

Ponderomotive Force

- Landau 30 / Fowler UVA

Consider a particle in a potential $m\ddot{x} = -\partial U/\partial x$. Now add an external force:

$$f(x,t) = f_0(x) \cos(-\omega t + \varphi(x)) \\ = f_1(x) \cos \omega t + f_2(x) \sin \omega t$$

Where ω is large compared to $1/T$, $\omega \gg 1/T$, with T is a typical timescale for motion in the potential.

- The rapidly oscillating force will generate oscillations around a smooth path

$$x(t) = X(t) + \zeta(t) \leftarrow \begin{array}{l} \text{assumed} \\ \text{to be small} \end{array}$$

\nearrow smooth path \nwarrow rapid oscillations

You might think that $X(t)$ would follow the potential $U(x)$, but in fact the oscillations modify the effective potential that the particle experiences

- Then for small ξ

$$m \ddot{X} + m \ddot{\xi} = -\frac{\partial U(X)}{\partial X} + \xi \frac{\partial^2 U(X)}{\partial X^2}$$

$$+ f(X, t) + \xi \frac{\partial f}{\partial X}$$

- Now ξ is small, but $\ddot{\xi}$ is not

$$\ddot{\xi} \sim \omega^2 \xi$$

Since ω is large,

- Equating the slow and fast parts

$$m \ddot{\xi} = f(X, t)$$

- And for the slow part

$$m \ddot{X} = -\frac{\partial U(X)}{\partial X} - \xi \frac{\partial^2 U(X)}{\partial X^2} + \xi \frac{\partial f}{\partial X}$$

Here we are averaging to remove any fast oscillations over a time Δt which is long compared to ω^{-1} but short compared to T

$$\omega^{-1} \ll \Delta t \ll T$$

• Now we can solve for \bar{x}

$$\bar{x} = - \frac{f(x,t)}{m\omega^2} \leftarrow \text{see our results for a driven oscillator}$$

• Then

$$\overline{\bar{x}} \frac{\partial^2 U(x)}{\partial x^2} = 0$$

↑ ↑
sinusoidal constant

But

$$\begin{aligned} \overline{\bar{x}} \frac{\partial f}{\partial x} &= - \frac{f}{m\omega^2} \frac{\partial f}{\partial x} = - \frac{2}{\omega^2} \frac{f^2}{2m\omega^2} \\ &= - \frac{2}{\omega^2} \frac{(f_1^2 + f_2^2)}{2m\omega^2} \end{aligned}$$

• So the slow motion satisfies

$$m \ddot{x} = - \frac{\partial U_{\text{eff}}}{\partial x}$$

Where

$$U_{\text{eff}} = U(x) + \frac{f^2(x)}{2m\omega^2}$$

the ponderomotive potential

For harmonic motion the velocity is

$$|\dot{z}| = \left| \frac{f}{m\omega} \right|$$

We see that

$$U_{\text{eff}} = U + \frac{1}{2} m \overline{\dot{z}^2}(x)$$

average kinetic energy at point X

Comment

- We have used the variable x and force f . We could have used a general coordinate q

$$L = \frac{1}{2} m_{\text{eff}} \dot{q}^2 - U(q) + L_{\text{fast}}(q)$$

$\propto \cos \omega t$

Then the EOM is

$$m_{\text{eff}} \ddot{q} = - \frac{\partial U}{\partial q} + \frac{\partial L_{\text{fast}}}{\partial q} + f_2(q) \sin \omega t$$

