

Boundary Conditions and The Inhomogeneous Equations

- The general solution to the inhomogeneous equation can be written

$$y(x) = \underbrace{c_1 y_1(x) + c_2 y_2(x)}_{\substack{\equiv y_{\text{homo}}(x) \\ \text{homogeneous sol}}} + y_p(x) \quad (12.3)$$

Where the particular solution

particular solution is one

solution to $\mathcal{L} y_p(x) = f(x)$ and $y_1(x)$

and $y_2(x)$ solve the homogeneous equation

$$\mathcal{L} y(x) = 0$$

inhomogeneous

- To prove this, suppose I have two [^]solutions to $\mathcal{L} y_p(x) = f(x)$, $y_{p1}(x)$ and $y_{p2}(x)$.

Their difference $\Delta y = y_{p1} - y_{p2}$ satisfies

$\mathcal{L} \Delta y = 0$ and thus can be written as

$$\Delta y = c_1 y_1 + c_2 y_2 \leftarrow \text{a general solution to } \mathcal{L} y = 0$$

- Further, if the boundary conditions are inhomogeneous (e.g. $v(t)|_{t=0} = v_0$) we can always let ^{the}homogeneous solution solve the inhomogeneous b.c.. Then the particular

solution satisfies the homogeneous b.c..

For example, if the b.c. are for the full system are:

$$\left. \begin{array}{l} \alpha_{11} y(a) + \alpha_{12} y'(a) = A \\ \alpha_{21} y(a) + \alpha_{22} y'(a) = B \end{array} \right\} \quad (13.1)$$

In homogeneous b.c

By making $y_{\text{homo}}(x)$ satisfy Eq (13.1) (by adjusting c_1 and c_2), then in order for the combination $y(x) = y_{\text{homo}}(x) + y_p(x)$ to satisfy Eq (13.1) we:

must demand that the particular solution satisfy

$$\left. \begin{array}{l} \alpha_{11} y_p(a) + \alpha_{12} y'_p(a) = 0 \\ \alpha_{21} y_p(a) + \alpha_{22} y'_p(a) = 0 \end{array} \right\} \quad \text{The homogeneous version of Eq (13.1)}$$

This is almost always the best way to proceed.

Green Functions

- We may formally solve the problem of finding a particular solution, by finding a function $G(x, x_0)$ which satisfies

$$\mathcal{L} G(x, x_0) = \delta(x - x_0)$$

i.e.

$$\left[\frac{d^2}{dx^2} + P(x) \frac{d}{dx} + Q(x) \right] G(x, x_0) = \delta(x - x_0)$$

or

$$\left[-\frac{d}{dx} p(x) \frac{d}{dx} + q(x) \right] G(x, x_0) = \delta(x - x_0)$$

- Typically we work in an interval $[a,..b]$ and demand (as discussed in the previous section) that G satisfies homogeneous b.c. at a, b

Then the particular solution is

$$y_p(x) = \int_a^b dx_0 G(x, x_0) f(x_0)$$

- Then we see that this satisfies the inhomogeneous eq $\mathcal{L} y_p = f$

$$\mathcal{L}_x y_p(x) = \int_a^b dx_0 \mathcal{L}_x G(x, x_0) f(x_0)$$

$$= \int_a^b dx_0 \delta(x - x_0) f(x_0) = f(x)$$

Constructing the Green Fcn

- Away from x_0 , $G(x, x_0)$ satisfies the homogeneous equation

$$\mathcal{L} G(x, x_0) = 0 \quad \text{for } x \neq x_0$$

- The Green function is found by solving

(15)

the homogeneous equation for $x > x_0$ and $x < x_0$
 and matching the solutions by integrating the
 equation across the δ -fcn.

Example: Consider a particle subject to drag
 and a force which acts for $t > 0$

$$(15.1) \quad \frac{dv}{dt} + \gamma v = f(t) \quad v(0) = V_0 \quad t \in [0, \infty]$$

↑
an inhomogeneous b.c.

