1.1 Newtonian mechanics a brief review

Momentum and Center of Mass

• Newton's equations of motion for a system of particles reads

$$\frac{d\boldsymbol{p}_a}{dt} = \boldsymbol{F}_a \tag{1.1}$$

where $a = 1 \dots N$ labels the particles. Here $p_a = m_a v_a$. We usually divide up the forces on the *a*-the particle into external forces acting on the system from outside, and internal forces acting between pairs of particles:

$$F_{a} = F_{a}^{\text{ext}} + \sum_{\substack{b \neq a \\ b \neq a}} F_{ab} \quad .$$
(1.2)
external forces

Here

$$\boldsymbol{F}_{ab} \equiv \text{ Force on particle } a \text{ by } b, \qquad (1.3)$$

and of course we have Newton's equal and opposite rule

$$\boldsymbol{F}_{ab} = -\boldsymbol{F}_{ba} \,. \tag{1.4}$$

• Summing over the particles we find (after using Eq. (1.4)) that the internal forces cancel and the total change in momentum per time is the sum of external forces

$$\frac{d\boldsymbol{P}_{\text{tot}}}{dt} = \boldsymbol{F}_{\text{tot}}^{\text{ext}}$$
(1.5)

where $P_{\text{tot}} = \sum_{a} p_{a}$ and $F_{\text{tot}}^{\text{ext}} = \sum_{a} F_{a}^{\text{ext}}$. If there are no external forces then P_{tot} is constant

• The velocity of the center of mass is

$$\boldsymbol{v}_{\rm cm} = \frac{\boldsymbol{P}_{\rm tot}}{M_{\rm tot}} = \frac{1}{M_{\rm tot}} \sum_{a} m_a \boldsymbol{v}_a \,. \tag{1.6}$$

The position of the center of mass (relative to an origin O) is

$$\boldsymbol{R}_{\rm cm} = \frac{1}{M_{\rm tot}} \sum_{a} m_a \boldsymbol{r}_a \,. \tag{1.7}$$

Angular momentum:

• Angular momentum is defined with respect to a specific origin O (i.e. r_a depends on O) which is not normally notated

$$\boldsymbol{\ell}_{a,O} \equiv \boldsymbol{\ell}_a \equiv \boldsymbol{r}_a \times \boldsymbol{p}_a \,. \tag{1.8}$$

It evolves as

$$\frac{d\boldsymbol{\ell}}{dt} = \boldsymbol{r}_a \times \boldsymbol{F}_a \tag{1.9}$$

• The total angular momentum $L_{tot} = \sum_{a} \ell_{a}$ changes due to the total *external* torque

$$\frac{d\boldsymbol{L}_{\rm tot}}{dt} = \boldsymbol{\tau}_{\rm tot}^{\rm ext} \,, \tag{1.10}$$

where $\tau_{\text{tot}}^{\text{ext}} = \sum_{a} \mathbf{r}_{a} \times \mathbf{F}_{a}^{\text{ext}}$ were we have generally assumed that the internal forces are radially directed $\mathbf{F}_{ab} \propto (\mathbf{r}_{a} - \mathbf{r}_{b})$

• The angular momentum depends on the origin O. Writing the position of the particle relative to the center of mass as Δr_a , i.e.

$$\boldsymbol{r}_a = \boldsymbol{R}_{\rm cm} + \Delta \boldsymbol{r}_a \,, \tag{1.11}$$

the angular momentum of the system about O is

$$\boldsymbol{L}_{O} = \boldsymbol{R}_{\rm cm} \times \boldsymbol{P}_{\rm tot} + \sum_{a} \Delta \boldsymbol{r}_{a} \times \boldsymbol{p}_{a} \quad . \tag{1.12}$$

Ang-mom of center of mass about O Ang-mom about the cm

Energy

• Energy conservation is derived by taking the dot product of v with dp/dt. We find that the change in kinetic energy (on the *a*-the particle) equals the work done (on the *a*-particle).

$$\frac{1}{2}m_a v_a^2(t)\Big|_{t_1}^{t_2} = W_a \tag{1.13}$$

where the work is

$$W_a = \int_{\boldsymbol{r}_a(t_1)}^{\boldsymbol{r}_a(t_2)} \boldsymbol{F}_a \cdot \mathrm{d}\boldsymbol{r}_a \tag{1.14}$$

