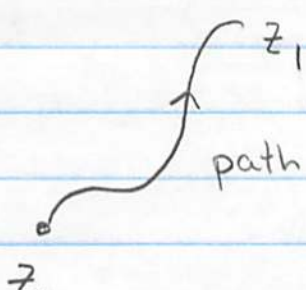


Integration

 path in complex plane $(x(t), y(t)) \equiv \gamma(t)$
real parameter of path

$$dx \equiv \dot{x} dt \quad dy = \dot{y} dt$$

$$\int_{z_0}^{z_1} f dz = \int_{z_0}^{z_1} (u + iv) (dx + idy)$$
$$= \int_{\text{path}} u dx - v dy + i \int_{\text{path}} v dx + u dy$$

Example 1

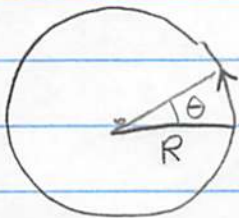
This is important!

$$I = \oint_{\text{circle}} \frac{dz}{z}$$

Parametrize the path by θ :

$$z = R e^{i\theta} = R \cos\theta + i R \sin\theta$$

$$dz = R e^{i\theta} i d\theta = z i d\theta$$




Thus:

$$\oint_{\text{circle}} \frac{dz}{z} = \int_0^{2\pi} i d\theta = 2\pi i$$

↑
no matter the size

Example 2 • Circle again


- Go twice around the circle the "clockwise" / "wrong" / "opposite" way $z = R e^{-i\theta}$



$$\oint_{\bar{z}} dz = \int_0^{2(2\pi)} -i d\theta = (2\pi i) (-2) \text{ wrong way}$$

- Changing the direction changes the sign!!

Example 3 for n integer (positive or negative but not zero)



$$I = \oint_{\bar{z}} dz z^n$$

circle again

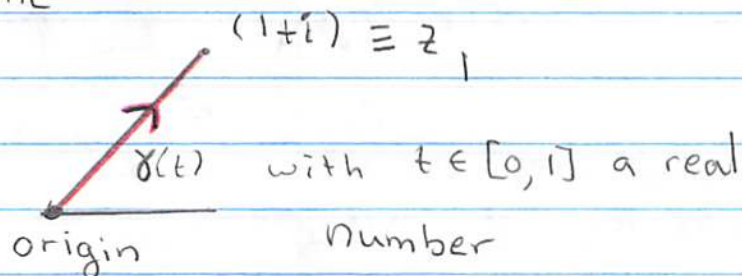
$$I = \int_0^{2\pi} i d\theta R^n e^{in\theta} = R^n \int_0^{2\pi} e^{in\theta} d\theta$$

n integer

$$I = 0 \text{ independent of } R!$$

Example 4 • Straight line

$$I = \int_0^{z_1} z^n dz$$



$$\begin{aligned} z(t) &= t(1+i) & dz &= dt(1+i) \\ &= t z_1 & dz &= dt z_1 \end{aligned}$$

Then

$$I = \int_0^1 (z_1 t)^n z_1 dt$$

$$= z_1^n \int_0^1 t^n dt$$

$$I = \frac{z_1^n}{n+1} \quad \text{as you could have hoped!}$$

For a general straight line connecting z_0 and z_1 ,

$$I = \int_{z_0}^{z_1} dz (z - z_0)^n = \frac{(z_1 - z_0)^{n+1}}{n+1}$$

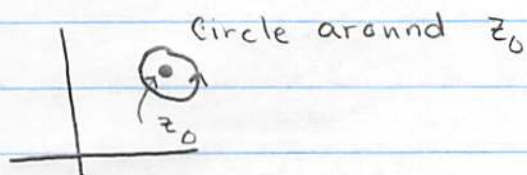
In fact the path, doesn't matter for holomorphic functions as we show next!

Example 5 Just shift example 1 and 3

$$\oint_{\text{Circle}} \frac{dz}{z - z_0} = 2\pi i$$

$$\oint_{\text{Circle}} \frac{dz}{z - z_0} (z - z_0)^n = 0$$

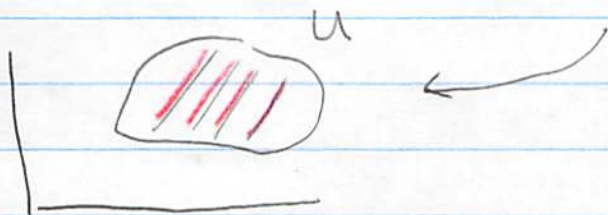
↑
for n positive,
negative, but not zero
integer



