4 Electric Fields in Matter

4.1 Parity and Time Reversal

(a) We discussed how fields transform under parity and time reversal. A useful table is

Quantity	Parity	Time Reversal
t	Even	Odd
r	Odd	Even
\overline{p}	Odd	Odd
$\boldsymbol{F}=$ force	Odd	Even
$\mathbf{L} = \mathbf{r} \times \mathbf{p}$	Even	Odd
Q = charge	Even	Even
j	Odd	Odd
$oldsymbol{E}$	Odd	Even
B	Even	Odd
\boldsymbol{A} vector potential	Odd	Odd

4.2 Electrostatics in Material

Basic setup

(a) In material we expand the medium currents j_{mat} in terms of a constitutive relation, fixing the currents in terms of the applied fields.

$$j_{mat} = [$$
 all possible combinations of the fields and their derivatives $]$ (4.1)

We have added a subscript mat to indicate that the current is a medium current. There is also an external current j_{ext} and charge density ρ_{ext} .

(b) When only uniform electric fields are applied, and the electric field is weak, and the medium is isotropic, the polarization current takes the form

$$\mathbf{j}_{\mathrm mat} = \sigma \mathbf{E} + \chi \partial_t \mathbf{E} + \dots \tag{4.2}$$

where the ellipses denote higher time derivatives of electric fields, which are suppressed by powers of t_{micro}/T_{macro} by dimensional analysis. For a conductor σ is non-zero. For a dielectric insulator σ is zero, and then the current takes the form

$$\mathbf{j}_b = \partial_t \mathbf{P} \tag{4.3}$$

 \bullet P is known as the polarization, and can be interpreted as the dipole moment per volume.

• We have worked with linear response for an isotropic medium where

$$\boldsymbol{P} = \chi \boldsymbol{E} \tag{4.4}$$

This is most often what we will assume.

For an anisotropic medium, χ is replaced by a susceptibility tensor

$$\mathbf{P}_i = \chi_{ij} \mathbf{E}^j \tag{4.5}$$

For a nonlinear (isotropic) medium P one could try a non-linear vector function of E,

$$P(E) \tag{4.6}$$

defined by the low-frequency expansion of the current at zero wavenumber.

(c) Current conservation $\partial_t \rho + \nabla \cdot \mathbf{j} = 0$ determines then that

$$\rho_{\mathrm mat} = -\nabla \cdot \mathbf{P} \tag{4.7}$$

(d) The electrostatic maxwell equations read

$$\nabla \cdot \boldsymbol{E} = \underbrace{-\nabla \cdot \boldsymbol{P}}_{\rho_{\text{mat}}} + \rho_{\text{ext}} \tag{4.8}$$

$$\nabla \times \mathbf{E} = 0 \tag{4.9}$$

or

$$\nabla \cdot \boldsymbol{D} = \rho_{\text{ext}} \tag{4.10}$$

$$\nabla \times \mathbf{E} = 0 \tag{4.11}$$

where the *electric displacement* is

$$D \equiv E + P \tag{4.12}$$

(e) For a linear isotropic medium

$$\mathbf{D} = (1 + \chi)\mathbf{E} \equiv \varepsilon \mathbf{E} \tag{4.13}$$

but in general D is a function of E which must be specified before problems can be solved.

Working problems with Dielectrics

(a) Using Eq. (4.7) and the Eq. (4.10) we find the boundary conditions that normal components of D jump across a surface if there is external charge, while the parallel components E are continuous

$$\boldsymbol{n} \cdot (\boldsymbol{D}_2 - \boldsymbol{D}_1) = \sigma_{\text{ext}}$$
 $D_{2\perp} - D_{1\perp} = \sigma_{\text{ext}}$ (4.14)

$$\mathbf{n} \times (\mathbf{E}_2 - \mathbf{E}_1) = 0$$
 $E_{2\parallel} - E_{1\parallel} = 0$ (4.15)

Very often σ_{ext} will be absent and then D_{\perp} will be continuous (but not E_{\perp}).

(b) A jump in the polarization induces bound surface charge at the jump.

$$-\boldsymbol{n}\cdot(\boldsymbol{P}_2-\boldsymbol{P}_1)=\sigma_{\mathrm mat} \tag{4.16}$$

(c) Since the curl of \boldsymbol{E} is zero we can always write

$$\mathbf{E} = -\nabla \varphi \tag{4.17}$$

and for linear media $(D(r) = \varepsilon(r)E(r))$ with a non-constant dielectric constant $\varepsilon(r)$, we find an equation for D

$$\nabla \cdot \varepsilon(\mathbf{r}) \nabla \varphi = 0 \tag{4.18}$$

(d) With the assumption of a linear medium $D = \varepsilon E$ and constant dielectric constant, the equations for electrostatics in medium are essentially identical to electrostatics without medium

$$-\varepsilon \nabla^2 \Phi = \rho_{\text{ext}} \,, \tag{4.19}$$

but, the new boundary conditions lead to some (pretty minor) differences in the way the problems are solved.

Energy and Stress in Dielectrics: Lecture 13.5

(a) We worked out the extra energy stored in a dielectric as an ensemble of external charges are placed into the dielectric. As the macroscopic electric field E and displacement D(E) are changed by adding external charge $\delta \rho_{ext}$, the change in energy stored in the capacitor material is

$$\delta U = \int_{V} d^3 x \, \boldsymbol{E} \cdot \delta \boldsymbol{D} \tag{4.20}$$

(b) For a linear dielectric δU can be integrated, becoming

$$U = \frac{1}{2} \int_{V} d^{3}x \, \boldsymbol{E} \cdot \boldsymbol{D} = \frac{1}{2} \int_{V} d^{3}x \, \varepsilon \boldsymbol{E}^{2}$$

$$(4.21)$$

(c) We worked out the stress tensor for a linear dielectric and found

$$T_E^{ij} = -\frac{1}{2}(D^i E^j + E^i D^j) + \frac{1}{2} \mathbf{D} \cdot \mathbf{E} \delta^{ij}$$

$$\tag{4.22}$$

$$=\varepsilon \left(-E^{i}E^{j} + \frac{1}{2}\mathbf{E}^{2}\delta^{ij}\right) \tag{4.23}$$

where in the first line we have written the stress in a form that can generalize to the non-linear case, and in the second line we used the linearity to write it in a form which is proportional the vacuum stress tensor.

(d) As always the force per volume in the Dielectric is

$$f^j = -\partial_i T_E^{ij} \tag{4.24}$$

where

$$T^{ij}$$
 = the force in the *j*-th direction per area in the *i*-th (4.25)

More precisely let n be the (outward directed) normal pointing from region LEFT to region RIGHT, then

$$n_i T^{ij}$$
 = the j-th component of the force per area, by region LEFT on region RIGHT . (4.26)

We can integrate the force/volume to find the net force on a given volume

$$F^{j} = \int_{V} d^{3}x f^{j}(\boldsymbol{x}) = -\int_{\partial V} da_{i} T^{ij}$$

$$(4.27)$$

This can be used to work out the force at a dielectric interface as done in lecture.