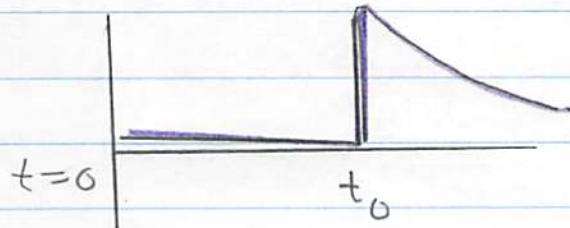
- We first set $f(t) = 0$ and solve for the homogeneous solution satisfying the inhomogeneous b.c.

$$(15.2) \quad v(t) = V_0 e^{-\gamma t}$$

- Then we solve the inhomogeneous equation with

$$(15.3) \quad \frac{dG}{dt} + \gamma G = \delta(t - t_0) \quad G \Big|_{t=0} = 0 \leftarrow \begin{matrix} \text{homogeneous} \\ \text{b.c.} \end{matrix}$$

First, qualitatively, this is a particle at rest, which gets an impulsive kick at t_0 :



we will show

$$G(t, t_0) = \Theta(t - t_0) e^{-\gamma(t - t_0)}$$

The particle gets a kick at $t = t_0$, its velocity then decays for $t > t_0$.

For $G(t, t_0)$ we

(15.5)

① Solve (15.1) for $t > t_0$, ② solve for $t < t_0$, and ③ match.

① The general homogeneous sol is $C_1 e^{-\gamma t}$ for $t > t_0$.

② The general homogeneous sol for $t < t_0$ is

$C_2 e^{-\gamma t}$. But we must set $C_2 = 0$ to

Satisfy the homogeneous b.c. $G(t) \Big|_{t=0} = 0$

③ We then match the two solutions.

Integrating the EOM from $t_0 - \varepsilon$ to $t_0 + \varepsilon$, and demanding that G remains bounded we find

$$\int_{t_0 - \varepsilon}^{t_0 + \varepsilon} dt \left[\frac{dG}{dt} + \gamma G \right] = \int_{t_0 - \varepsilon}^{t_0 + \varepsilon} \delta(t - t_0)$$

$$G \Big|_{t_0 + \varepsilon} - G \Big|_{t_0 - \varepsilon} + O(\varepsilon) = 1$$

this is small $\int_{t_0 - \varepsilon}^{t_0 + \varepsilon} G$ for bounded G

In the current case

$$G(t, t_0) \Big|_{t=t_0 - \varepsilon} = 0 \quad \text{and therefore}$$

$$G(t, t_0) \Big|_{t=t_0 + \varepsilon} = 1$$

(16)

From our known solution, $G(t_0 + \varepsilon) = Ce^{-\gamma t} \Big|_{t=t_0}$
 for $t > t_0$ we find

$$Ce^{-\gamma t_0} = 1 \Rightarrow C = e^{\gamma t_0} \quad \text{and}$$

thus

$$G(t) = e^{-\gamma(t-t_0)} \quad t > t_0$$

Or

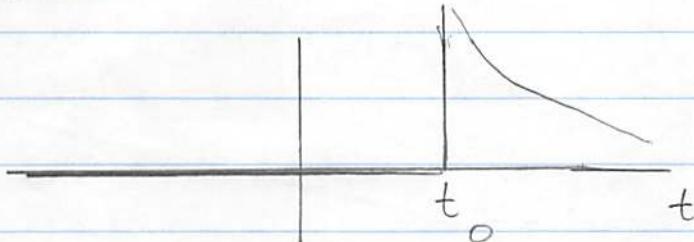
$$G(t, t_0) = \Theta(t - t_0) e^{-\gamma(t-t_0)}$$

unit
impulsive
↓ force

Picture:

$$\frac{dv}{dt} + \gamma v = \delta(t - t_0)$$

(16.1)



velocity jumps,
and then decays

It is easy to check that $\mathcal{L} G(t, t_0) = \delta(t - t_0)$.

