

# Electricity and Magnetism + Helmholtz Theorems

$$\nabla \cdot \vec{E}_{SI} = \rho_{SI} / \epsilon_0$$

$$c^2 = \frac{1}{\mu_0 \epsilon_0}$$

$$\nabla \times \vec{B}_{SI} = \mu_0 \vec{j}_{SI} + \mu_0 \epsilon_0 \frac{\partial \vec{E}_{SI}}{\partial t}$$

$$\nabla \cdot \vec{B}_{SI} = 0$$

$$-\nabla \times \vec{E}_{SI} = \frac{\partial \vec{B}_{SI}}{\partial t}$$

In order to reduce  $\mu_0$ ,  $\epsilon_0$  etc and to make the speed of light more explicit

Define

$$\vec{E} \equiv \sqrt{\epsilon_0} \vec{E}_{SI}$$

$$\rho = \frac{\rho_{SI}}{\sqrt{\epsilon_0}}$$

$$\vec{B} \equiv \frac{\vec{B}_{SI}}{\sqrt{\mu_0}}$$

$$\vec{j} = \sqrt{\mu_0} \vec{j}_{SI}$$

This is known as Heaviside-Lorentz units, and is the set of units I prefer, since the speed of light is explicit.

Then the Maxwell Equations read

$$a) \quad \nabla \cdot \vec{E} = \rho$$

$$b) \quad \nabla \times \vec{B} = \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

$$c) \quad \nabla \cdot \vec{B} = 0$$

$$d) \quad -\nabla \times \vec{E} = \frac{\partial \vec{B}}{\partial t}$$

↑  
sourced  
↓

↑  
source free  
↓

Then we can use the Helmholtz Theorem to good effect in the source free equations

From c)  $\nabla \cdot \vec{B} = 0 \Rightarrow \vec{B} = \nabla \times \vec{A}$

From d)  $-\nabla \times \vec{E} = \frac{\partial \vec{B}}{\partial t} \Rightarrow -\nabla \times \left( \vec{E} + \frac{1}{c} \frac{\partial \vec{A}}{\partial t} \right) = 0$

So there is a  $\phi$  such that:

$$\vec{E} + \frac{1}{c} \frac{\partial \vec{A}}{\partial t} = -\nabla \phi \Rightarrow \vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} - \nabla \phi$$

Usually it is easier to work with  $(\phi, \vec{A})$  since two of the Maxwell equations are automatically satisfied.

## E+M and Electrostatics

$$\text{For } \vec{B} = \vec{j} = 0$$

$$\left. \begin{array}{l} \nabla \cdot \vec{E} = \rho \\ \nabla \times \vec{E} = 0 \end{array} \right\}$$

Using Helmholtz since  $\nabla \times \vec{E} = 0$

$$\vec{E} = -\nabla \phi \quad E_i = -\partial_i \phi$$

Then

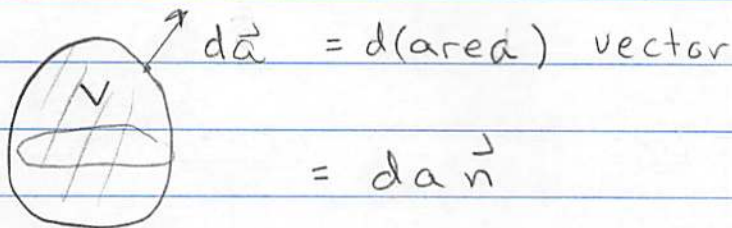
$$-\nabla \cdot (\nabla \phi) = \rho \quad \text{or} \quad \underbrace{-\nabla^2 \phi = \rho}_{\text{Poisson eq}} \quad \text{or} \quad \underbrace{-\partial_i \partial_i \phi = \rho}_{\text{Same}}$$

We will use the Poisson equation to illustrate a number of points throughout the course



# E+M and the Stoke's Theorems

①



$$\oint_V \nabla \cdot \vec{W} = \oint_{\partial V} d\vec{a} \cdot \vec{W}$$

Divergence

$$\oint_V \partial_j W^i = \oint_{\partial V} da_j W^i$$

②



then

Curl

$$\int_A d\vec{a} \cdot (\nabla \times \vec{W}) = \int_{\partial A} \vec{W} \cdot d\vec{l}$$

or

$$\int da_j \epsilon^{ijk} \partial_j W_k = \int dl_i W^i$$

③ Finally,

A diagram showing a curved line segment from point  $a$  to point  $b$ . An arrow labeled  $d\vec{l}$  points from  $a$  towards  $b$ .

$$\int_a^b d\vec{l} \cdot \vec{\nabla} \phi = \phi(x^b) - \phi(x^a)$$

## Examples of The Stokes Theorems from EM

• Maxwell Eqns in integral form

$$d) \quad -\nabla \times \vec{E} = \frac{1}{c} \frac{\partial \vec{B}}{\partial t} \quad \leftarrow \text{differential form of Faraday law}$$

Integrating over area

$$-\int d\vec{a} \cdot \nabla \times \vec{E} = \frac{1}{c} \frac{\partial}{\partial t} \int \vec{B} \cdot d\vec{a}$$

$$d) \quad -\oint \vec{E} \cdot d\vec{l} = \frac{1}{c} \frac{\partial}{\partial t} \int \vec{B} \cdot d\vec{a} \quad \leftarrow \text{integral form of Faraday law}$$

