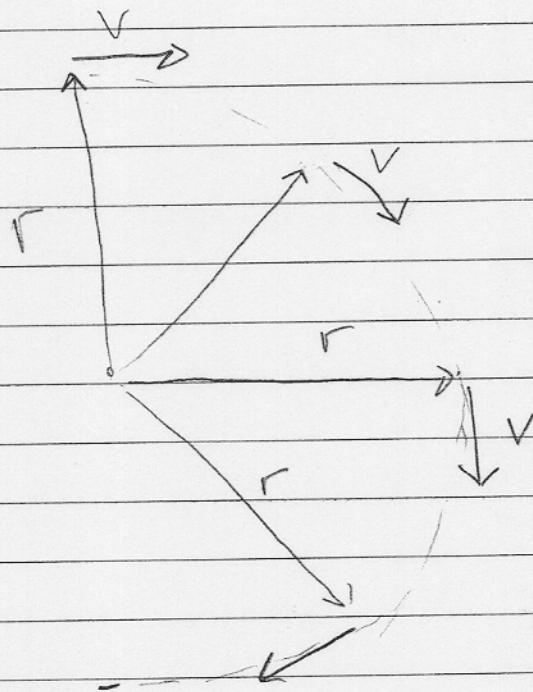


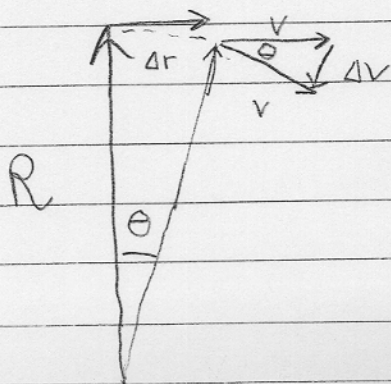
Uniform Circular motion (constant velocity)

- Speed, $|\vec{v}| = \sqrt{v_x^2 + v_y^2}$, is constant
- The radius $|\vec{R}| = R$ is constant
- but \vec{v} , and \vec{R} are changing directions all the time



$$\vec{a} = \frac{d\vec{v}}{dt} \neq 0$$

Physical Analysis



$$\frac{\Delta v}{v} = \frac{\Delta r}{R}$$

$$\Delta v = \frac{v}{R} \Delta r$$

$$a = \frac{\Delta v}{\Delta t} = \frac{v}{R} \frac{\Delta r}{\Delta t} = \left| \frac{v^2}{R} = a \right|$$

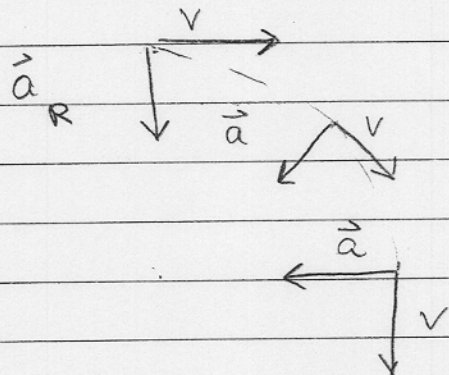
The magnitude of accel.

The direction of the ^{radial} acceleration is in

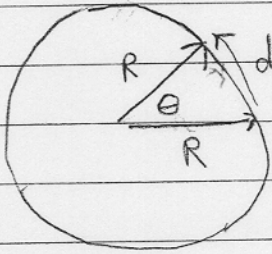
$$\vec{a}_R = \frac{v^2}{r} \times (\text{unit vector pointing toward center of circle})$$

$$\vec{a}_R = \frac{v^2}{r} \cdot (-\hat{R})$$

Picture



Mathematical Derivation:



The ball is going around in a circle at a constant rate

$$V = \frac{2\pi r}{T}$$

T = time to make one revolution
period

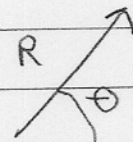
f = frequency = $\frac{1}{T}$ = # of revs per sec

$$\theta = \frac{d}{R} = \frac{V \cdot t}{R} = \frac{2\pi R \cdot t}{RT}$$

$$\theta = \frac{2\pi t}{T} \quad \text{note: for } t = T \quad \theta = 2\pi \checkmark$$

