underline{B} = -\underline{a}^0 \underline{b}^0 + \underline{\vec{a}} \cdot \underline{\vec{b}}$$

because L was adjusted to preserve this quadratic form

② For any set of ^(upper) contravariant indices, define their _(lower) covariant counterparts with the metric tensor:

$$\underline{X}_{\mu} \equiv (-ct, \vec{x})$$

$$\underline{X}_{\mu} = g_{\mu\nu} X^{\nu} \quad g_{\mu\nu} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

Lowering indices just changes sign of 0-th component, Sim,
we raise indices with $g^{\mu\nu}$:

$$X^\mu = g^{\mu\nu} X_\nu \quad g^{\mu\nu} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

So clearly

$$X^\mu = g^{\mu\nu} g_{\nu\sigma} X^\sigma \quad g^\mu{}_\sigma = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

$\delta^\mu{}_\sigma = g^\mu{}_\sigma = \text{Identity matrix}$

We define Covariant indices so the inner product,
can now be written as

$$A \cdot B = A_\mu B^\mu = -a^0 b^0 + \vec{a} \cdot \vec{b}$$

③ Note if $A_\mu A^\mu$ is to be invariant under Lorentz transformation, then since $A^\mu = L^\mu{}_\nu A^\nu$, we define the transformation rule for lower indices (covariant components) with L^{-1} and as a row

$$\underline{A}_\nu = A_\mu (L^{-1})^\mu{}_\nu \quad \text{or} \quad \underline{A}_\nu = (L^{-1T})_\nu{}^\mu A_\mu$$

i.e. lower indices transform with inverse and as a row

$$(\underline{A}_0, \underline{A}_1, \underline{A}_2, \underline{A}_3) = (A_0, A_1, A_2, A_3) \begin{pmatrix} L^{-1} \end{pmatrix}$$

So that

$$\begin{aligned}\underline{A}_\mu \underline{B}^\mu &= (\underline{A}_0 \underline{A}_1 \underline{A}_2 \underline{A}_3) \begin{pmatrix} \underline{B}^0 \\ \underline{B}^1 \\ \underline{B}^2 \\ \underline{B}^3 \end{pmatrix} \\ &= (\underline{A}_0 \underline{A}_1 \underline{A}_2 \underline{A}_3) (L^{-1})(L) \begin{pmatrix} \underline{B}^0 \\ \underline{B}^1 \\ \underline{B}^2 \\ \underline{B}^3 \end{pmatrix} \\ &= \underline{A}_\mu \underline{B}^\mu\end{aligned}$$

(4) Note that under lorentz transform

$$\begin{aligned}\underline{A} \cdot \underline{B} &= \underline{A}^\mu g_{\mu\nu} \underline{B}^\nu = -\underline{a}^0 \underline{b}^0 + \underline{\vec{a}} \cdot \underline{\vec{b}} \\ &= \underline{A}^\mu g_{\mu\nu} \underline{B}^\nu = -\underline{a}^0 \underline{b}^0 + \underline{\vec{a}} \cdot \underline{\vec{b}} = \underline{A} \cdot \underline{B}\end{aligned}$$

Without the need of transforming $g_{\mu\nu}$. This says that $g_{\mu\nu}$ is an invariant tensor

$$(L^{-1T})^\rho_\mu g_{\rho\sigma} L^{-1\sigma}_\nu = g_{\mu\nu}$$

Or in matrices:

$$(L^{-1T}) g L^{-1} = g$$

i.e.

$$L^{-1T} = g L g \quad (\text{note } g^{-1} = g)$$

Restoring indices

$$g_{\mu\nu}(L^\nu{}_\rho) g^{\rho\sigma} = (L^{-1T})^\sigma{}_\mu$$

In a fit of notational madness (which is standard) we define

$$\boxed{L_{\mu}{}^\sigma \equiv g_{\mu\nu} L^\nu{}_\rho g^{\rho\sigma} = (L^{-1T})^\sigma{}_\mu}$$

