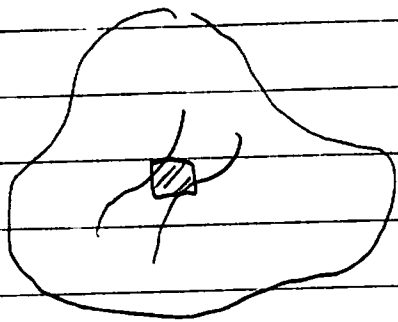


# Energy Conservation for Linear Matter;



The energy density

•  $u_{\text{mech}}$  = mechanical energy/vol  
(compression, thermal)

•  $u_{\text{em}}$  = The electric and magnetic energy/vol

•  $u_{\text{TOT}} = \text{total} = u_{\text{mech}} + u_{\text{em}}$

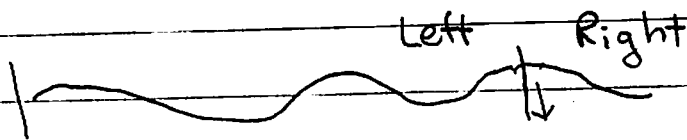
• For the total energy flux Expect:  $\frac{1}{2} \vec{E} \cdot \vec{D} + \frac{1}{2} \vec{B} \cdot \vec{H}$

$$\partial_t u_{\text{TOT}} + \partial_i S_{\text{TOT}}^i = 0$$

In this way an isolated system will conserve energy.

• The energy flux  $\vec{S}_{\text{TOT}}$  has mechanical pieces,  $\vec{S}_{\text{mech}}$ , and electromagnetic flux

Ex: stretched string



$$u_{\text{mech}} = \frac{1}{2} T \left( \frac{\partial y}{\partial x} \right)^2 + \frac{1}{2} \rho \left( \frac{\partial y}{\partial t} \right)^2$$

$$\vec{S} = T_0 \frac{\partial y}{\partial x} \frac{\partial y}{\partial t} = \underbrace{\text{Force}} \cdot \underbrace{\text{velocity}}$$

$\vec{S}_{\text{mech}}$  records how energy is mechanically transported from one region to another

We will show:

$$\partial_t (u_{\text{mech}} + u_{\text{em}}) + \partial_i (S_{\text{mech}}^i + S_{\text{em}}^i) = 0$$

Where  $u_{\text{em}} = \frac{1}{2} \vec{E} \cdot \vec{D} + \frac{1}{2} \vec{B} \cdot \vec{H}$

and  $\vec{S}_{\text{em}} = c (\vec{E} \times \vec{H})$

↑ energy flux in electromagnetism

In integral form:

$$\frac{d(u_{\text{mech}} + u_{\text{em}})}{dt} = - \int \vec{S}_{\text{em}} \cdot d\vec{a} - \int \vec{S}_{\text{mech}} \cdot d\vec{a}$$

0 for a mechanically isolated system

Then

$$[S] = \frac{\text{energy}}{\text{vol}} \cdot \frac{\text{m}}{\text{s}} = \frac{\text{energy}}{\text{area s}}$$

Prf - Imagine a charged string

$$\partial_t u_{\text{mech}} + \partial_i S^i_{\text{mech}} = \vec{j} \cdot \vec{E}$$

Now

$$\vec{j} \cdot \vec{E} = c (\nabla \times \vec{H} - \frac{1}{c} \partial_t \vec{D}) \cdot \vec{E}$$

$$= c (\nabla \times \vec{H}) \cdot \vec{E} - E \partial_t \vec{D}$$

$$= \nabla \cdot (c \vec{H} \times \vec{E}) + \vec{H} \cdot c \nabla \times \vec{E}$$

equivalent

$$= -\nabla \cdot \vec{S}_{\text{em}} - (E \partial_t D + H \partial_t B)$$

$$= -\nabla \cdot \vec{S}_{\text{em}} - \partial_t u_{\text{em}}$$

And so

$$\partial_t (u_{\text{mech}}) + \partial_i S^i = -\partial_t u_{\text{em}} - \partial_i S^i_{\text{em}}$$

$$u_{\text{em}} = \frac{1}{2} \vec{E} \cdot \vec{D} + \frac{1}{2} \vec{B} \cdot \vec{H}$$

$$\vec{S}_{\text{em}} = c \vec{E} \times \vec{H}$$

# Momentum Conservation

$$\partial_t g_{\text{Tot}}^j + \partial_i T_{\text{Tot}}^{ij} = 0$$

- $g_{\text{Tot}}$  is the total momentum per volume
- $T_{\text{Tot}}^{ij}$  is the force in the  $i$ th direction per area in  $j$ -th
- This guarantees that the total momentum is conserved

$$\frac{dP_{\text{Tot}}^j}{dt} = \int dV \partial_t g_{\text{Tot}}^j = \int dV [-\partial_i T_{\text{Tot}}^{ij}]$$

$$= - \int_{\partial V} T_{ij} n_j dS = 0$$



for an isolated system

Will show that

$$\begin{aligned} \partial_t g_{\text{mech}}^j + \partial_i T_{\text{mech}}^{ij} &= \rho \vec{E} + \vec{j} \times \vec{B} \\ &= -\partial_t (\vec{g}_{\text{em}}^j) - \partial_i T_{\text{em}}^{ij} \end{aligned}$$