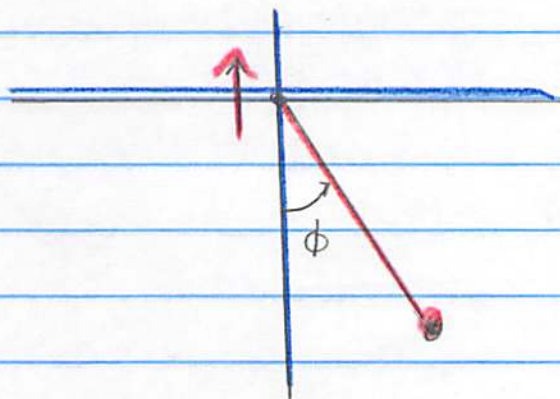
force $f_q = f_1(q) \cos \omega t$

The ponderomotive potential is

$$U_{\text{eff}} = U(q) + \frac{f_q^2}{2 m_{\text{eff}} \omega^2}$$

• It can also be generalized to more coordinates

Example: Inverted pendulum with driven support



$$y = a \cos \Omega t - l \cos \phi \quad x = l \sin \phi$$

Then

$$L = \frac{1}{2} m l^2 \dot{\phi}^2 - m l a \Omega \sin \Omega t \sin \phi \dot{\phi} + \frac{1}{2} m a^2 \Omega^2 \cos^2 \Omega t - \underbrace{m g (a \cos \Omega t - l \cos \phi)}_{\textcircled{2}}$$

Neglecting total derivatives $\textcircled{1}$, $\textcircled{2}$:

$$L = \frac{1}{2} m l^2 \dot{\phi}^2 - \underbrace{m l a \Omega \sin \Omega t \sin \phi \dot{\phi}}_{\textcircled{1}} + m g l \cos \phi$$

This term is also a total derivative

$$\underbrace{- m l a \Omega \sin \Omega t \sin \phi \dot{\phi}}_{\textcircled{1}} = - \frac{d}{dt} (\sin \Omega t \cos \phi) + \underbrace{\Omega \cos \Omega t \cos \phi}_{\text{no } \phi \text{ term!}}$$

So

$$L = \frac{1}{2} m l^2 \dot{\phi}^2 - l m a \Omega^2 \cos \Omega t \cos \phi + m g l \cos \phi$$

So the EOM:

$$m l^2 \ddot{\phi} = + l m a \Omega^2 \cos \Omega t \sin \phi - m g l \sin \phi$$

$$\underbrace{\hspace{10em}}_{m_{\text{eff}} = m l^2}$$

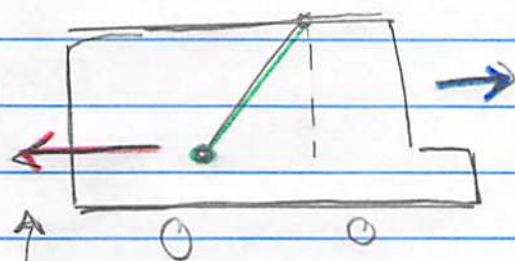
$$\underbrace{\hspace{10em}}_{\text{"generalized force"}}$$

$$\underbrace{\hspace{10em}}_{- \partial U / \partial \phi}$$

gravitational torque

$$\equiv \text{torque } \tau_{\phi}$$

- So the oscillating force is easy to interpret
If I have an accelerating bus

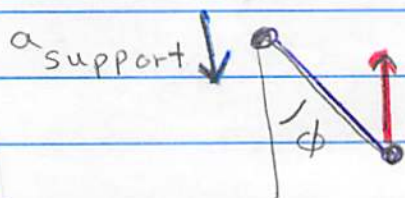


accelerating bus

$$F_{\text{eff}} = -m a_{\text{bus}}$$

There is an effective force $F_{\text{eff}} = -m a_{\text{bus}}$

Here at time $t=0$ we have:



$$F_{\text{eff}} = -m a_{\text{support}} = m a \Omega^2 \cos \Omega t$$

- And the torque it produces (by it I mean the effective force created by the accelerating support. This effective force creates the torque)