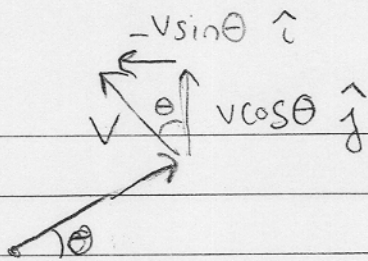
So

$$\vec{R} = R \cos \theta \hat{i} + R \sin \theta \hat{j}$$



$$\vec{R} = R \cos \frac{2\pi t}{T} \hat{i} + R \sin \frac{2\pi t}{T} \hat{j}$$

$$\frac{d\vec{R}}{dt} = -R \sin \frac{2\pi t}{T} \cdot \frac{2\pi}{T} \hat{i} + R \cos \frac{2\pi t}{T} \cdot \frac{2\pi}{T} \hat{j}$$
$$= -\frac{2\pi R}{T} \sin \theta \hat{i} + \frac{2\pi R}{T} \cos \theta \hat{j}$$



$$\vec{v} = \frac{d\vec{r}}{dt} = -v \sin \theta \hat{i} + v \cos \theta \hat{j}$$

$$|\vec{v}| = (v^2 \sin^2 \theta + v^2 \cos^2 \theta)^{1/2} = v \quad \checkmark$$

Now

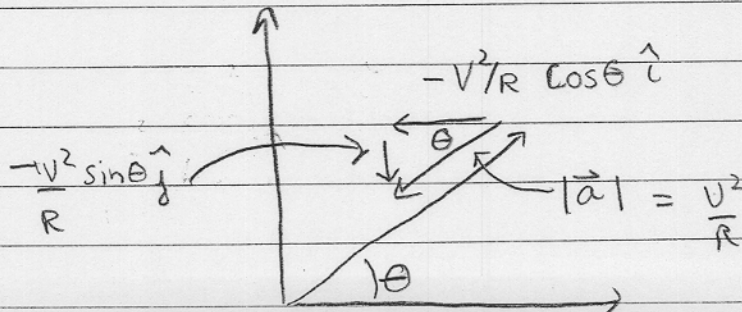
$$\vec{v} = v \left(-\sin \frac{2\pi t}{T} \right) \hat{i} + v \left(\cos \frac{2\pi t}{T} \right) \hat{j}$$

$$\vec{a} = \frac{d\vec{v}}{dt} = v \left(-\cos \frac{2\pi t}{T} \right) \cdot \frac{2\pi}{T} \hat{i} + \frac{v}{R} \left(-\sin \frac{2\pi t}{T} \right) \cdot \frac{2\pi}{T} \hat{j}$$

Multiply & Divide By R

$$\vec{a} = -\frac{v}{R} \underbrace{\frac{2\pi R}{T}}_v \left(\cos \theta \hat{i} + \sin \theta \hat{j} \right)$$

$$\vec{a} = -\frac{v^2}{R} \left(\cos \theta \hat{i} + \sin \theta \hat{j} \right)$$

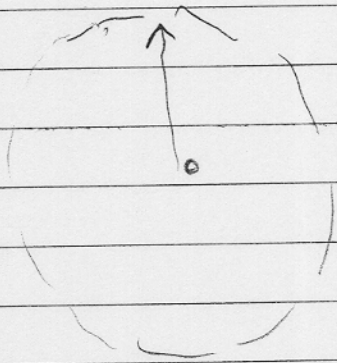


Newton's Laws and Circular Motion

- Whenever there is acceleration there must be force
- In the absence of forces objects move in a straight line (demonstrate)

Prob

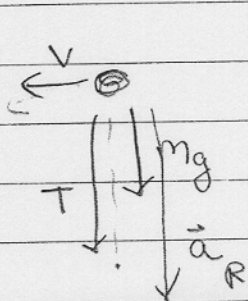
A ball is connected to a string and whirled in a vert. circ. Estimate the tension in the rope at the top



Solution:

$$v \sim \frac{2\pi R}{T} \sim \frac{2\pi \cdot 1/4 \text{ m}}{0.33 \text{ s}} \sim 5 \text{ m/s} \quad m \sim 20 \text{ g}$$