• *Potential Energy.* For conservative forces the force can be written as (minus) the gradient of a scalar function which we call the potential energy

$$\boldsymbol{F}_a = -\nabla_{\boldsymbol{r}_a} U \tag{1.15}$$

Consider the potential energy U_{12} between particle 1 and 2. Since the force is equal and opposite

$$F_{12} = -\nabla_{r_1} U_{12}(r_1, r_2) = +\nabla_{r_2} U_{12}(r_1, r_2) = -F_{21}$$
(1.16)

and this is used to conclude that interaction potential between two particles is of the form

$$U_{12}^{\rm int} = U(|\boldsymbol{r}_1 - \boldsymbol{r}_2|) \tag{1.17}$$

Typically we divide up the potential into an external potential and the internal ones

$$U(\boldsymbol{r}_a) = U^{\text{ext}}(\boldsymbol{r}_a) + \frac{1}{2} \sum_{ab, a \neq b} U^{\text{int}}_{ab}(\boldsymbol{r}_a, \boldsymbol{r}_b)$$
(1.18)

The sum over the internal potentials comes with a factor of a half because the energy between particle-1 and particle-2 is counted twice in the sum, e.g. for just two particles

$$U_{12}^{\text{int}}(\boldsymbol{r}_1, \boldsymbol{r}_2) = \frac{1}{2} \left(U(|\boldsymbol{r}_1 - \boldsymbol{r}_2|) + U(|\boldsymbol{r}_2 - \boldsymbol{r}_1|) \right) \,. \tag{1.19}$$

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• *Energy*. The total energy is

$$E = \sum_{a} \frac{1}{2} m_a v_a^2 + U^{\text{ext}}(\boldsymbol{r}_a) + \frac{1}{2} \sum_{ab, a \neq b} U^{\text{int}}_{ab}(\boldsymbol{r}_a, \boldsymbol{r}_b)$$
(1.20)

and is constant if there are no non-conservative forces.

If there are non-conservative forces then

$$E(t_2) - E(t_1) = W_{\rm NC} \tag{1.21}$$

where the work done by the non-conservative forces is $W_{NC} = \sum_a \int F_a^{NC} \cdot \mathrm{d}r_a$

• It is convenient to measure velocities relative to the center of mass

$$\boldsymbol{v}_a = \boldsymbol{v}_{\rm cm} + \Delta \boldsymbol{v}_a \tag{1.22}$$

where $\Delta \boldsymbol{v}_a = \dot{\Delta} \boldsymbol{r}_a$, then the kinetic energy

$$K = \underbrace{\frac{1}{2}M_{\text{tot}}v_{\text{cm}}^2}_{\underline{\lambda}} + \underbrace{\sum_{a}\frac{1}{2}m_a\Delta v_a^2}_{\underline{\lambda}}$$
(1.23)

KE of center-mass KE relative to center-mass

Galilean invariance:

• Consider newtons laws then for an isolated system of particles

$$\frac{d\boldsymbol{p}_a}{dt} = \boldsymbol{F}_a \tag{1.24}$$

where $\boldsymbol{F}_a = -\nabla_{\boldsymbol{r}_a} U$ with

$$U = \frac{1}{2} \sum_{ab,a \neq b} U_{ab}^{\text{int}}(|\boldsymbol{r}_a - \boldsymbol{r}_b|)$$
(1.25)

Here the space-time coordinates are measured by an observer O with origin.

Then consider an observer O' moving with *constant* velocity -u relative to O. The "new" coordinates (those measured by O') are related to the old coordinates via a Galilean boost

$$\boldsymbol{r}_a \to \boldsymbol{r}_a' = \boldsymbol{r}_a + \boldsymbol{u}t \tag{1.26}$$

$$t \to t' = t \tag{1.27}$$

The potential which only depends on $r_a - r_b$ is independent of the shift. The observer measures

$$\boldsymbol{v}_a \to \boldsymbol{v}_a' = \boldsymbol{v}_a + \boldsymbol{u} \tag{1.28}$$

$$\boldsymbol{p}_a \to \boldsymbol{p}_a' = \boldsymbol{p}_a + m_a \boldsymbol{u} \tag{1.29}$$

The equations of motion for observer O' are unchanged

$$\frac{d\mathbf{p}'_a}{dt'} = \mathbf{F}'_a \qquad \mathbf{F}' \equiv \nabla_{\mathbf{r}'} U(|\mathbf{r}'_a - \mathbf{r}'_b|)$$
(1.30)