## 4 Electric Fields in Matter

### 4.1 Parity and Time Reversal

(a) We discussed how fields transform under parity and time reversal. A useful table is

| Quantity | Parity | Time Reversal |
| :--- | :---: | :---: |
| $t$ | Even | Odd |
| $\boldsymbol{r}$ | Odd | Even |
| $\boldsymbol{p}$ | Odd | Odd |
| $\boldsymbol{F}=$ force | Odd | Even |
| Ł $=\boldsymbol{r} \times \boldsymbol{p}$ | Even | Odd |
| $Q=$ charge | Even | Even |
| $\boldsymbol{j}$ | Odd | Odd |
| $\boldsymbol{E}$ | Odd | Even |
| $\boldsymbol{B}$ | Even | Odd |
| $\boldsymbol{A}$ vector potential | Odd | Odd |

### 4.2 Electrostatics in Material

## Basic setup

(a) In material we expand the medium currents $\boldsymbol{j}_{\text {mat }}$ in terms of a constitutive relation, fixing the currents in terms of the applied fields.

$$
\begin{equation*}
\boldsymbol{j}_{\mathrm{m} a t}=[\text { all possible combinations of the fields and their derivatives }] \tag{4.1}
\end{equation*}
$$

We have added a subscript mat to indicate that the current is a medium current. There is also an external current $\boldsymbol{j}_{\text {ext }}$ and charge density $\rho_{\text {ext }}$.
(b) When only uniform electric fields are applied, and the electric field is weak, and the medium is isotropic, the polarization current takes the form

$$
\begin{equation*}
\boldsymbol{j}_{\mathrm{m} a t}=\sigma \boldsymbol{E}+\chi \partial_{t} \boldsymbol{E}+\ldots \tag{4.2}
\end{equation*}
$$

where the ellipses denote higher time derivatives of electric fields, which are suppressed by powers of $t_{\text {micro }} / T_{\text {macro }}$ by dimensional analysis. For a conductor $\sigma$ is non-zero. For a dielectric insulator $\sigma$ is zero, and then the current takes the form

$$
\begin{equation*}
\boldsymbol{j}_{b}=\partial_{t} \boldsymbol{P} \tag{4.3}
\end{equation*}
$$

- $\boldsymbol{P}$ is known as the polarization, and can be interpreted as the dipole moment per volume.
- We have worked with linear response for an isotropic medium where

$$
\begin{equation*}
\boldsymbol{P}=\chi \boldsymbol{E} \tag{4.4}
\end{equation*}
$$

This is most often what we will assume.
For an anisotropic medium, $\chi$ is replaced by a susceptibility tensor

$$
\begin{equation*}
\boldsymbol{P}_{i}=\chi_{i j} \boldsymbol{E}^{j} \tag{4.5}
\end{equation*}
$$

For a nonlinear (isotropic) medium $\boldsymbol{P}$ one could try a non-linear vector function of $\boldsymbol{E}$,

$$
\begin{equation*}
\boldsymbol{P}(\boldsymbol{E}) \tag{4.6}
\end{equation*}
$$

defined by the low-frequency expansion of the current at zero wavenumber.
(c) Current conservation $\partial_{t} \rho+\nabla \cdot \boldsymbol{j}=0$ determines then that

$$
\begin{equation*}
\rho_{\mathrm{m} a t}=-\nabla \cdot \boldsymbol{P} \tag{4.7}
\end{equation*}
$$

(d) The electrostatic maxwell equations read

$$
\begin{align*}
& \nabla \cdot \boldsymbol{E}=\underbrace{-\nabla \cdot \boldsymbol{P}}_{\rho_{\mathrm{mat}}}+\rho_{\mathrm{ext}}  \tag{4.8}\\
& \nabla \times \boldsymbol{E}=0 \tag{4.9}
\end{align*}
$$

or

$$
\begin{align*}
\nabla \cdot \boldsymbol{D} & =\rho_{\mathrm{e} x t}  \tag{4.10}\\
\nabla \times \boldsymbol{E} & =0 \tag{4.11}
\end{align*}
$$

where the electric displacement is

$$
\begin{equation*}
D \equiv E+P \tag{4.12}
\end{equation*}
$$

(e) For a linear isotropic medium

$$
\begin{equation*}
\boldsymbol{D}=(1+\chi) \boldsymbol{E} \equiv \varepsilon \boldsymbol{E} \tag{4.13}
\end{equation*}
$$

but in general $\boldsymbol{D}$ is a function of $\boldsymbol{E}$ which must be specified before problems can be solved.