Analyze Newton's laws at top



$$-T - mg = -m \frac{v^2}{R}$$

$$T = \frac{mv^2}{R} - mg \sim 18.4 \text{ N}$$

As the velocity becomes less and less, the tension becomes less and less

The minimum velocity before the ball falls can be found by setting $T=0$

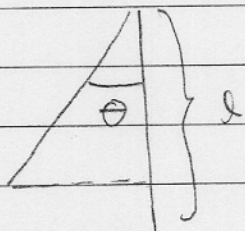
$$0 = mg - \frac{mv_{\min}^2}{R}$$

$$v_{\min} = \sqrt{gR}$$

$$v_{\min} = (9.8 \text{ m/s}^2 \cdot 0.25 \text{ m})^{1/2} \approx 1.5 \text{ m/s}$$

Problem

A ball is circulating in a conical pendulum



Determine the frequency ^{of rotation} ω as a function of l and θ

based on class

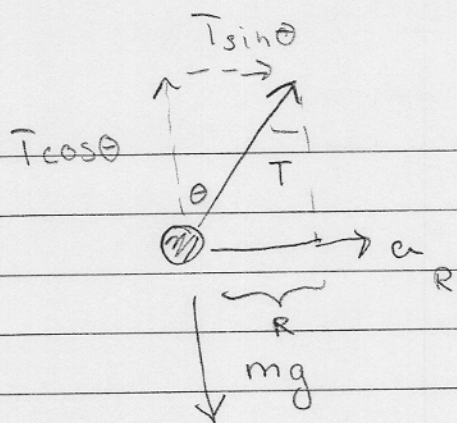
Observations: \rightarrow larger the angle the larger the frequency
 \rightarrow smaller l faster frequency

Solution ① Draw a free body diagram ② all possible forces in all possible directions

② analyze constraints

③ work enthusiastically

① x



x $T \sin \theta = m a_R = m \frac{v^2}{R}$

y $+T \cos \theta - mg = m a_y$

② We have analyzed constraints a_y , $a_R = \frac{v^2}{R}$

③ Work

$$T = \frac{mg}{\cos \theta} \Rightarrow \frac{mg \sin \theta}{\cos \theta} = \frac{mv^2}{R}$$

$$g \frac{\sin \theta}{\cos \theta} = \frac{v^2}{l \sin \theta}$$

$$\sqrt{\frac{gl}{\cos \theta}} \sin \theta = v$$

Now $f = \frac{1}{T} = \frac{1}{\frac{2\pi R}{v}} = \frac{v}{2\pi R} = \frac{\sqrt{\frac{gl}{\cos \theta}} \sin \theta}{2\pi l \sin \theta}$

$$f \approx \sqrt{\frac{g}{l \cos \theta}}$$

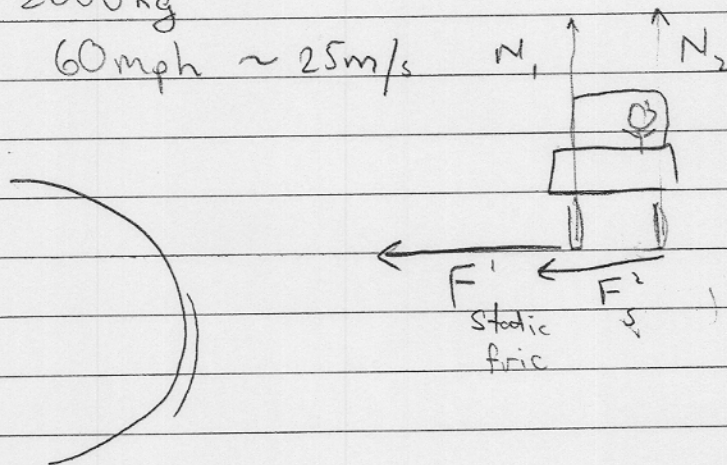
→ Note; ① when l smaller higher freq.
② when θ larger, $\cos \theta$ smaller,
and frequency higher

Banked Roads and highways.

