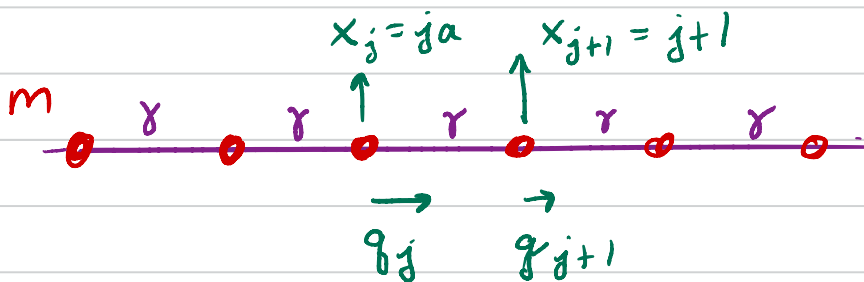


## Transition To Continuum

- Goldstein 13.1
- Consider an infinite chain of oscillators.
- The unperturbed positions are  $x_j = ja$ .  
The mass is  $m$ , the spring constant is  $\gamma$  (since  $k$  will be needed for wavenumber). The displacement of the  $j$ -th site is  $q_j(t)$



The oscillators have a Lagrangian

$$L = \sum_j \frac{1}{2} m \dot{q}_j^2 - \frac{1}{2} \gamma (q_{j+1} - q_j)^2$$

with EOM

$$m \ddot{q}_j = \gamma (q_{j+1} - q_j) - \gamma (q_j - q_{j-1})$$

i.e

$$m \frac{d^2}{dt^2} \begin{pmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{pmatrix} = \begin{pmatrix} -2\gamma & \gamma & & \\ \gamma & -2\gamma & \gamma & \\ & \gamma & -2\gamma & \gamma \\ & & \gamma & -2\gamma \end{pmatrix}$$

- As usual we look for eigenmodes

$$q_j = A E_j e^{-i\omega t}$$

↑ eigenfrequency

- Substituting we have

$$\star -m\omega^2 E_j - \gamma(E_{j+1} - E_j) + \gamma(E_j - E_{j-1}) = 0$$

①
②
③

- Motivated by the wavelike solution we take

$$E_j = e^{ikx_j}, \text{ so } q_j = A e^{ikx_j - i\omega t}$$

↑ eigenvector

- Now

$$\begin{aligned} \textcircled{1} \quad q_{j+1} - q_j &= A e^{-i\omega t} (e^{ikx_{j+1}} - e^{ikx_j}) \\ &= A e^{-i\omega t + ikx_j} (e^{ika} - 1) \end{aligned}$$

$$\textcircled{2} \quad q_{j-1} - q_j = A e^{-i\omega t + ikx_j} (1 - e^{-ika})$$

$$\textcircled{3} \quad m\omega^2 q_j = A e^{-i\omega t + ikx_j}$$

- So equation  $\star$  yields

$$-m\omega^2 + \gamma \underbrace{(2 - e^{ika} - e^{-ika})}_{= 4\sin^2(ka/2)} = 0$$

- Or

$$\omega_0 \equiv \sqrt{\frac{\gamma}{m}}$$

$$\omega^2(k) = 4\omega_0^2 \sin^2(ka/2)$$

Debye  
Dispersion  
Curve

## Summary:

① We have found a set of eigenvectors labelled by  $k$ . If only one eigenmode is excited

$$q_j(t) = \text{Re} [ A_k E_j^k e^{-i\omega t} ]$$
$$= \text{Re} [ A_k e^{ikx_j - i\omega(k)t} ]$$

eigenfrequency

② The eigen-frequency for a given  $k$  is

$$\omega(k) = \pm 2\omega_0 \sin(ka/2)$$



## Transition to the Continuum

- In the low- $k$  limit we do not "see" the individual atoms. We should be able to reproduce our results with a continuum theory for  $ka \ll 1$



$$\sin(ka/2)$$

- Expanding  $\hat{\phantom{a}}$  for  $ka \ll 1$  we have:

$$\omega = \pm 2\omega_0 \left( \frac{ka}{2} - \frac{1}{3!} \left( \frac{ka}{2} \right)^3 + \dots \right)$$

$$= \pm v_0 k \left( 1 - (ka)^2/24 + \dots \right)$$

where we have defined the velocity  $\omega_0 a$

$$v_0 = \omega_0 a = a \sqrt{\frac{\gamma}{m}}$$

- The correction,  $(ka)^2/24$ , leads to dispersion and will change the velocity of the wave as  $k$  becomes comparable to the spacing  $a$ , as we will see later
- First let's reproduce these results with continuum mechanics