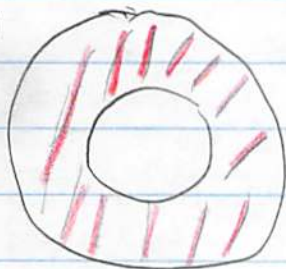
Prove it yourself. Set $(z - z_0) = R e^{i\theta}$ ← parameter of integration

Some Terminology

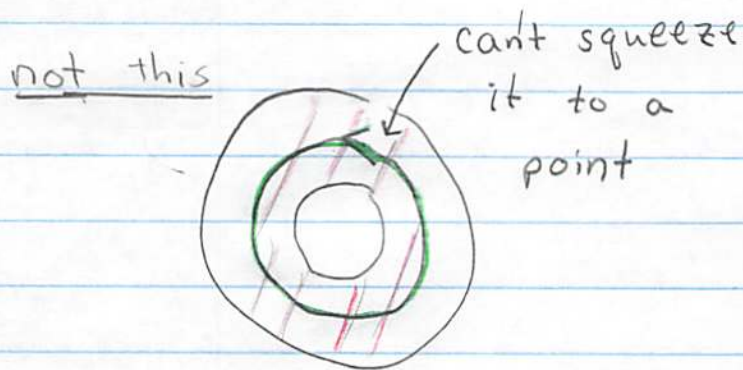
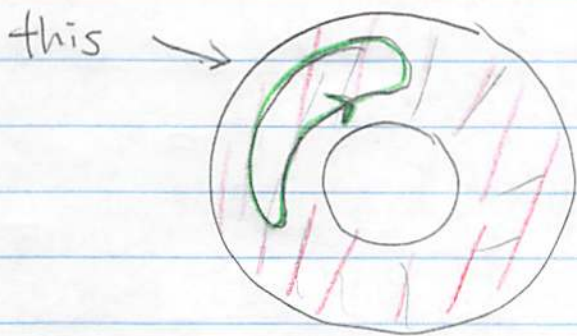
- An open simply connected set in the complex plane looks like this



This is connected, but not simply connected, because it has a hole in it



- A non-intersecting curve deformable to a point, or homologous/homotopic to a point, looks like:



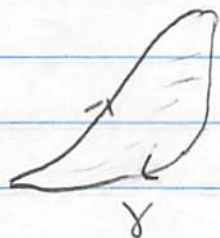
- Every closed curve in a simply connected set is deformable to a point.

Cauchy Theorem in Homotopic Form

Consider open set in the complex plane. Assume that $f(x, y)$ is holomorphic in U



Then on any closed non-intersecting path, deformable to a point in U :



$$I = \oint_{\gamma} dz f(z) = 0$$

Proof

$$I = \oint_{\text{path}} u dx - v dy + i \oint_{\text{path}} v dx + u dy$$

In general the Stokes theorem says for $P(x, y), Q(x, y)$

$$\oint_{\text{loop}} P dx + Q dy = \int_{\text{area}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

Yielding in this case

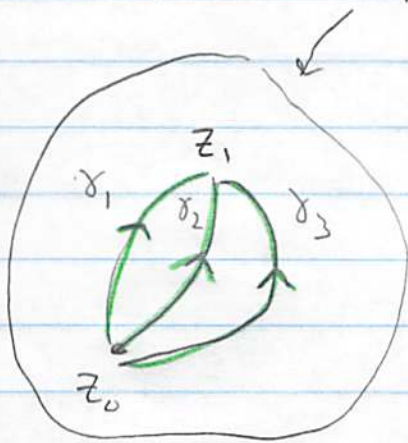
By Cauchy Riemann

So

$$I = \int dx dy \left(\frac{-\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) + i \int dx dx \left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right)$$

Examples

(1)



Open set U where $f(z)$ is holomorphic
 $\gamma_1, \gamma_2, \gamma_3$ are homotopic (homologous)
 since you can deform γ_1 to γ_2 while
 remaining in U . They all give

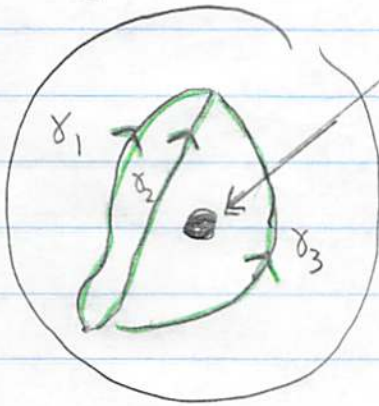
$$\int_{\gamma_1} = \int_{\gamma_2} = \int_{\gamma_3}$$

the same integral

$$\int_{z_0}^{z_1} f(z) dz$$

not simply connected, but still connected & open.