- You wish to divert I95 by 90° , estimate the minimum Radius of curvature needed to accomplish this

Sol: $m_{\text{car}} \sim 2000 \text{ kg}$

$U_{\text{car}} \sim 60 \text{ mph} \sim 25 \text{ m/s}$



Typical $\mu_s \sim 0.4$

Normal force from each tire

Four tires $F_s^{\text{max}} = m \frac{U^2}{R}$

$4 \cdot \mu_s N = m \frac{U^2}{R}$

$4N - mg = m a_y$

$N = mg/4$

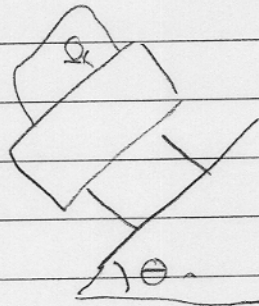
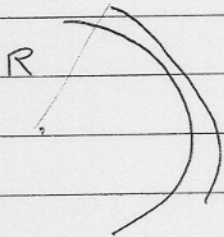
$4 \mu_s \frac{mg}{4} = m \frac{U^2}{R}$

$R = \frac{U^2}{g \mu_s} \approx 159 \text{ m}$

A typical exit ramp:

- ① Estimate the recommended speed $\sim 30 \text{ mph} \sim 13 \text{ m/s}$
② Estimate the typical radius of curvature ~ 30 .

Now typically the road
is banked

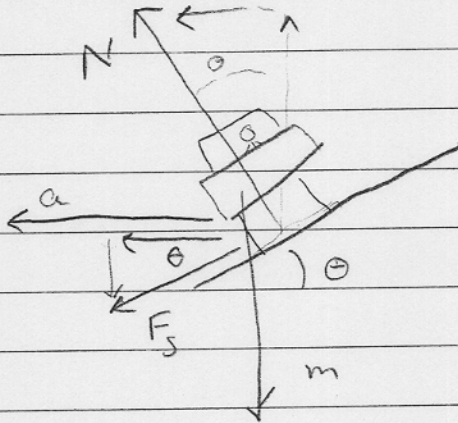


- Estimate the minimum μ_s which will hold the car on the road in the absence of banking.

$$\mu_s^0 = \frac{v^2}{gR} \approx 0.58 = \frac{(13 \text{ m/s})^2}{(9.8 \text{ m/s}^2)(30 \text{ m})}$$

- Determine the μ_s which will hold the car on the road for a banking angle of 15°

Now if the road is banked



(1) x

$$-N \sin \theta - \mu_s N \cos \theta = -m \frac{v^2}{R}$$

(2) y

$$N \cos \theta - mg - \mu_s N \sin \theta = m a_y$$

(2) Constraints $a_y = 0$ $a_x = v^2/R$

(3) Count:

Unknowns: N, μ_s ✓

Equations: 2

Work

$$N (\cos \theta - \mu_s \sin \theta) = mg$$

$$N = mg / (\cos \theta - \mu_s \sin \theta)$$

$$N (\sin\theta + \mu_s \cos\theta) = \frac{m v^2}{R}$$

$$\cancel{m} g \frac{(\sin\theta + \mu_s \cos\theta)}{(\cos\theta - \mu_s \sin\theta)} = \cancel{m} \frac{v^2}{R}$$

$$\frac{\sin\theta + \mu_s \cos\theta}{\cos\theta - \mu_s \sin\theta} = \frac{v^2}{Rg}$$

$$s + \mu_s c = \frac{v^2}{Rg} (c - \mu_s s)$$

Note

$$\begin{cases} c \equiv \cos\theta \\ s \equiv \sin\theta \end{cases}$$

$$-s + \frac{v^2}{Rg} c = + \mu_s c + \mu_s s \frac{v^2}{Rg}$$

$$\frac{v^2}{Rg} c - s = \mu_s$$

$$c + s \frac{v^2}{Rg}$$

$$\mu_s = \frac{\frac{v^2}{Rg} \tan\theta}{1 + \frac{v^2}{Rg} \tan\theta} = \mu_s$$

$$v = 13 \text{ m/s} \quad \sim 30 \text{ mph}$$

$$\theta \approx 15^\circ$$

$$R = 30 \text{ m}$$

$$0.27 \approx \mu_s$$

↑
wet conditions

$$\frac{v^2}{gR} = 0.58$$