

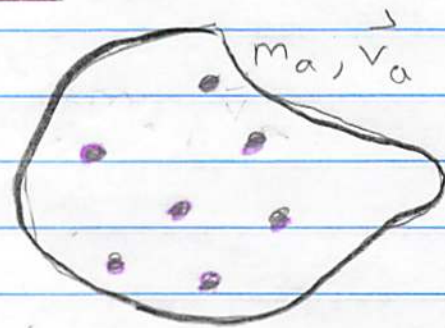
# Momentum of a System of Particles

Newton:

$$\frac{d\vec{p}_a}{dt} = \vec{F}_a$$

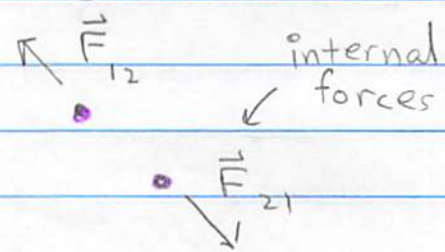
with  $\vec{p}_a = m_a \vec{v}_a$

system



Now divide the forces up into external forces and internal ones:

$$\vec{F}_a = \vec{F}_a^{\text{ext}} + \sum_b \vec{F}_{ab}$$



Force on a-th particle by b-th

Summing over particles:

$$\frac{d\vec{p}_{\text{Tot}}}{dt} = \sum_a \vec{F}_a^{\text{ext}} + \sum_{a,b} \vec{F}_{ab}$$

$$\frac{d\vec{p}_{\text{Tot}}}{dt} = \vec{F}_{\text{Tot}}^{\text{ext}}$$

Total external force

Equal and opposite:  
Newton's 3rd Law  
 $\vec{F}_{ab} = -\vec{F}_{ba}$

where

$$\vec{p}_{\text{Tot}} = \sum_a m_a \vec{v}_a = \text{Total momentum}$$

- Define the center of mass

$$\star R_{cm} \equiv \sum m_a \vec{r}_a / M_{TOT} \quad \text{and so:}$$

$$\star \vec{V}_{cm} = \sum_a m_a \vec{v}_a / M_{TOT}$$

So

$$P_{TOT} \equiv M_{TOT} \vec{V}_{cm}$$

## Angular Momentum

the EOM

$$\frac{d\vec{p}_a}{dt} = \vec{F}_a$$

- Taking the cross product:

$$\vec{r}_a \times \frac{d\vec{p}_a}{dt} = \vec{r}_a \times \vec{F}_a$$

Now:

since  $\vec{p}_a = m\vec{v}_a$

$$\frac{d}{dt} \vec{r}_a \times \vec{p}_a = \cancel{v_a \times \vec{p}_a} + \vec{r}_a \times \frac{d\vec{p}_a}{dt}$$

- So the angular momentum changes as:

$$\frac{d\vec{l}_a}{dt} = \vec{r}_a \times \vec{F}_a \quad \vec{l}_a \equiv \vec{r}_a \times \vec{p}_a$$



- Summing over the particles, and again writing

$$\vec{F}_a = \vec{F}_a^{\text{ext}} + \vec{F}_{ab}$$

We have

$$\frac{d\vec{L}_{\text{tot}}}{dt} = \underbrace{\sum_a \vec{r}_a \times \vec{F}_a^{\text{ext}}}_{\text{external torques on the system}} + \underbrace{\sum_{ab} \vec{r}_a \times \vec{F}_{ab}}_{\text{internal torque } \vec{L}_{\text{int}}}$$

with

$$\vec{L}_{\text{tot}} = \sum_a \vec{l}_a \equiv \text{total angular momentum}$$

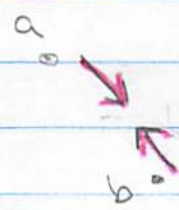
- Now the internal torques cancel (for a large variety of forces) since

$$\begin{aligned} \vec{L}_{\text{int}} &= \sum_{ab} \vec{r}_a \times \vec{F}_{ab} = \frac{1}{2} \sum_{ab} (\vec{r}_a \times \vec{F}_{ab} + \vec{r}_b \times \vec{F}_{ba}) \\ &= \frac{1}{2} \sum_{ab} (\vec{r}_a - \vec{r}_b) \times \vec{F}_{ab} \end{aligned}$$