So perhaps its not so mad

$$\begin{aligned} A_{\mu}{}^\nu &= A_\rho (L^{-1})^\mu{}_\nu \\ &= (L^{-1T})^\mu{}_\nu A_\rho \end{aligned}$$

$$\boxed{A_{\mu}{}^\nu = L_{\nu}{}^\mu A_\rho}$$

Exercise

- A tensor transforms as

$$\underline{T}^{\mu\nu} = L^{\mu}_{\rho} L^{\nu}_{\sigma} T^{\rho\sigma}$$

Show that the transformation rule for T^{μ}_{ν} is

$$\underline{T}^{\mu}_{\nu} = L^{\mu}_{\rho} T^{\rho}_{\sigma} (L^{-1})^{\sigma}_{\nu}$$

or equivalently

$$\underline{T}^{\mu}_{\nu} = L^{\mu}_{\rho} L^{\sigma}_{\nu} T^{\rho}_{\sigma}$$

Solution:

• Lower ν ,

$$T^{\mu}_{\nu} = L^{\mu}_{\rho} L^{\sigma}_{\nu} T^{\rho\sigma}$$

$$T^{\mu}_{\nu} = L^{\mu}_{\rho} L^{\sigma}_{\nu} T^{\rho}_{\sigma}$$

$$= L^{\mu}_{\rho} T^{\rho}_{\sigma} (L^{-1})^{\sigma}_{\nu}$$

$$= L^{\mu}_{\rho} T^{\rho}_{\sigma} (L^{-1})^{\sigma}_{\nu}$$

Excercise:

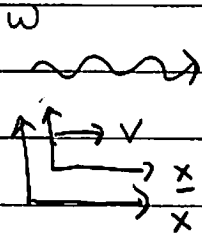
- Explain that if a plane wave of light $e^{-i\omega t + \vec{k} \cdot \vec{x}}$ where $k = \frac{\omega}{c}$, is to move at the speed of light in all frames, then

$$K^\mu = \left(\frac{\omega}{c}, \vec{k} \right)$$

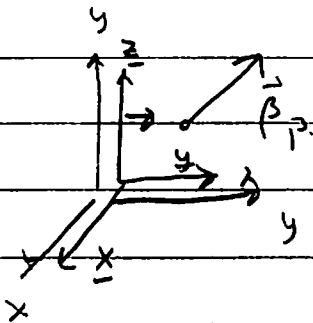
must be a four vector. ① Show that

$K \cdot K = 0$. ② and show the relativistic doppler shift formula is

$$\underline{\omega} = \sqrt{\frac{1-\beta}{1+\beta}} \omega$$



Particles in Special Relativity + Proper Time



$$\vec{\beta}_P = \frac{V_P}{c}$$

$$\bullet \quad dx^\mu = (cdt, d\vec{x}) = dx^0 (1, \vec{\beta}_P)$$

put $\vec{\beta}_P = \frac{d\vec{x}}{dx^0}$ to distinguish from $\beta = \frac{v}{c}$

note

• Then we can construct the invariant

$$ds^2 = dx_\mu dx^\mu = -c^2 dt^2 (1 - \beta_P^2)$$

Since it is invariant we can interpret it in the rest frame of the particle, where $dt = d\tau$

$$ds^2 = -c^2 d\tau^2 \leftarrow \text{proper time. time between clicks in the particle's wrist watch}$$

So in any frame:

$$d\tau = \sqrt{-ds^2/c^2} = dt \sqrt{1 - \beta_P^2}$$

or

$$\boxed{d\tau = \frac{dt}{\gamma_P}}$$

- Define the four velocity as the distance per unit proper time

$$U^\mu = \frac{dx^\mu}{d\tau} \leftarrow \text{this is a four vector since } dx^\mu \text{ is a four vector and } d\tau \text{ is a Lorentz scalar}$$