## Transition to the continuum

- Returning to the lagrangian we introduce a field  $q(t, x)$

$q_j \longrightarrow q(t, x)$  continuous variable:  
displacement at  $x$  at  $t$ .

$$\sum \frac{m}{2} \dot{q}_j^2 \longrightarrow \int dx \mu (\partial_t q)^2$$

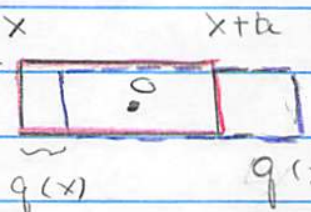
↑ mass per length =  $m/a$

- The potential term is

$$\sum \frac{1}{2} a (ka) \left( \frac{q_{j+1} - q_j}{a} \right)^2 \longrightarrow \int dx Y \left( \frac{\partial q}{\partial x} \right)^2$$

Young modulus  
 $\equiv ka$

net force on 0:



elongation per length

$$F_0 = Y \left\{ \frac{q(x+a) - q(x)}{a} \right\}$$

$$= Y \left( \frac{q(x+a) - q(x)}{a} \right)$$

So the Lagrangian and action:

Lagrangian and action of Rod:

$$L = \int dx \left[ \frac{1}{2} \mu (\partial_t q)^2 - \frac{1}{2} Y (\partial_x q)^2 \right]$$

$$S = \int dt dx \left[ \frac{1}{2} \mu (\partial_t q)^2 - \frac{1}{2} Y (\partial_x q)^2 \right]$$

Lagrangian density

# The Lagrange Equations

- Now lets determine the equation of motion

$$S[q] = \int dt dx \mathcal{L}(\partial_t q, \partial_x q, q)$$

↑ Lagrange density

- Lets get a notation:

So

$$y^a = (y^1, y^2) = (t, x)$$

$$\partial_a q = (\partial_t q, \partial_x q)$$

$$dt dx = d^2 y$$

$$\mathcal{L}(\partial_a q, q)$$

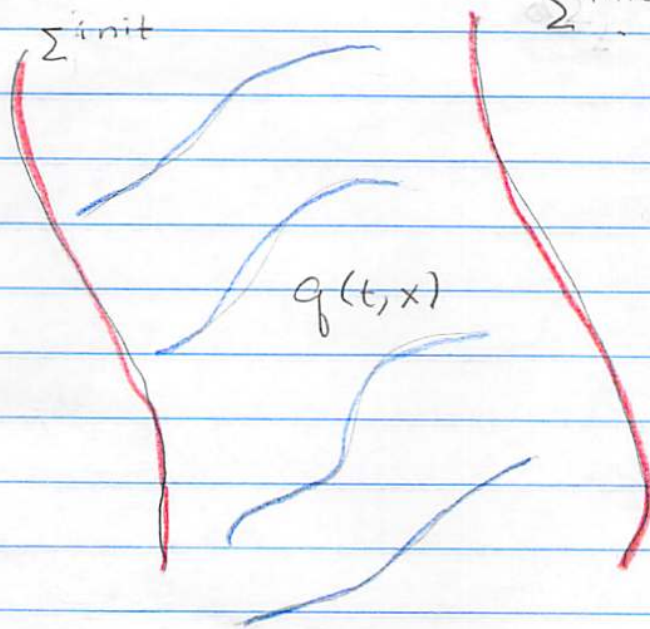
$$P^a = \frac{\partial \mathcal{L}}{\partial(\partial_a q)} = \text{canonical momentum}$$

$$\equiv (P^0, P^1)$$

- The variational problem takes place between two space time surfaces

$$\Sigma_1 = \Sigma^{\text{init}}$$

$$\Sigma^{\text{final}} = \Sigma_2$$



$\Sigma_1, \Sigma_2$  are analogous to the endpoints  $t_1, t_2$

Varying the action  $S[q+\delta q] - S[q] \equiv \delta S$

$$\delta S = \int d^2y \left( \frac{\partial \mathcal{L}}{\partial(\partial_a q)} \partial_a(\delta q) + \frac{\partial \mathcal{L}}{\partial q} \delta q \right)$$