$$f_{\phi} = ma \Omega^2 \cos \Omega t \ l \ \sin \phi$$

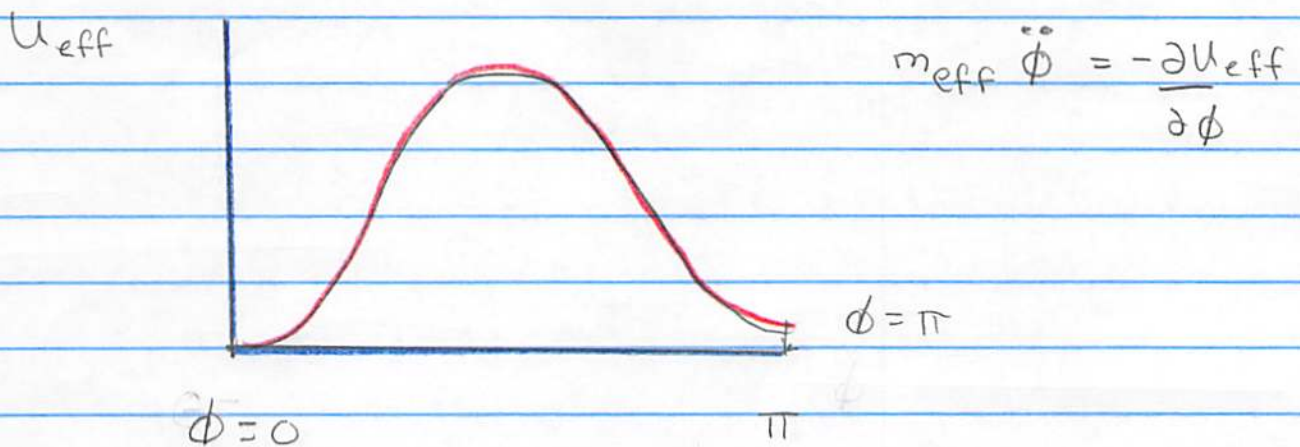
Now we are ready to evaluate U_{eff}

$$U_{\text{eff}} = U(\phi) + \frac{f_{\phi}^2}{2 m_{\text{eff}} \Omega^2}$$

$$\cos^2 \Omega t = 1/2$$

$$U_{\text{eff}} = -mg l \cos \phi + \frac{m a^2 \Omega^2 \sin^2 \phi}{4}$$

- Now Lets analyze the Effective potential for $ma^2 \Omega^2 / 4 \gg mgl$, Then we neglect the $\cos \phi$ term



So we see that $\phi = \pi$ is a minimum of the potential! Let us analyze the stability incorporating the gravitational potential;
Expand

$$U_{\text{eff}} = -mg l \cos \phi + m a^2 \Omega^2 / 4 \sin^2 \phi \quad \text{near } \phi = \pi$$

• Near $\phi = \pi$, $\cos \phi = -1 + \phi^2/2$, $\sin^2 \phi = \phi^2$

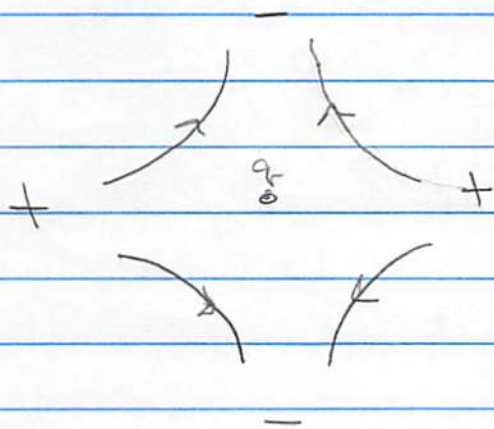
$$U = \left[\frac{mgl}{2} + \left(-\frac{1}{2} + \frac{a^2 \Omega^2}{4gl} \right) \phi^2 + \dots \right]$$

So stability at $\phi = \pi$ only happens when U is concave up, so we require the underlined term to be > 0 ;

$$a^2 \Omega^2 > 2gl$$

① Watch video [\(click me\)](#)

② Another example of the ponderomotive force is the Paul Trap For charged ions. Recall that an electrostatic field can't be used to create a stable minimum since field lines do not end



$$\phi = \frac{k}{2} (x^2 + y^2 - 2z^2)$$

$$f \propto -q \nabla \phi$$

$$f \propto -x \hat{x} - y \hat{y} + 2z \hat{z}$$

restoring force

non-restoring force!