Then

$$\begin{aligned} U^\mu &= \gamma_p \frac{dx^\mu}{dt} = \gamma_p \left(c \frac{dt}{dt}, \frac{d\vec{x}}{dt} \right) \\ &= (\gamma_p c, \gamma_p \vec{v}_p) \equiv (u^0, \vec{u}) \end{aligned}$$

Exercise

i) Show that $U_\mu U^\mu = -c^2$

ii) Show that

$$\frac{\vec{u}}{u^0} = \frac{\vec{v}_p}{c}$$

$$\frac{dx_\mu dx^\mu}{d\tau d\tau} = \frac{ds^2}{(d\tau)^2} = -c^2 \frac{dt^2}{dt^2} = -c^2$$

- Energy and Momentum of a Particle. Consider the action

$$S = \int L dt = \int p dq - H dt$$

So the action of a free particle involves

$$S = \vec{p} \cdot d\vec{x} - \vec{E} \cdot dt$$

So it is almost irresistible to make E/c and momentum a four vector. Good things will happen if you do, specifically energy and momentum will be conserved in all frames. ^(not proved!!) Thus we require that the quantities E/c and \vec{p} form a four vector

$$P^\mu \equiv \left(\frac{E}{c}, \vec{p} \right)$$

Then $P \cdot dX = -E dt + \vec{p} \cdot d\vec{x}$ is Lorentz invariant. Requiring that at small velocities, $\vec{p} \approx m\vec{v}$ leads to

$$P^\mu = m u^\mu = \left(m c \gamma_p, m \gamma_p \vec{v} \right)$$

$$\uparrow \text{ or } E = \gamma_p m c^2$$

Exercises:

i) Show that $P_\mu P^\mu = -(mc)^2$ and $\frac{v_p}{c} = \frac{\vec{p}}{\sqrt{p^2 + (mc)^2}}$

ii) And $\frac{\vec{v}}{c} = \frac{\vec{p}}{E/c} = \frac{\partial E}{\partial \vec{p}}$ = think group velocity

iii) From the transformation rule $\underline{u}^\mu = L^\mu_\nu u^\nu$ deduce that the velocity transforms as

$$\underline{v}_p = \frac{(v_p - v)}{(1 - v_p v/c^2)}$$

for a particle moving in x-direction @ velocity v_p and an observer moving with rel. velocity v

Covariant Electrodynamics

① $\partial_\mu \equiv \frac{\partial}{\partial x^\mu} = \left(\frac{1}{c} \frac{\partial}{\partial t}, \vec{\nabla} \right)$ transforms as a four vector.

$$\frac{\partial}{\partial x^\mu} = \frac{\partial}{\partial x^\nu} (L^\mu{}_\nu)$$

There is also ^{contra}variant components $\partial^\mu = \left(-\frac{1}{c} \frac{\partial}{\partial t}, \vec{\nabla} \right)$

So

$$\partial_\mu \partial^\mu = -\frac{1}{c^2} \frac{\partial^2}{\partial t^2} + \nabla^2 \equiv \square = \frac{\partial^2}{\partial x_\mu^2}$$

is invariant

② Then there is the continuity Eqn

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{j} = 0 \Rightarrow \frac{1}{c} \frac{\partial (c\rho)}{\partial t} + \nabla \cdot \vec{J} = 0$$

So take

$J^\mu = (c\rho, \vec{J})$, as a four vector,

$$\partial_\mu J^\mu = 0$$

③ Then the equations for the gauge potential

$$-\square \phi = J^0/c$$

$$-\square \vec{A} = \vec{J}/c$$

Together with the Lorentz gauge condition:

$$\frac{1}{c} \frac{\partial \phi}{\partial t} + \nabla \cdot \vec{A} = 0$$

So in order to have a Lorentz invariant theory take (ψ, \vec{A}) to be a four vector

$$A^\mu = (\psi, \vec{A})$$

Then the wave eqn becomes

$$\boxed{-\square A^\mu = J^\mu / c} \quad \text{and} \quad \boxed{\partial_\mu A^\mu = 0}$$