The δ -fcn arises when we differentiate

$$\frac{d}{dt} \Theta(t - t_0) = \delta(t - t_0)$$

← origin of δ -fcn
in $\mathcal{L} G = \delta(t - t_0)$

The General Solution:

$$y(t) = y_{\text{homo}}(t) + \int_a^\infty G(t, t_0) f(t_0) dt_0$$

$$y(t) = Ce^{-\gamma t} + \int_a^t e^{-\gamma(t-t_0)} f(t_0) dt_0$$

Second Order DEQ and Green funcs

- The procedure to construct the green function is always the same as in the previous example
 - Solve the homogeneous equations to the left and right
 - integrate across the S-fcn to match the two sols

Let us follow this procedure for the equation

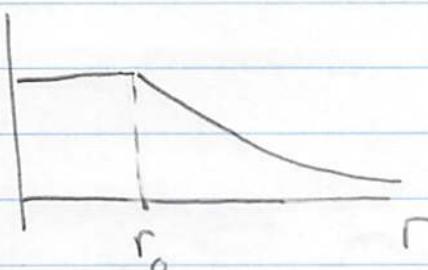
$$\left[-\frac{d}{dx} p(x) \frac{d}{dx} + q(x) \right] G(x,x_0) = \delta(x-x_0)$$

- For definiteness take a specific problem. The potential of a charged spherical shell



$$\Phi(r)$$

$$\Phi(r, r_0) = \begin{cases} \frac{Q}{4\pi r_0} & r < r_0 \\ \frac{Q}{4\pi r} & r > r_0 \end{cases}$$



This is the solution to

$$\nabla \cdot E = \rho$$

$$E = -\nabla \Phi$$

$$-\nabla^2 \Phi = \rho$$

Where $\rho(r) = \frac{Q}{4\pi r^2} \delta(r - r_0)$ r_0 and charge Q

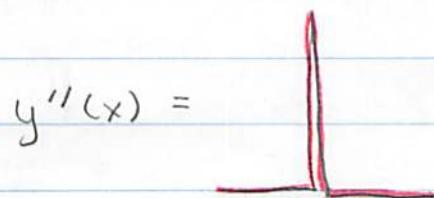
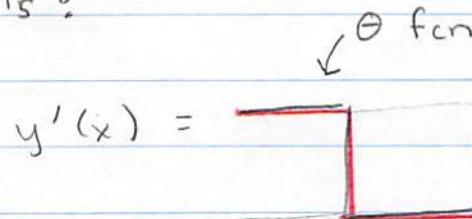
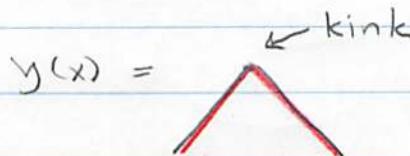
↖ Spherical shell of radius

$$-\nabla^2 \Phi = -\frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial \Phi}{\partial r} = \frac{Q}{4\pi r^2} \delta(r - r_0)$$

So we see that we are trying to find the Green function of

$$-\frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} G(r, r_0) = \delta(r - r_0) \quad \Phi = \frac{Q}{4\pi} G(r, r_0)$$

- Note we are looking for a solution that looks like this:



So the function is continuous, but has a discontinuous derivative. We can see this directly from the general EoM

Integrating from $x_0 - \varepsilon$ to $x_0 + \varepsilon$

$$-\int_{x_0 - \varepsilon}^{x_0 + \varepsilon} dx \left[-\frac{d}{dx} \left(p(x) \frac{dG}{dx} \right) + q(x) G \right] = \int_{x_0 - \varepsilon}^{x_0 + \varepsilon} \delta(x - x_0) G dx$$

