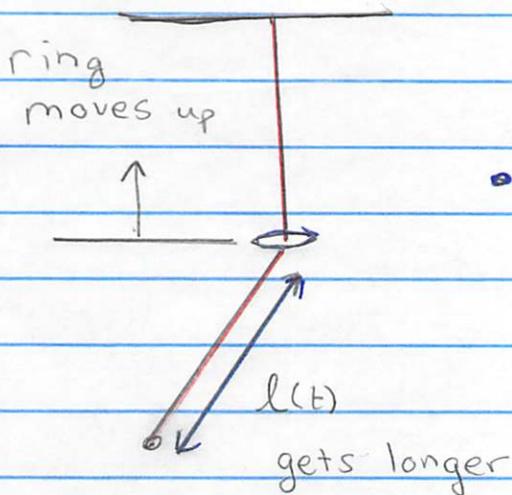


Adiabatic Invariance

• Example

- A string pendulum is passed through a loop. The loop is slowly raised

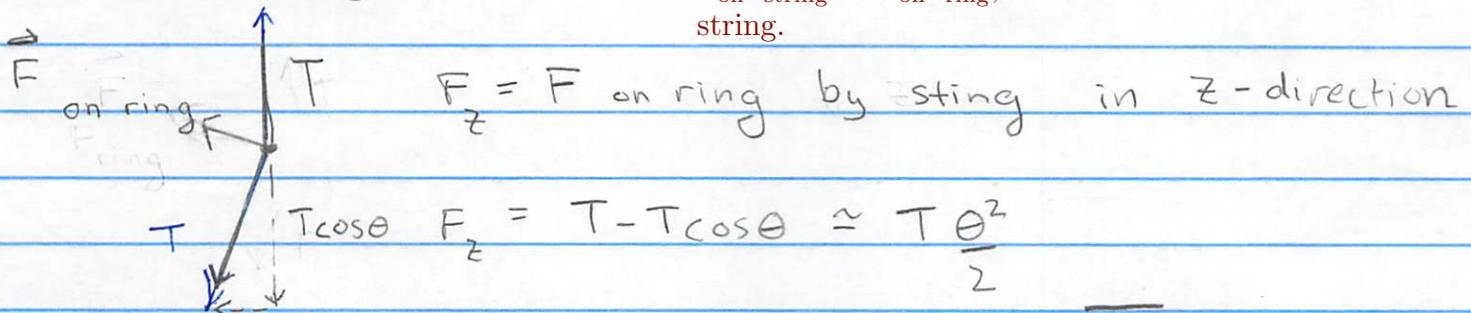


- The string pendulum does work on the ring. E changes in time, but the resonance frequency $\omega = \sqrt{g/l}$ also changes, leaving:

$$\frac{E}{\omega} = \alpha E \sqrt{l} \approx \text{constant}$$

Simple argument:

There is an equal-and-opposite force to $\vec{F}_{\text{on-ring}}$, $\vec{F}_{\text{on-string}} = -\vec{F}_{\text{on-ring}}$, which causes the kink in the string.



So the average upward force is $\overline{\theta^2/2} = E$

$$\overline{F_z} = mg \frac{\overline{\theta^2}}{2} = \frac{E}{2l}$$

So the work done by string per time is

$$-\frac{dE}{dt} = \overline{F_z} \frac{dl}{dt} = \frac{E}{2l} \frac{dl}{dt}$$

Which implies (by multiplying by \sqrt{l})

$$\frac{d}{dt}(E\sqrt{l}) = 0$$

As we will this was to be expected. For a slow change of a parameter, there is an adiabatic invariant. For the SHO this evaluates to the energy per frequency

$$\frac{E(t)}{\omega(t)} \approx \text{constant}$$

General Discussion:

- Consider a 1D system with 1D motion that is periodic and subject to an external parameter $\lambda(t)$ which is slow

$T \equiv$ period of oscillation $\rightarrow T \frac{d\lambda}{dt} \ll \lambda$ $\leftarrow \lambda$ is e.g. the length of string $l(t)$ changing in time.