Similarly we have for Maxwell equations a), b), c)

$$a) \quad \oint_{\partial V} \vec{E} \cdot d\vec{a} = \int_V d^3x \rho$$

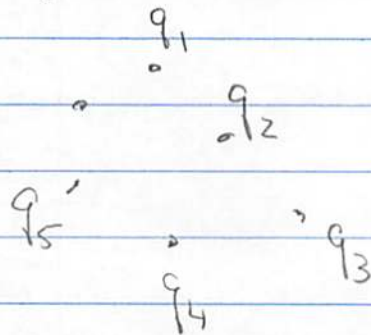
$$b) \quad \oint \vec{B} \cdot d\vec{l} = \int d\vec{a} \cdot \frac{\vec{j}}{c} + \frac{1}{c} \frac{\partial}{\partial t} \int \vec{E} \cdot d\vec{a}$$

$$c) \quad \oint_{\partial V} \vec{B} \cdot d\vec{a} = 0$$



## Example of Stoke's Theorem and integration by parts

$$U = \frac{1}{2} \sum_{i \neq j} \frac{q_i q_j}{4\pi |\vec{r}_i - \vec{r}_j|}$$



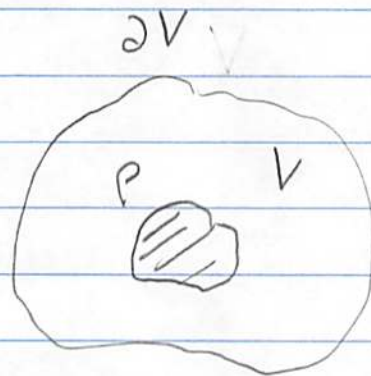
$$U = \frac{1}{2} \sum_i q_i \phi(\vec{r}_i)$$

For a continuous charge density  $\rho$

$$U = \frac{1}{2} \int d^3r \rho(\vec{r}) \phi(\vec{r})$$

Want to show

$$U = \frac{1}{2} \int d^3r \vec{E} \cdot \vec{E}$$



Proof

$$U = \frac{1}{2} \int_V d^3\vec{r} (-\partial_i \partial^i \phi) \phi$$

poisson eq.  
 $(-\partial_i \partial^i \phi = \rho)$

$$(\partial_i \partial^i \phi) \phi = \partial_i (\partial^i \phi \phi) - \partial^i \phi \partial_i \phi$$

$$U = \frac{1}{2} \int_V d^3r -\partial_i (\partial^i \phi \phi) + \frac{1}{2} \int_V \partial^i \phi \partial_i \phi$$

Then using the divergence theorem

$$U = \underbrace{\frac{1}{2} \oint_{\partial V} da_i (-\partial^i \phi)}_{\text{boundary term}} + \frac{1}{2} \int_V \partial^i \phi \partial_i \phi$$

boundary term important in some applications.

If  $V$  is large enough and  $\phi \xrightarrow[r \rightarrow \infty]{} 0$  sufficiently quickly, it can be neglected

$$U = \frac{1}{2} \int_V \partial^i \phi \partial_i \phi = \frac{1}{2} \int_V \vec{E} \cdot \vec{E}$$

General Rule for integration by parts (IBP)

$$\int_V d^3r (-\partial_i \partial^i \phi) \phi = \int_V \partial^i \phi \partial_i \phi + \text{bdry terms}$$

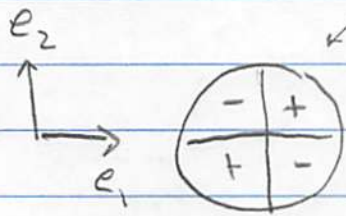
↑  
move the  
derivative from one  
side to other +  
change sign

I have collected a number of examples from the EM course of IBP in homework.



# Tensors

- Example: want to describe the potential from a charge distribution and its orientation. This charge distribution is described by two vectors. Far from this set of charges the potential takes the form



$$\phi(r) \approx \frac{1}{4\pi} \frac{1}{2} Q^{ij} \frac{\hat{r}_i \hat{r}_j}{r^3}$$

- Where the quadrupole tensor is

$$Q^{ij} = \int d^3\vec{x} \rho(\vec{r}) (3x^i x^j - r^2 \delta^{ij})$$

- Note this tensor is traceless:

$$\text{trace} = \delta_{ij} Q^{ij} = \int d^3 \rho(r) [3 x^i x^j \delta_{ij} - r^2 \delta^{ij} \delta_{ij}]$$

Use  $\delta^{ij} \delta_{ij} = 3$ ,  $x^i x^j \delta_{ij} = r^2$  to find

$$\text{Trace} = \delta_{ij} Q^{ij} = 0$$

- Rotations rotate each "arm" of the tensor

$$\underline{Q}^{ij} = R^i_k R^j_m Q^{km}$$

← original tensor

↑ rotated tensor components



Then,  $\vec{Q} = Q^{ij} \vec{e}_i \vec{e}_j$ , is the physical tensor  
and is unchanged by the rotation, since

$$\vec{e}_i \vec{e}_j = \vec{e}_l \vec{e}_m (\mathcal{R}^{-1})^l_i (\mathcal{R}^{-1})^m_j$$