Yielding

\downarrow electric field in our example

$$-\left. p(x) \frac{dG}{dx} \right|_{x=x_0 + \varepsilon} + \left. p(x) \frac{dG}{dx} \right|_{x=x_0 - \varepsilon} = 1 \quad (20.1)$$

Jump condition

For the simple case of a charged sphere this says that the jump in the electric field is due to the surface charge.

$$-\left. r^2 \frac{\partial G}{\partial r} \right|_{r=r_0 + \varepsilon} - \left. (-r^2 \frac{\partial G}{\partial r}) \right|_{r=r_0 - \varepsilon} = 1 \quad (20.2)$$

or since $G = \Phi / (Q/4\pi)$ and $E_r = -\partial \Phi / \partial r$

$$\left. 4\pi r^2 E_r \right|_{\text{out}} - \left. 4\pi r^2 E_r \right|_{\text{in}} = Q \quad (20.3)$$

- Now we have analyzed the "jump condition" which relates the interior and exterior solutions. We now should solve for these solutions

homogeneous

- Let the solution to the left ($x < x_0$) be $y_{<} (x)$ and the solution to the right be $y_{>} (x)$ (i.e. $x > x_0$). For our case we solve

$$-\frac{d}{dr} r^2 \frac{d}{dr} \bar{\Phi} = 0 \quad \left\{ \begin{array}{l} \text{b.c. regular as } r \rightarrow 0 \\ \text{and vanishes as } r \rightarrow \infty \end{array} \right.$$

There are two solutions 1 and $\frac{1}{r}$

$$y(r) = C_1 \cdot 1 + C_2 \cdot \frac{1}{r} \quad (\text{why?})$$

- Our solutions obey homogeneous b.c., so one of these constants can be chosen at will, since if y satisfies the DEQ and b.c., then so does $Cy(r)$. Here then, $y_{<} (r) = 1$ and $y_{>} (r) = \frac{1}{r}$

These follow from our b.c., that $G(r, r_0)$ be regular at $r \rightarrow 0$ and $r \rightarrow \infty$.

- The Green function then takes the form

$$G(x, x_0) = C_1 y_{<} (x) \Theta(x_0 - x) + C_2 y_{>} (x) \Theta(x - x_0)$$

Continuity gives at $r = r_0$ the condition:

$$(21.1) \quad G(x, x_0) = C [y_{<} (x) y_{>} (x_0) \Theta(x_0 - x)$$

$$+ y_{>} (x) y_{<} (x_0) \Theta(x - x_0)]$$

There is an interesting point here which we will return to later. When specifying the boundary conditions for the solutions of

$$\frac{-\partial}{\partial r} \left(r^2 \frac{\partial \Phi}{\partial r} \right)$$

The function $p(r) = r^2$ has zeros and singularities at $r = 0$ and $r = \infty$. These are known as singular points of the diffeq. The two solutions are

$$y_1(r) = 1 \quad y_2(r) = \frac{1}{r}$$

which are regular as $r \rightarrow 0$ and $r \rightarrow \infty$ respectively. Our boundary conditions are regularity at $r = 0$ and $r = \infty$. These boundary conditions are homogeneous. For instance if $y_1 = C_1/r$ and $y_2 = C_2/r$ are regular as $r \rightarrow \infty$ then any linear combination is also regular as $r \rightarrow \infty$

Now we can determine the remaining coefficient C from the jump condition Eq (20.1)

Substituting Eq (21.1) into Eq (20.1) gives
(Do it!!!)

$$-\left. p(x) C y'_>(x) y'_<(x_0) \right|_{x=x_0+\varepsilon} + \left. p(x) C y'_<(x) y'_>(x_0) \right|_{x=x_0-\varepsilon} = 1$$

Or

$$C = \frac{1}{p(x_0) [y'_>(x_0) y'_<(x_0) - y'_>(x_0) y'_<(x_0)]}$$

i.e.

$$C = \frac{1}{p(x_0) W(x_0)} \quad W(x_0) = y'_> y'_< - y'_< y'_>$$

↑
recall that
Wronskian of $y'_>, y'_<$

and

this is constant (Eq 6.1)

$$G(x, x_0) = \frac{y'_>(x) y'_<(x_0) \Theta(x-x_0) + y'_<(x) y'_>(x_0) \Theta(x_0-x)}{p(x_0) W(x_0)}$$

Eq (22.1)

the green fcn for a general
2nd order DEQ.