- The Hamiltonian of the system $H(q, p, \lambda)$. The energy of the system is, $E = H(q, p, \lambda)$, which implicitly determines p , $p = p(q, E, \lambda)$.
- From Hamilton's EOM $dH/dt = \partial H/\partial t$

$$\frac{dE}{dt} = \frac{\partial H}{\partial t} = \left(\frac{\partial H}{\partial \lambda} \right)_p \frac{d\lambda}{dt}$$

$\leftarrow q$ will always be held fixed below

- Now we can average over a time scale Δt which is long compared to the period T , but short compared to the adiabatic time scale

$$\frac{\Delta E}{\Delta t} = \overline{\left(\frac{\partial H}{\partial \lambda}\right)_p} \frac{\Delta \lambda}{\Delta t}$$

- Where the average means averaged over a cycle

$$\overline{\left(\frac{\partial H}{\partial \lambda}\right)_p} = \frac{1}{T} \oint \left(\frac{\partial H}{\partial \lambda}\right)_p dt \quad \leftarrow \text{This is the time averaged force exerted by the string on the ring in our example}$$

$$T \equiv \oint dt \equiv \text{period}$$

- rewriting $dt = dq / \dot{q} = dq / (\partial H / \partial p)_\lambda$

$$\frac{\Delta E}{\Delta t} = \frac{\Delta \lambda}{\Delta t} \oint \left(\frac{\partial H}{\partial \lambda}\right)_p \frac{dq}{\left(\frac{\partial H}{\partial p}\right)_\lambda}$$

$$\oint \frac{dq}{\left(\frac{\partial H}{\partial p}\right)_\lambda}$$

This trajectory is over a cycle with fixed λ where E is an independent variable and constant variable. p is regarded as a function of the independent variables E, λ through the implicit equation $E = H(p(E, \lambda), \lambda)$

and is an

- Now at fixed λ , the energy is constant independent var.

$$\left(\frac{\partial E}{\partial \lambda}\right)_E = 0 = \left(\frac{\partial H}{\partial \lambda}\right)_p \cdot 1 + \left(\frac{\partial H}{\partial p}\right)_\lambda \left(\frac{dp}{d\lambda}\right)_E \quad p = p(q, E, \lambda)$$

$$\text{or } \left(\frac{\partial H}{\partial \lambda}\right)_p / \left(\frac{\partial H}{\partial p}\right)_\lambda = -\left(\frac{\partial p}{\partial \lambda}\right)_E$$

So

$$\frac{\Delta E}{\Delta t} = \frac{\Delta \lambda}{\Delta t} \frac{\oint - (\partial P / \partial \lambda)_E dq}{\oint (\partial P / \partial E)_q dq}$$

Re-arranging

$$\oint \left(\frac{\partial P}{\partial E} \right) \frac{\Delta E}{\Delta t} + \frac{\partial P}{\partial \lambda} \frac{\Delta \lambda}{\Delta t} dq = 0$$

←—————→

or

$$\Delta P / \Delta t$$

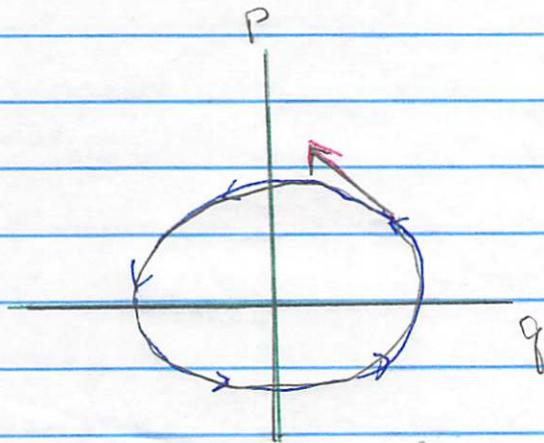
And thus

$$\frac{\Delta I}{\Delta t} = 0 \quad I = \oint \frac{p dq}{2\pi}$$

inserting 2π is
conventional in
the classical
theory

During the evolution of the system with a time dependent parameter λ , the Energy will change in time but the adiabatic invariant $I(E, \lambda) \equiv \oint p dq / 2\pi$ will remain fixed in time.