- By having the polarity switch signs rapidly

$$\phi = \frac{k}{2} \cos \Omega t (x^2 + y^2 - 2z^2)$$

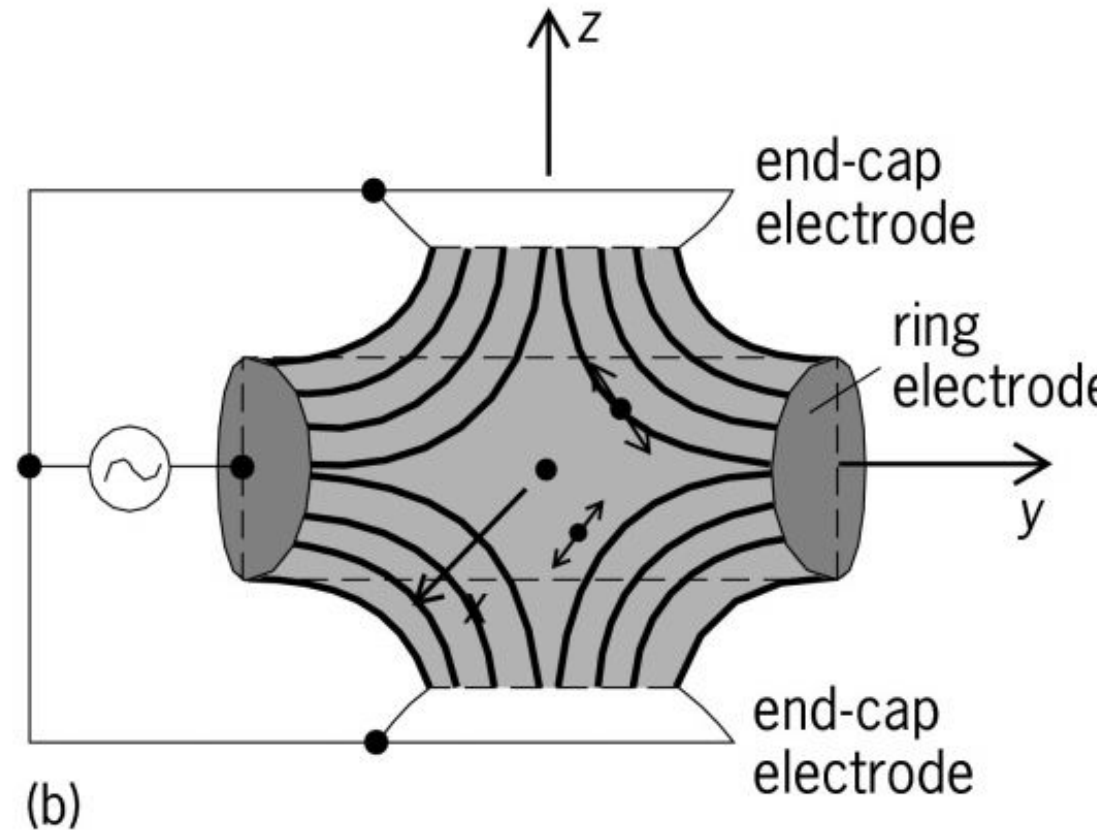
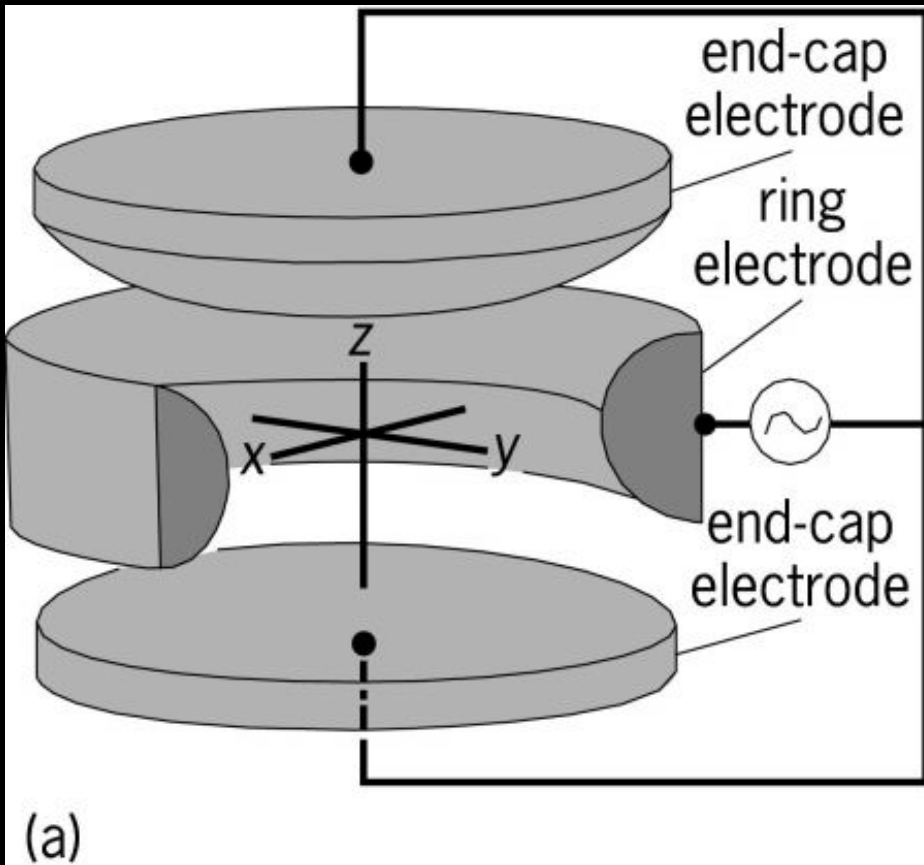
- We create a restoring force $\propto \Omega^2$