(2)

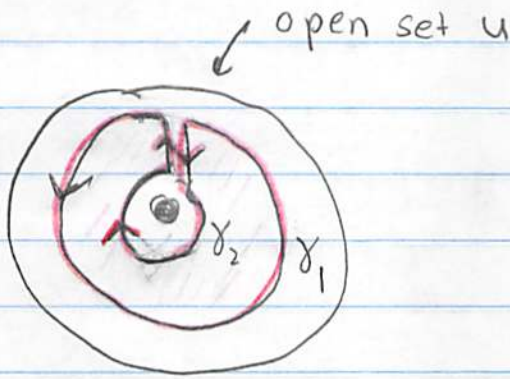


open set now excludes
 the origin (where for example the
 function is not holomorphic)

• γ_1 and γ_2 have the
 same integral. they are
 homotopic / homologous

• γ_1 and γ_3 are not homologous and their integrals
 are not the same

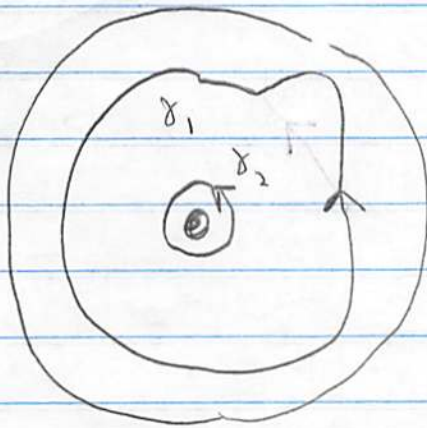
(3)



- The curve $\gamma_1 + \gamma_2$ is deformable to a point, gives zero for analytic functions

$$\int_{\gamma_1} f(z) dz + \int_{\gamma_2} f(z) dz = 0 \quad \text{i.e. } I_{\gamma_1} = -I_{\gamma_2}$$

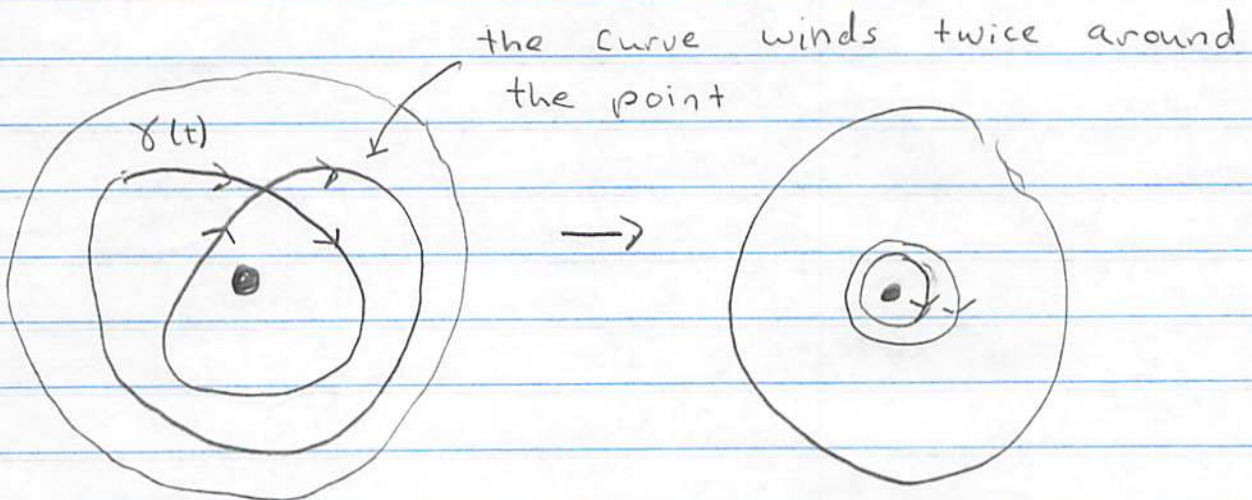
(4)