- To understand what I means, first note that we may use the curl theorem:



$$\vec{V} = (p, 0) \quad d\vec{l} = (dq, dp)$$

Then

$$\oint \vec{V} \cdot d\vec{l} = \int (\nabla \times \vec{V}) \cdot d\vec{a}$$

To write $\oint p dq = \int_{\text{line}} dp dq$
line area

$$I = \int \frac{dq dp}{2\pi}$$

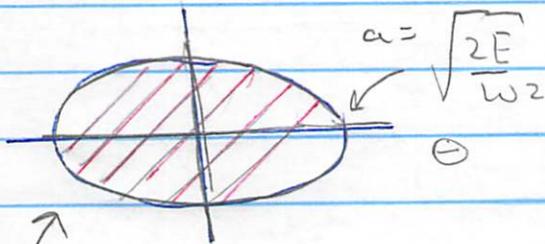
area
determined by E

so the phase space
area remains fixed
in time

- For a SHO:

$$E = \frac{p^2}{2} + \frac{\omega^2}{2} q^2$$

$$b = \sqrt{2E}$$



Area of Ellipse
 $A = \pi ab$

$$I = \oint p dq / 2\pi$$

$$= \int \frac{dp dq}{2\pi}$$

area

$$I = \frac{E}{\omega}$$

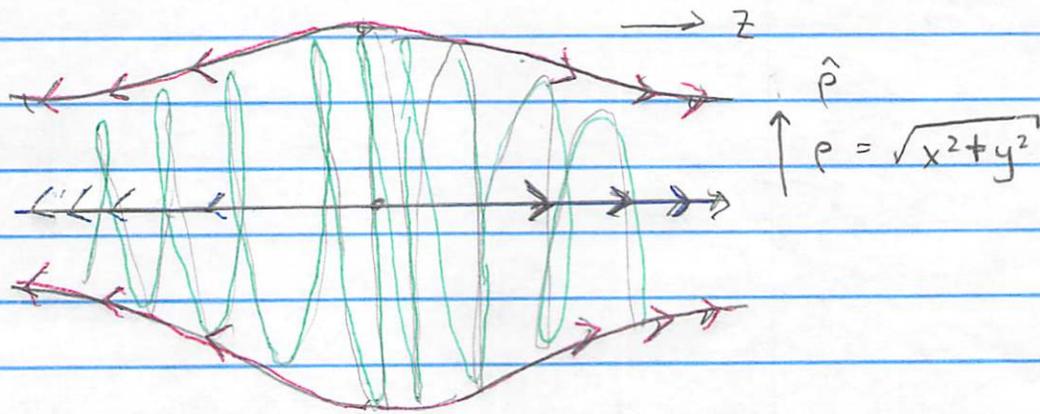
- So the energy per frequency is constant!

Example - Magnetic Confinement of Charged Particle

- Consider a fast moving electron in a magnetic field which grows slowly along the z -direction, e.g. $B_z(z) = B_0 (1 + z^2/a^2)$

- Since $\nabla \cdot \vec{B} = 0$ there is a small correction to $\vec{B} = B_z(z) \hat{z} - \frac{1}{2} B'(z) \rho \hat{\rho}$ in the directions

perpendicular to the z -axis



- As the charged particle flies toward the region of high field, the transverse (x, y) kinetic energy increases, and the particle's longitudinal kinetic energy decreases until it reaches a stopping point.