↑ the denom is
a constant indep of
 x_0

- For our particular example

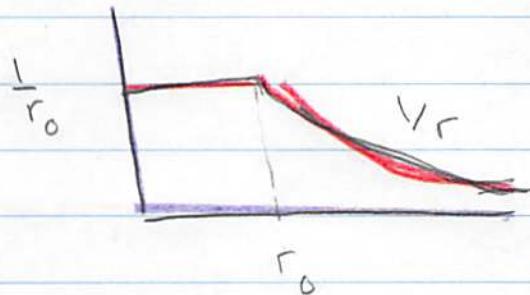
$$y_> = 1/r \quad y_< = 1 \quad p(r) = r^2$$

$$W(r) = \cancel{y_>}^{\circ} y'_< - y'_< \cancel{y_>}^{\circ} = -1 \cdot \frac{2}{\partial r} \frac{1}{r} = \frac{1}{r^2}$$

And $p(r) W(r) = 1$ thus

$$G(r, r_0) = \frac{1}{r} \cdot 1 \Theta(r - r_0) + 1 \cdot \frac{1}{r_0} \Theta(r_0 - r) \quad \checkmark$$

- Graph



as expected!
This is the potential
of a charged sphere
up to $Q/4\pi r_0^2$

We said that for the differential equation

$$\left[-\frac{d}{dx} p(x) \frac{d}{dx} + q(x) \right] G(x, x_o) = \delta(x - x_0)$$

we had a green function given by Eq. (22.1) in the hand written notes. Expanding the above equation, we have

$$-p(x) \left[\frac{d^2}{dx^2} + P(x) \frac{d}{dx} + Q(x) \right] G(x, x_0) = \delta(x - x_0)$$

were $P(x) = p'(x)/p(x)$ and $Q(x) = q(x)/(-p(x))$. Now note that the green function \hat{G} of Eq. (1) in the notes satisfies

$$\left[\frac{d^2}{dx^2} + P(x) \frac{d}{dx} + Q(x) \right] G_{\text{other}}(x, x_o) = \delta(x - x_0)$$

and is therefore just a little different from Eq. (22.1) because the coefficient of d^2/dx^2 is normalized differently. Thinking carefully, if we know G then multiplying the “other” equation by $-p(x)$ and changing $-p(x) \rightarrow -p(x_0)$ on the rhs where it multiplies $\delta(x - x_0)$, we can conclude that

$$-p(x_0)G(x, x_0) = G_{\text{other}}(x, x_0)$$

For this reason the green function sometimes looks different in different books.

Green Fcn of the SHO

$$\left[m \frac{d^2}{dt^2} + \gamma m \frac{d}{dt} + m\omega_0^2 \right] x = f(t) \quad \begin{matrix} x(a) = x_0 \\ v(a) = v_0 \end{matrix}$$

- First the homogeneous equations. The general procedure for differential equations is to look for solutions of the form, $e^{i\omega t}$, and to solve for ω

$$[-m\omega^2 - i\gamma\omega + m\omega_0^2] e^{-i\omega t} = 0 \quad \begin{matrix} x(a) = x_0 \\ v(a) = v_0 \end{matrix}$$