$$\oint_{\gamma_1} dz f(z) = \oint_{\gamma_2} dz f(z)$$

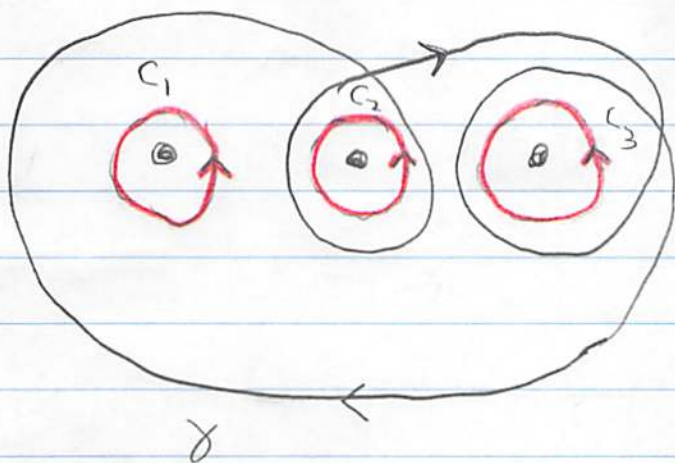
- The two contours now point in the same direction (unlike Ex. 3)

(5)



$$\oint_{\gamma} dz f(z) = 2 \oint_{\text{circle}} dz f(z)$$

(6) One more:

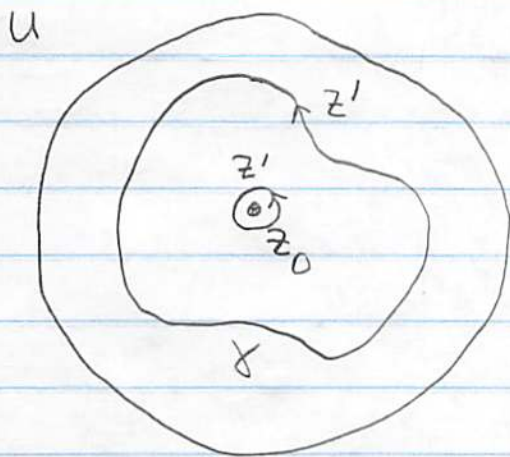


$$\oint_{\gamma} dz f(z) = -\oint_{C_1} f(z) dz - 2 \oint_{C_2} f(z) dz - 2 \oint_{C_3} f(z) dz$$

circle twice around, but
 γ goes clockwise while C_1, C_2, C_3
go counter-clockwise the "normal"
way

Cauchy Formula, Holomorphy = analyticity

Then consider the integral of a holomorphic function around a path deformable to a point which contains z_0 :



$$I = \oint_{\gamma} \frac{dz'}{z' - z_0} f(z')$$

Now deform γ to a small circle around z_0 . We can do this because $f(z')$ and $1/(z' - z_0)$ are holomorphic except at z_0 .

$$I = \oint_{\text{circle}} dz' \frac{f(z')}{z' - z_0}$$

But $f(z)$ is holomorphic/continuous at z_0 and is thus approximately constant $f(z') \approx f(z_0) + \text{tiny}$

$$I = f(z_0) \oint \frac{dz'}{z' - z_0} = f(z_0) 2\pi i$$

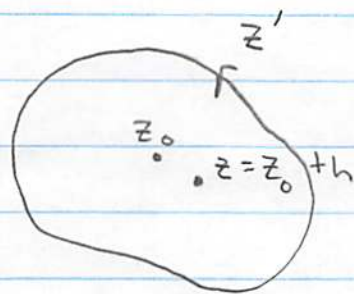
And we find

$$f(z_0) = \frac{1}{2\pi i} \oint_{\gamma} \frac{dz' f(z')}{(z' - z_0)}$$

There is more. Pick a point $z = z_0 + h$ close to z_0 with h small

$$f(z_0 + h) = \frac{1}{2\pi i} \oint \frac{f(z')}{z' - (z_0 + h)}$$

And expand in h :



$$\frac{1}{z' - (z_0 + h)} = \frac{1}{z' - z_0} \frac{1}{\left(1 - \frac{h}{z' - z_0}\right)}$$

this converges for h small

$$= \frac{1}{z' - z_0} \left[1 + \left(\frac{h}{z' - z_0}\right) + \left(\frac{h}{z' - z_0}\right)^2 + \dots \right]$$

Then

$$f(z_0 + h) = \frac{1}{2\pi i} \oint \frac{f(z')}{z' - z_0} \left[\frac{1}{z' - z_0} + \frac{h}{(z' - z_0)^2} + \frac{h^2}{(z' - z_0)^3} + \dots \right]$$

i.e.

$$f(z_0 + h) = \sum_{n=0}^{\infty} a_n h^n \quad \leftarrow \text{Taylor series}$$

with

$$a_n = \frac{f^{(n)}(z_0)}{n!} = \frac{1}{2\pi i} \oint \frac{dz' f(z')}{(z' - z_0)^{n+1}}$$

• Thus we have shown that holomorphic functions (i.e. satisfying cauchy-riemann equations) are analytic by explicit construction.