Analysis

$$\bullet L = \frac{1}{2} m v^2 + e \vec{v} \cdot \frac{\vec{A}}{c}$$

- Now for a constant magnetic field in the z -direction

$$\vec{A} = \frac{B_0}{2} (-y, x, 0) + \text{gradient corrections if } B \text{ is not constant}$$

- The conserved energy (Hamiltonian function)

$$h(q, \dot{q}) = \frac{\partial L}{\partial \vec{v}} \cdot \vec{v} - L = \frac{1}{2} m v^2 = E$$

i.e. for $\vec{v} = (\vec{v}_\perp, \dot{z})$

$$E = \frac{1}{2} m \dot{z}^2 + \frac{1}{2} m v_\perp^2$$

The period of orbit is $2\pi/\omega_c$

Recall that for a particle

in a magnetic field the "cyclotron" frequency is $\omega_c = eB/mc$.

$$\text{and } \frac{1}{2} m v_\perp^2 = \frac{1}{2} m (\omega_c R)^2$$

- Now the particle has small v_z . We evaluate the adiabatic invariant for $v_z = 0$, and then recognize that if z and v_z change, the adiabatic invariant will be fixed

$$I = \frac{1}{2\pi} \oint p \cdot dq$$

for circular orbit

- Now for a circular orbit

$$\vec{p} = \frac{\partial L}{\partial \vec{v}} = m\vec{v} + \frac{e}{c} \vec{A}$$

- Now algebra determines the integral invariant for $\dot{z} = 0$

$$I = \frac{1}{2\pi} \oint (m\vec{v} + \frac{e}{c} \vec{A}) \cdot \vec{v} dt$$

$\underbrace{\hspace{10em}}_{\vec{p}} \cdot \underbrace{\hspace{10em}}_{d\vec{q}}$

$$I = \frac{1}{2\pi} \int m v_{\perp}^2 dt + \frac{e}{2\pi c} \oint \vec{A} \cdot d\vec{r}$$

$\underbrace{\hspace{10em}}_{\Phi_0 = -B\pi R^2}$

Use the circulation

thrm and $\vec{B} = \nabla \times \vec{A}$

$$\Phi = \oint \vec{A} \cdot d\vec{r} = \int \vec{B} \cdot d\vec{a}$$

$$= -B\pi R^2$$

$$\Phi_0 = -B\pi R^2$$



$$= \frac{1}{2\pi} m v_{\perp}^2 \frac{2\pi}{\omega_c} - \frac{e}{2\pi c} B\pi R^2$$

Use $\omega_c = eB/mc$

$$\frac{1}{2} m v_{\perp}^2 = \frac{1}{2} m (\omega_c R)^2$$

$$I = \frac{1}{2} m v_{\perp}^2 \left(\frac{mc}{eB} \right)$$

so

$$\frac{1}{2} m v_{\perp}^2 = I \omega_c \quad \omega_c = \frac{eB}{mc}$$

- Now we can use that I is approximately constant as z - slowly changes

$$\frac{1}{2} m \dot{z}^2 + \frac{1}{2} m v_{\perp}^2 = E$$

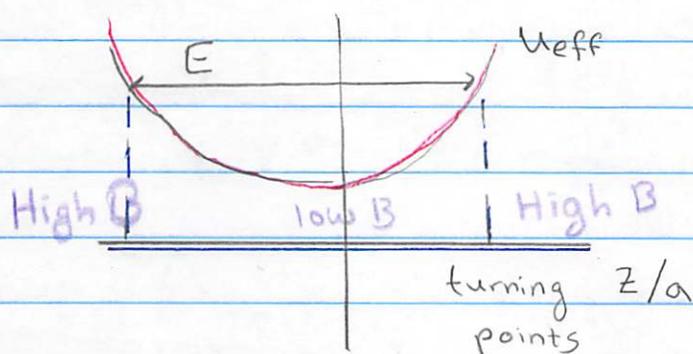
$$\frac{1}{2} m \dot{z}^2 + \frac{I e B(z)}{m c} = E$$

- So for $B(z) = B_0 (1 + z^2/a^2)$ we can describe the motion as that of an effective potential

$$\frac{1}{2} m \dot{z}^2 = E - U_{\text{eff}}(z)$$

where

$$U_{\text{eff}} = \frac{I e B_0}{m c} \left(1 + \frac{z^2}{a^2} \right)$$



which can be used to evaluate the period of oscillations and the turning points