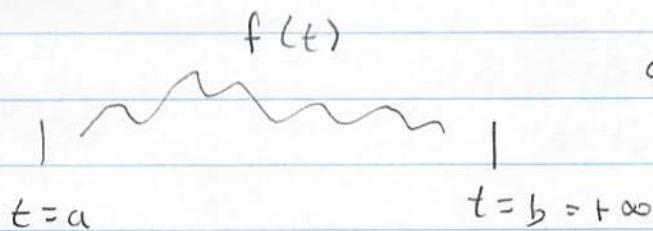
Solve for small γ , $\omega = \pm\omega_0 - i\frac{\gamma}{2}$

So the homogeneous solution is

$$x(t) = A_1 e^{-\gamma/2 t} e^{i\omega_0 t} + A_2 e^{-\gamma/2 t} e^{-i\omega_0 t}$$

we adjust
 A_1 and A_2
to satisfy b.c.

- Now we look for the Green function:



$a < t_0$

causal b.c.
homogeneous

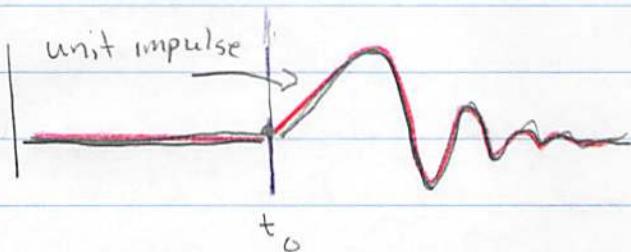
$$G(a, t_0) = 0$$

$$\mathcal{L} G(t, t_0) = \delta(t - t_0)$$

$$\dot{G}(a, t_0) = 0$$

(25)

Then qualitatively; the particle gets a kick at t_0 and then moves



homogeneous

 γ

- ① Then $x_{<}(t) = 0$. This is the only solution which satisfies the b.c. $G(q, t_0) = 0 \quad \frac{dG(q, t_0)}{dt} = 0$
- ② For $x_{>}(t)$ we take a super-position of the two exponents which vanishes at t_0 .

$$x_{>} (t) = C e^{-\gamma_L (t - t_0)} \sin(\omega_0 (t - t_0))$$

- ③ The remaining constant follows from the jump

$$\int_{t_0 - \varepsilon}^{t_0 + \varepsilon} m \frac{d^2}{dt^2} x + \text{lower derius} = \int_{t_0 - \varepsilon}^{t_0 + \varepsilon} s(t - t_0)$$

$$\left. m \frac{dx}{dt} \right|_{t_0 + \varepsilon} - \left. m \frac{dx}{dt} \right|_{t_0 - \varepsilon} = 1$$

$$\text{unit impulse} \rightarrow \left. m \frac{dx}{dt} \right|_{t_0 + \varepsilon} = 1$$

$$C = \frac{1}{m\omega_0}$$

$$x_{>} (t) = C \omega_0 (t - t_0) + O((t - t_0)^2)$$

So

$$(26.1) \quad \text{★ } G(t, t_0) = e^{-\frac{\gamma/2(t-t_0)}{m\omega_0}} \sin(\omega_0(t-t_0)) \theta(t-t_0)$$

The general solution is then

$$y(t) = A_1 e^{-\frac{\gamma/2 t}{m\omega_0}} e^{+i\omega_0 t} + A_2 e^{-\frac{\gamma/2 t}{m\omega_0}} e^{-i\omega_0 t} + \int_0^t f(t_0) e^{-\frac{\gamma/2(t-t_0)}{m\omega_0}} \sin(\omega_0(t-t_0)) dt_0$$

Causal Green Functions via Fourier Transform

- For very simple equations like the damped SHO or the drag equation the F.Transform is an easy way to proceed

$$\frac{dv}{dt} + \gamma v = f(t) \quad v(a) = v_0$$

- with homogeneous solution $(e^{-\gamma t})$ and Green function satisfying

$$\frac{dG}{dt} + \gamma G = \delta(t-a) \quad G(t=a, t_0) = 0$$