$\swarrow = -\vec{F}_{ab}$

Now, typically the forces are directional

$$\vec{F}_{ab} \propto \vec{r}_a - \vec{r}_b \quad \text{like gravity}$$



and then the internal torques vanish, being of the form

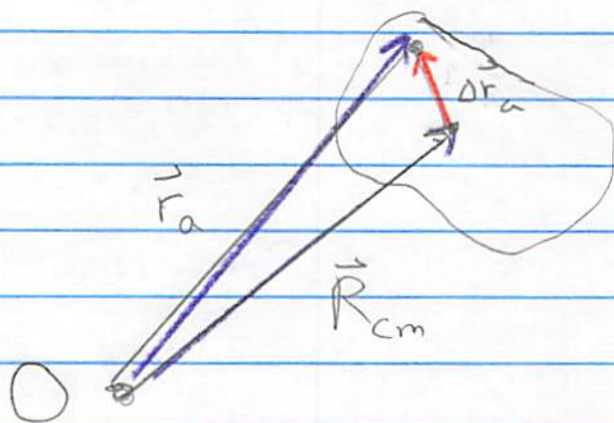
$$(\vec{F}_a - \vec{F}_b) \times (\vec{r}_a - \vec{r}_b) = 0$$

And then

$$\frac{d\vec{L}_{\text{Tot}}}{dt} = \vec{\tau}_{\text{ext Tot}}$$

There can be modifications to this when spin is involved, and  $\vec{F}_{ab} \neq$  proportional to  $\vec{r}_a - \vec{r}_b$

We have worked with a specific origin  $O$ . Let us pause to determine the angular momentum around the CM:



$$\vec{r}_a = \vec{R}_{cm} + \Delta \vec{r}_a$$

So

$$\vec{L}_O = \sum_a (\vec{R}_{cm} + \Delta \vec{r}_a) \times \vec{p}_a$$



Yielding:

$$\vec{L}_O = \vec{R}_{cm} \times \vec{P}_{TOT} + \sum_a \vec{\Delta r}_a \times \vec{p}_a$$

←—————→                      ←—————→

angular momentum of cm around O                      angular momentum about the cm

$$\vec{P}_{TOT} = \sum \vec{p}_a$$

## Energy

- Take a single particle

$$\frac{d\vec{p}}{dt} = \vec{F}$$

- Multiply by  $\vec{v}$

$$\vec{v} \cdot \frac{d\vec{p}}{dt} = \vec{F} \cdot \vec{v}$$

- Use  $\vec{p} = m\vec{v}$  and then

$$\frac{d}{dt} \left( \frac{1}{2} m v^2 \right) = \vec{v} \cdot m \vec{v}$$

- To find after integration from  $t_i \rightarrow t_f$

$$\frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 = \int_{x_i}^{x_f} \vec{F} \cdot d\vec{x}$$

- For  $\vec{F}$  conservative:

$$\vec{F} = -\frac{\partial U(x)}{\partial \vec{x}}$$

And

$$W_{if} = -(U(x_f) - U(x_i))$$



• Yielding  $T \equiv \frac{1}{2} m \dot{x}^2$

$$T(\dot{x}_f) + U(x_f) = T(\dot{x}_i) + U(x_i)$$

So energy is conserved. In general (see Tong)  
(or Goldstein)

$$E = \underbrace{\sum_a \frac{1}{2} m \vec{V}_a^2}_{\text{Kinetic}} + \underbrace{U^{\text{ext}}(x_a) + \frac{1}{2} \sum_{a \neq b} U(|\vec{r}_a - \vec{r}_b|)}_{\text{potential}}$$

• A short exercise also shows that if we write

$$\vec{V}_a = \vec{V}_{\text{cm}} + \Delta \vec{V}_a \quad \leftarrow \begin{array}{l} \text{velocity} \\ \text{relative} \\ \text{to cm.} \end{array}$$

Then show for yourself that:

$$T = \frac{1}{2} M V_{\text{cm}}^2 + \frac{1}{2} \sum_a m \Delta V_a^2$$

↑  
Kinetic  
energy  
of cm

↑  
internal kinetic  
energy.