## Working problems with Dielectrics

(a) Using Eq. (4.7) and the Eq. (4.10) we find the boundary conditions that normal components of $\boldsymbol{D}$ jump across a surface if there is external charge, while the parallel components $\boldsymbol{E}$ are continuous

$$
\begin{align*}
\boldsymbol{n} \cdot\left(\boldsymbol{D}_{2}-\boldsymbol{D}_{1}\right) & =\sigma_{\mathrm{e} x t} & D_{2 \perp}-D_{1 \perp} & =\sigma_{\mathrm{e} x t}  \tag{4.14}\\
\boldsymbol{n} \times\left(\boldsymbol{E}_{2}-\boldsymbol{E}_{1}\right) & =0 & E_{2 \|}-E_{1 \|} & =0
\end{align*}
$$

Very often $\sigma_{\text {ext }}$ will be absent and then $D_{\perp}$ will be continuous (but not $E_{\perp}$ ).
(b) A jump in the polarization induces bound surface charge at the jump.

$$
\begin{equation*}
-\boldsymbol{n} \cdot\left(\boldsymbol{P}_{2}-\boldsymbol{P}_{1}\right)=\sigma_{\mathrm{mat}} \tag{4.16}
\end{equation*}
$$

(c) Since the curl of $\boldsymbol{E}$ is zero we can always write

$$
\begin{equation*}
\boldsymbol{E}=-\nabla \varphi \tag{4.17}
\end{equation*}
$$

and for linear media $(\boldsymbol{D}(\boldsymbol{r})=\varepsilon(\boldsymbol{r}) \boldsymbol{E}(\boldsymbol{r}))$ with a non-constant dielectric constant $\varepsilon(\boldsymbol{r})$, we find an equation for $\boldsymbol{D}$

$$
\begin{equation*}
\nabla \cdot \varepsilon(\boldsymbol{r}) \nabla \varphi=0 \tag{4.18}
\end{equation*}
$$

(d) With the assumption of a linear medium $\boldsymbol{D}=\varepsilon \boldsymbol{E}$ and constant dielectric constant, the equations for electrostatics in medium are essentially identical to electrostatics without medium

$$
\begin{equation*}
-\varepsilon \nabla^{2} \Phi=\rho_{\mathrm{e} x t} \tag{4.19}
\end{equation*}
$$

but, the new boundary conditions lead to some (pretty minor) differences in the way the problems are solved.

## Energy and Stress in Dielectrics: Lecture 13.5

(a) We worked out the extra energy stored in a dielectric as an ensemble of external charges are placed into the dielectric. As the macroscopic electric field $\boldsymbol{E}$ and displacement $\boldsymbol{D}(\boldsymbol{E})$ are changed by adding external charge $\delta \rho_{\mathrm{e} x t}$, the change in energy stored in the capacitor material is

$$
\begin{equation*}
\delta U=\int_{V} \mathrm{~d}^{3} x \boldsymbol{E} \cdot \delta \boldsymbol{D} \tag{4.20}
\end{equation*}
$$

(b) For a linear dielectric $\delta U$ can be integrated, becoming

$$
\begin{equation*}
U=\frac{1}{2} \int_{V} \mathrm{~d}^{3} x \boldsymbol{E} \cdot \boldsymbol{D}=\frac{1}{2} \int_{V} \mathrm{~d}^{3} x \varepsilon \boldsymbol{E}^{2} \tag{4.21}
\end{equation*}
$$

(c) We worked out the stress tensor for a linear dielectric and found

$$
\begin{align*}
T_{E}^{i j} & =-\frac{1}{2}\left(D^{i} E^{j}+E^{i} D^{j}\right)+\frac{1}{2} \boldsymbol{D} \cdot \boldsymbol{E} \delta^{i j}  \tag{4.22}\\
& =\varepsilon\left(-E^{i} E^{j}+\frac{1}{2} \boldsymbol{E}^{2} \delta^{i j}\right) \tag{4.23}
\end{align*}
$$

where in the first line we have written the stress in a form that can generalize to the non-linear case, and in the second line we used the linearity to write it in a form which is proportional the vacuum stress tensor.
(d) As always the force per volume in the Dielectric is

$$
\begin{equation*}
f^{j}=-\partial_{i} T_{E}^{i j} \tag{4.24}
\end{equation*}
$$

where

$$
\begin{equation*}
T^{i j}=\text { the force in the } j \text {-th direction per area in the } i \text {-th } \tag{4.25}
\end{equation*}
$$

More precisely let $\boldsymbol{n}$ be the (outward directed) normal pointing from region LEFT to region RIGHT, then

$$
\begin{equation*}
n_{i} T^{i j}=\text { the } j \text {-th component of the force per area, by region } L E F T \text { on region } R I G H T . \tag{4.26}
\end{equation*}
$$

We can integrate the force/volume to find the net force on a given volume

$$
\begin{equation*}
F^{j}=\int_{V} d^{3} x f^{j}(\boldsymbol{x})=-\int_{\partial V} d a_{i} T^{i j} \tag{4.27}
\end{equation*}
$$

This can be used to work out the force at a dielectric interface as done in lecture.