$$f_{\text{eff}} \propto -\nabla \bar{f}^2 = -\nabla (x^2 + y^2 + 4z^2)$$

in all three directions

- Design and implementation of the Paul Trap earned Wolfgang Paul and Hans Dehmelt a Nobel Prize in 1989

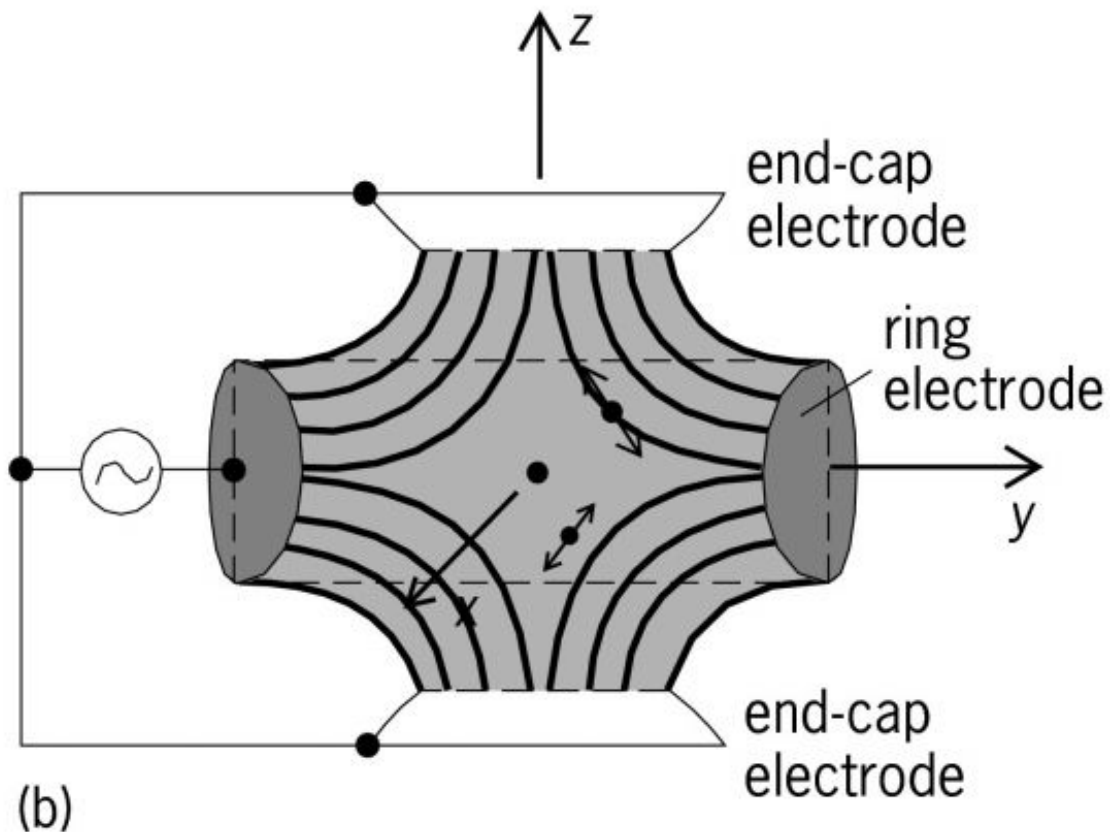
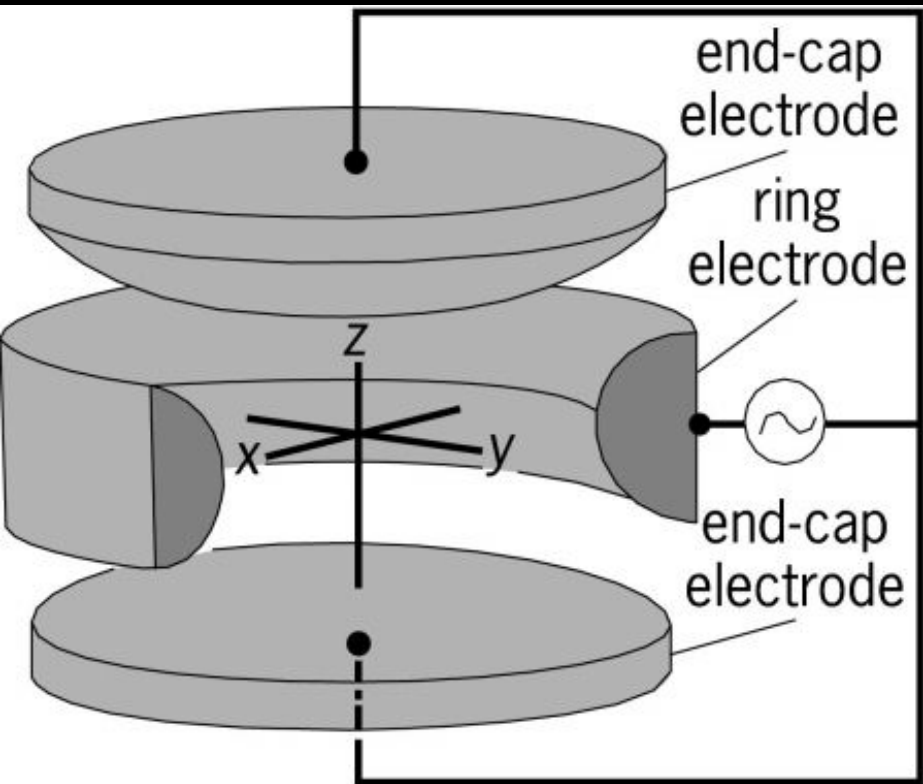
A Paul Trap for Ion Trapping



Electrostatic potential: there is no stable point

$$\phi = \frac{1}{2}A(x^2 + y^2 - 2z^2)$$

A Paul Trap for Ion Trapping



Electrostatic potential with a rapidly changing polarity:
this is stable!

$$\phi = \frac{1}{2} A \cos(\Omega t) (x^2 + y^2 - 2z^2)$$