↑ Same

Where

$$\vec{g}_{\text{em}} = \frac{\epsilon_0 \mu_0}{c^2} \vec{S}_{\text{em}}$$

$$T_{\text{em}}^{ij} = \underbrace{-\epsilon_0 E^i E^j + \frac{1}{2} \epsilon_0 E^2 \delta_{ij}}_{\text{electric stress}}$$

$$+ \underbrace{-\frac{B^i B^j}{\mu} + \frac{1}{2} \frac{B^2}{\mu} \delta_{ij}}_{\text{magnetic stress}}$$

So that the full result:

$$\partial_t (\vec{g}_{\text{mech}} + \vec{g}_{\text{em}}) + \partial_i (T_{\text{mech}}^{i\alpha} + T_{\text{em}}^{i\alpha}) = 0$$

Prf

$$\partial_t \vec{g}_{\text{mech}}^j + \frac{\partial T_{\text{mech}}^{ij}}{\partial x^i} = f_{\text{em}}^j$$

Now write

$$f_{\text{em}}^j = \rho E^j + \left( \frac{\vec{v}}{c} \times \vec{B} \right)^j$$

Then use  $\nabla \cdot \vec{D} = \rho$   $\frac{\vec{v}}{c} = \nabla \times \vec{H} - \frac{1}{c} \partial_t \vec{D}$

Find

$$f_{\text{em}}^j = \underbrace{(\nabla \cdot \vec{D}) E^j}_{(1)} + \underbrace{[(\nabla \times \vec{H}) \times \vec{B}]^j}_{(2)} - \underbrace{\frac{1}{c} (\partial_t \vec{D} \times \vec{B})^j}_{(3)}$$

The rest is labor which I will not go through  
(see Jackson)

$$(1) \Rightarrow -\partial_i T_{E}^{ij} \quad \text{with} \quad T_{E}^{ij} = -\epsilon E^i E^j + \frac{1}{2} \epsilon E^2 \delta^{ij}$$

$$(2) \Rightarrow -\partial_i T_{B}^{ij} \quad \text{with} \quad T_{B}^{ij} = -\frac{1}{\mu} B^i B^j + \frac{1}{2} \frac{B^2}{\mu} \delta^{ij}$$

$$(3) \Rightarrow -\partial_t \vec{g}_{em} \quad \text{with} \quad \vec{g}_{em} = \vec{D} \times \vec{B} = \frac{\epsilon \mu}{c^2} \vec{S}$$

(plus a term from (1))

The result is:

$$\rho \vec{E}^j + \vec{J}/c \times \vec{B} = -\partial_t \vec{g}_{em} - \partial_i T_{em}^{ij}$$

$$\partial_t (g_{mech}^j + g_{em}^j) + \partial_i (T_{mech}^{ij} + T_{em}^{ij}) = 0$$

$$\partial_t g_{mech}^j + \partial_i T_{mech}^{ij} = \rho E^j + \left( \frac{\vec{J} \times \vec{B}}{c} \right)^j$$

same thing

Or in terms of integrals:

$$\frac{d(P_{mech}^j + P_{em}^j)}{dt} = - \int da n_i T_{em}^{ij} - \int da n_i T_{mech}^{ij}$$

Total momentum

0 for a mechanically isolated system

$$\vec{P} = \int dV \vec{g}$$

## Angular Momentum Conservation

$$\partial_t g^k + \partial_l T^{lk} = 0 \quad \Leftarrow \text{momentum conservation}$$

And take  $T^{lk} = T^{kl}$  symmetric

$$\partial_t ((\vec{r} \times \vec{g})_i) + \epsilon_{ijk} r^j \partial_l T^{lk} = 0$$

ang  
momentum

$$\frac{\partial r^j}{\partial r^l}$$

Now  $\epsilon_{ijk} r^j \partial_l T^{lk} = \epsilon_{ijk} \left[ \partial_l (r^j T^{lk}) - \underbrace{\delta_l^j}_{=T^{jk}} T^{lk} \right]$

So since  $\epsilon_{ijk} T^{jk} = 0$ , we have

$$\partial_t ((\vec{r} \times \vec{g})_i) + \partial_l (\epsilon_{ijk} r^j T^{lk}) = 0$$

So the angular momentum of the system is conserved, provided the stress tensor is symmetric

$$\vec{L}_{\text{field}} = \int_V \vec{r} \times \vec{g}_{\text{em}}$$

$$\frac{d}{dt} (\vec{L}_{\text{mech}} + \vec{L}_{\text{field}})_i = - \int_{\partial V} dS \epsilon_{ijk} r^j T^{kl} n_l$$

net torque  
exerted on system