So we integrate by parts:

$$\delta S = \int d^2y \left( \partial_a \left( \frac{\partial \mathcal{L}}{\partial(\partial_a q)} \delta q \right) - \partial_a \left( \frac{\partial \mathcal{L}}{\partial(\partial_a q)} \right) \delta q \right)$$

↑ divergence

$$\text{of a vector: } \partial_a P^a = \vec{\nabla} \cdot \vec{V}$$

So using the divergence theorem:

$$\delta S = \int_{\Sigma_2} d\Sigma_{2a} P^a \delta q - \int_{\Sigma_1} d\Sigma_{1a} P^a \delta q + \int d^2y \left( -\partial_a \left( \frac{\partial \mathcal{L}}{\partial(\partial_a q)} \right) + \frac{\partial \mathcal{L}}{\partial q} \right) \delta q$$

← bndry terms →

$$+ \int d^2y \left( -\partial_a \left( \frac{\partial \mathcal{L}}{\partial(\partial_a q)} \right) + \frac{\partial \mathcal{L}}{\partial q} \right) \delta q$$

So the continuum Lagrange eom read

$$\boxed{-\partial_a \left( \frac{\partial \mathcal{L}}{\partial(\partial_a q)} \right) + \frac{\partial \mathcal{L}}{\partial q} = 0}$$

← Euler Lagrange equations for a field

Compare

$$-\frac{d}{dt} \frac{\partial L}{\partial \dot{q}} + \frac{\partial L}{\partial q} = 0$$

- For the current case:

$$\mathcal{L} = \frac{1}{2} \mu (\partial_t q)^2 - \frac{1}{2} Y (\partial_x q)^2 \quad \leftarrow \text{Lagrange density}$$

- The EOM read:

$$-\partial_t \left( \frac{\partial \mathcal{L}}{\partial (\partial_t q)} \right) - \partial_x \frac{\partial \mathcal{L}}{\partial (\partial_x q)} = 0$$

$$-\partial_t (\mu \partial_t q) + \partial_x (Y \partial_x q) = 0$$

- Leading to a wave equation for  $q$

$$\mu \partial_t^2 q - Y \partial_x^2 q = 0$$

If we substitute  $q = a e^{ikx} e^{-i\omega(k)t}$  we find

$$-\mu \omega^2 + Y k^2 = 0$$

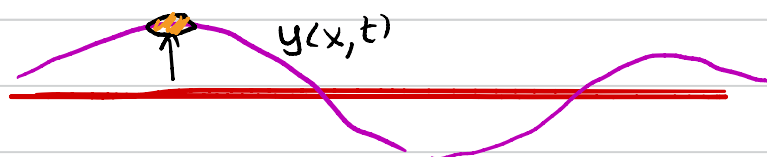
$$\omega(k) = \pm \sqrt{\frac{Y}{\mu}} k$$

$$\omega(k) = \pm v_0 k$$



## Another Example: The string

- Consider the string with tension  $T$



- The Kinetic Energy is  $\mu \equiv \text{mass/length}$

$$KE = \int dx \frac{1}{2} \mu (\partial_t y)^2$$

- The potential energy arises due to the stretching. We are increasing the length from  $l_1 = \Delta x$  to  $l_2 = \sqrt{(\Delta x)^2 + (\Delta y)^2}$ . This takes work which is

$$\Delta W = \int_{l_1}^{l_2} T dl = T \left[ \sqrt{\Delta x^2 + (\Delta y)^2} - \Delta x \right]$$

$$\approx \frac{T}{2} \left( \frac{\partial y}{\partial x} \right)^2 \Delta x$$

expand  
for small  
 $\Delta y / \Delta x \ll 1$

- So

$$S = \int dt dx \left[ \frac{1}{2} \mu (\partial_t y)^2 - \frac{T}{2} (\partial_x y)^2 \right]$$

- Thus we can find the EOM by varying the action, e.g.

$$(\partial_t y)^2 \rightarrow (\partial_t y + \partial_t \delta y)^2 \simeq (\partial_t y)^2 + 2 \partial_t y \partial_t \delta y$$

So

$$\delta S = \int dt dx \left[ \mu \partial_t y \partial_t \delta y - T \partial_x y \partial_x \delta y \right]$$

↑ integrate by parts ↑

And

$$\delta S = \int dt dx \left[ \underline{\underline{-\partial_t(\mu \partial_t y) + \partial_x(T \partial_x y)}} \right] \delta y = 0$$

Setting            to zero gives the EOM.