④ Now the fields

$$\left. \begin{aligned} \vec{E} &= -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} - \nabla \psi \\ \vec{B} &= \nabla \times \vec{A} \end{aligned} \right\}$$

These are combined into a rank 2 antisymmetric tensor

Where

$$F^{\alpha\beta} = \begin{matrix} & \beta \longrightarrow \\ \begin{matrix} \downarrow \alpha \\ \downarrow \end{matrix} & \begin{pmatrix} 0 & E^x & E^y & E^z \\ -E^x & 0 & B^z & -B^y \\ -E^y & -B^z & 0 & B^x \\ -E^z & B^y & -B^x & 0 \end{pmatrix} \end{matrix} \equiv \partial^\alpha A^\beta - \partial^\beta A^\alpha$$

We can see this

$$F^{0i} \equiv E^i = -\frac{1}{c} \frac{\partial A^i}{\partial t} - \frac{\partial \varphi}{\partial x_i} = \partial^0 A^i - \partial^i A^0 \equiv F^{0i}$$

$$B_k = (\nabla \times A)_k$$

$$\begin{aligned} F^{ij} &= \varepsilon^{ijk} B_k = \varepsilon^{ijk} \underbrace{\varepsilon_{klm}}_{(\delta^i_l \delta^j_m - \delta^j_l \delta^i_m)} \partial^l A^m \\ &= \partial^i A^j - \partial^j A^i \end{aligned}$$

So $F^{\alpha\beta} = \partial^\alpha A^\beta - \partial^\beta A^\alpha$ transforms as a second rank tensor in the following way

$$F^{\mu\nu} = L^\mu_\alpha L^\nu_\beta F^{\alpha\beta}$$

Exercise,

• Show that

$$F^i = F^{0i} = -F^{i0} = F^i_0 = -F_0^i = F^{0i}$$

5) Now the EOM (Part I)

$$\nabla \cdot \mathbf{E} = \rho \Rightarrow -\partial_\mu \overbrace{F^{\mu 0}}^{(-E^i)} = \overbrace{J^0/c}^{\rho}$$

and

$$-\frac{1}{c} \partial_t \mathbf{E} + \nabla \times \mathbf{B} = \frac{\mathbf{J}}{c} \Rightarrow -\left(\frac{\partial}{\partial x^0} F^{0i} + \frac{\partial}{\partial x^l} F^{li} \right) = J^i/c$$

So

$$\boxed{-\partial_\alpha F^{\alpha\beta} = J^\beta/c}$$

Exercise:

• Starting from $-\partial_\alpha F^{\alpha\beta} = J^\beta/c$ and the definition of $F^{\alpha\beta}$ derive:

$$-\square A^\beta = J^\beta/c$$

Solution

$$-\partial_\alpha \underbrace{(\partial^\alpha A^\beta - \partial^\beta A^\alpha)}_{\equiv F^{\alpha\beta}} = -\partial_\alpha \partial^\alpha A^\beta + \partial^\beta (\partial_\alpha A^\alpha) = J^\beta$$

Lorentz Gauge
↓

Lorentz Gauge $\partial_\alpha A^\alpha = 0$, so

$$-\partial_\alpha \partial^\alpha A^\beta = 0 \quad \text{or} \quad -\square A^\beta = J^\beta$$

⑥ The Remaining Maxwell Eqs

$$\nabla \cdot \mathbf{B} = 0$$

$$\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t} + \nabla \times \mathbf{E} = 0$$

Comparison with the first two eqs in absence of currents gives

$$\left. \begin{array}{l} \nabla \cdot \mathbf{E} = 0 \\ -\frac{1}{c} \frac{\partial \mathbf{E}}{\partial t} + \nabla \times \mathbf{B} = 0 \end{array} \right\}$$

So the second two Maxwell eqs involve the replacement (duality)
 $\mathbf{E} \rightarrow \mathbf{B}$ and $\mathbf{B} \rightarrow -\mathbf{E}$.

Thus define the dual tensor

$$\tilde{F}^{\mu\nu} = \begin{pmatrix} 0 & B^x & B^y & B^z \\ -B^x & 0 & -E^z & E^y \\ -B^y & E^z & 0 & -E^x \\ B^z & -E^y & E^x & 0 \end{pmatrix}$$

So

$$\partial_\mu \tilde{F}^{\mu\nu} = 0$$

The dual tensor can be defined from $F_{\mu\nu}$

$$\tilde{F}^{\mu\nu} = \frac{1}{2} \epsilon^{\mu\nu\alpha\beta} F_{\alpha\beta} \quad \leftarrow \text{this implements the replacement } \vec{E} \rightarrow \vec{B}, \vec{B} \rightarrow -\vec{E}$$

Here

$$\epsilon^{\mu\nu\alpha\beta} = \begin{cases} +1 & \text{for even perms of } 0,1,2,3 \\ -1 & \text{for odd perms of } 0,1,2,3 \\ 0 & \text{otherwise} \end{cases}$$

Expressing in terms of $\epsilon^{\mu\nu\alpha\beta}$ antisymmetric in $\mu\alpha\beta$

$$\partial_\mu \tilde{F}^{\mu\nu} = -\frac{1}{2} \epsilon^{\nu\mu\alpha\beta} \partial_\mu F_{\alpha\beta} = 0$$

This can be written as the Bianchi-Identity

$$\partial_{[\mu} F_{\nu_1 \nu_2 \nu_3]} = 0 \quad \text{or} \quad \partial_{\mu_1} F_{\mu_2 \mu_3} - \partial_{\mu_2} F_{\mu_1 \mu_3} + \partial_{\mu_3} F_{\mu_1 \mu_2}$$

where $\partial_{[\mu} F_{\nu_1 \nu_2 \nu_3]}$ stands for the antisymmetric combo

examples

$$T_{[\mu_1 \mu_2]} = \frac{1}{2!} (T_{\mu_1 \mu_2} - T_{\mu_2 \mu_1})$$

like a 2x2 determinant

$$T_{[\mu_1 \mu_2 \mu_3]} = \frac{1}{3!} \left[(T_{\mu_1 \mu_2 \mu_3} - T_{\mu_1 \mu_3 \mu_2}) - (T_{\mu_2 \mu_1 \mu_3} - T_{\mu_2 \mu_3 \mu_1}) + (T_{\mu_3 \mu_1 \mu_2} - T_{\mu_3 \mu_2 \mu_1}) \right]$$

like a 3x3 determinant

Exercise

Show that if $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$ then the second two Maxwell eqs are automatically satisfied

Solution

$$\begin{aligned}\partial_\mu \tilde{F}^{\mu\nu} &= \partial_\mu \frac{1}{2} \epsilon^{\mu\nu\alpha\beta} (\partial_\alpha A_\beta - \partial_\beta A_\alpha) \\ &= -\frac{1}{2} \epsilon^{\nu\mu\alpha\beta} (\partial_\mu \partial_\alpha A_\beta - \partial_\mu \partial_\beta A_\alpha) = 0\end{aligned}$$

But, $\underbrace{\partial_\mu \partial_\alpha A_\beta = \partial_\alpha \partial_\mu A_\beta}_{\text{Symmetric}}$ and $\underbrace{\epsilon^{\nu\mu\alpha\beta} = -\epsilon^{\nu\alpha\mu\beta}}_{\text{antisymmetric}}$

And the contraction of antisymmetric and a symmetric tensor gives zero.